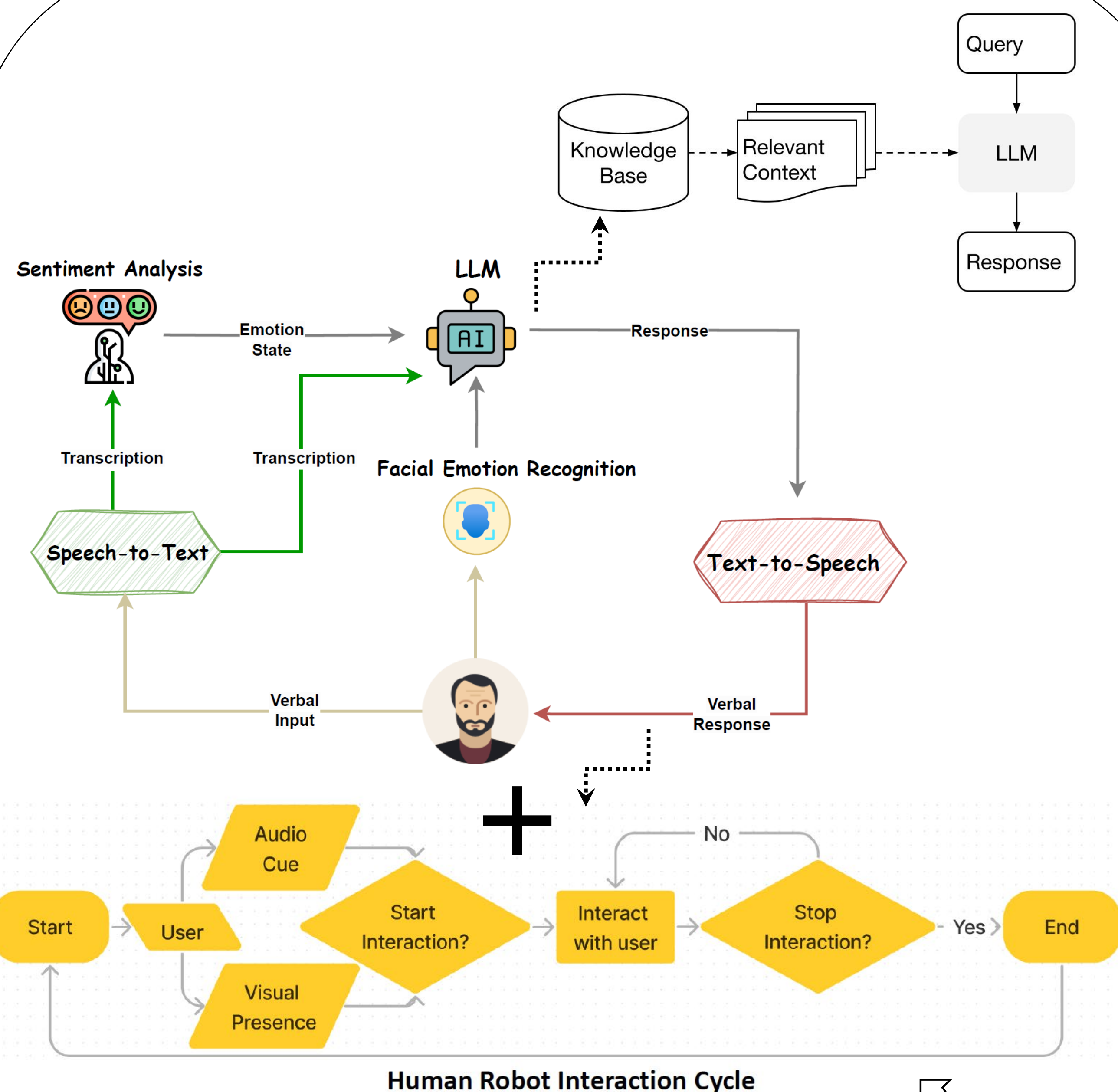


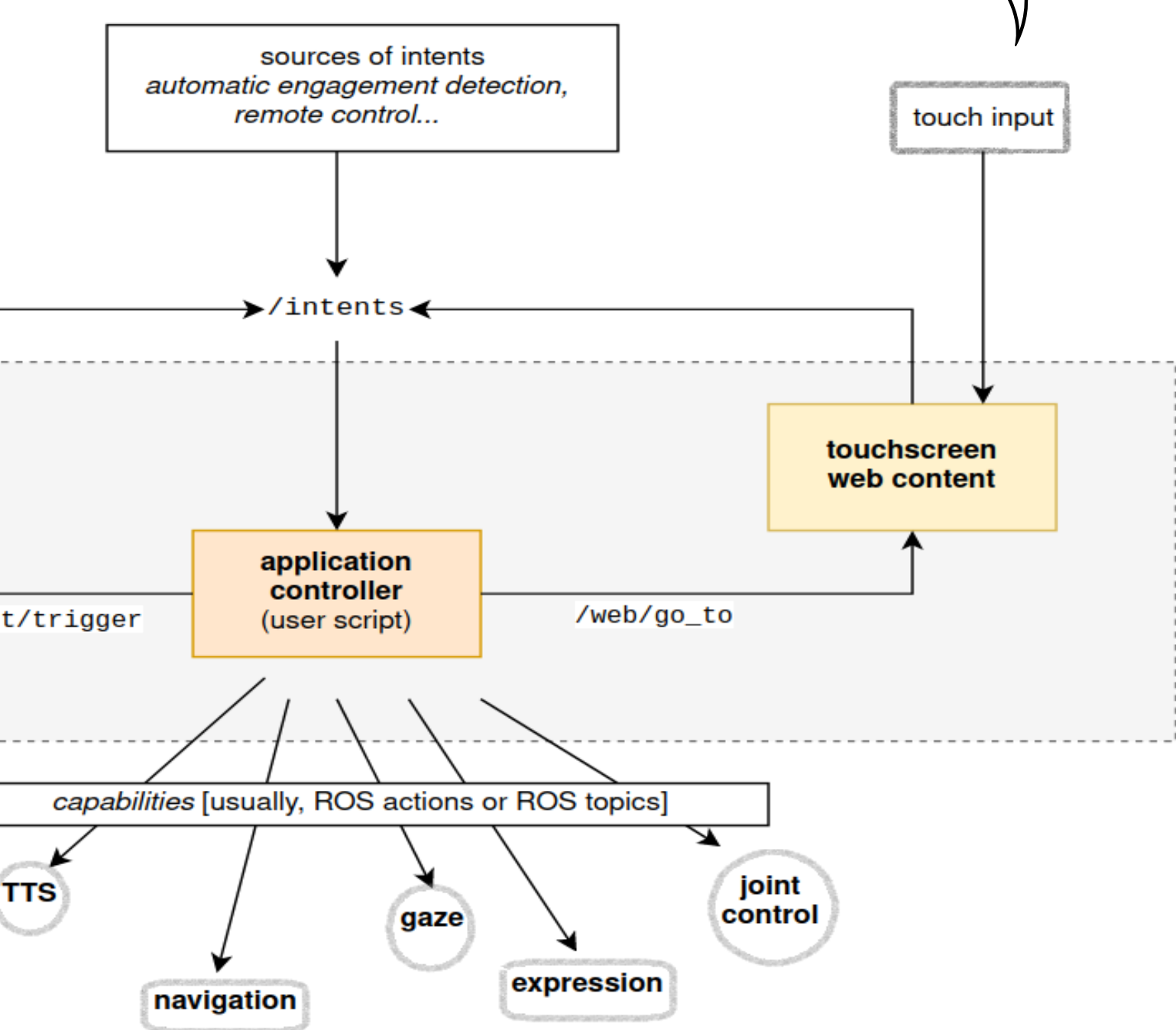
Motivation

- **A**chieving seamless and immersive conversation.
- **B**ridging the gap between companionship and functional utility.
- **C**reating robots that engage users in a way that feels emotionally intelligent, dynamic, and responsive.
- **D**esigning an open-source Natural Language Processing.
- **E**nhancing immersive conversations through ARI and NAO.

Framework and Models



Human Robot Interaction Cycle



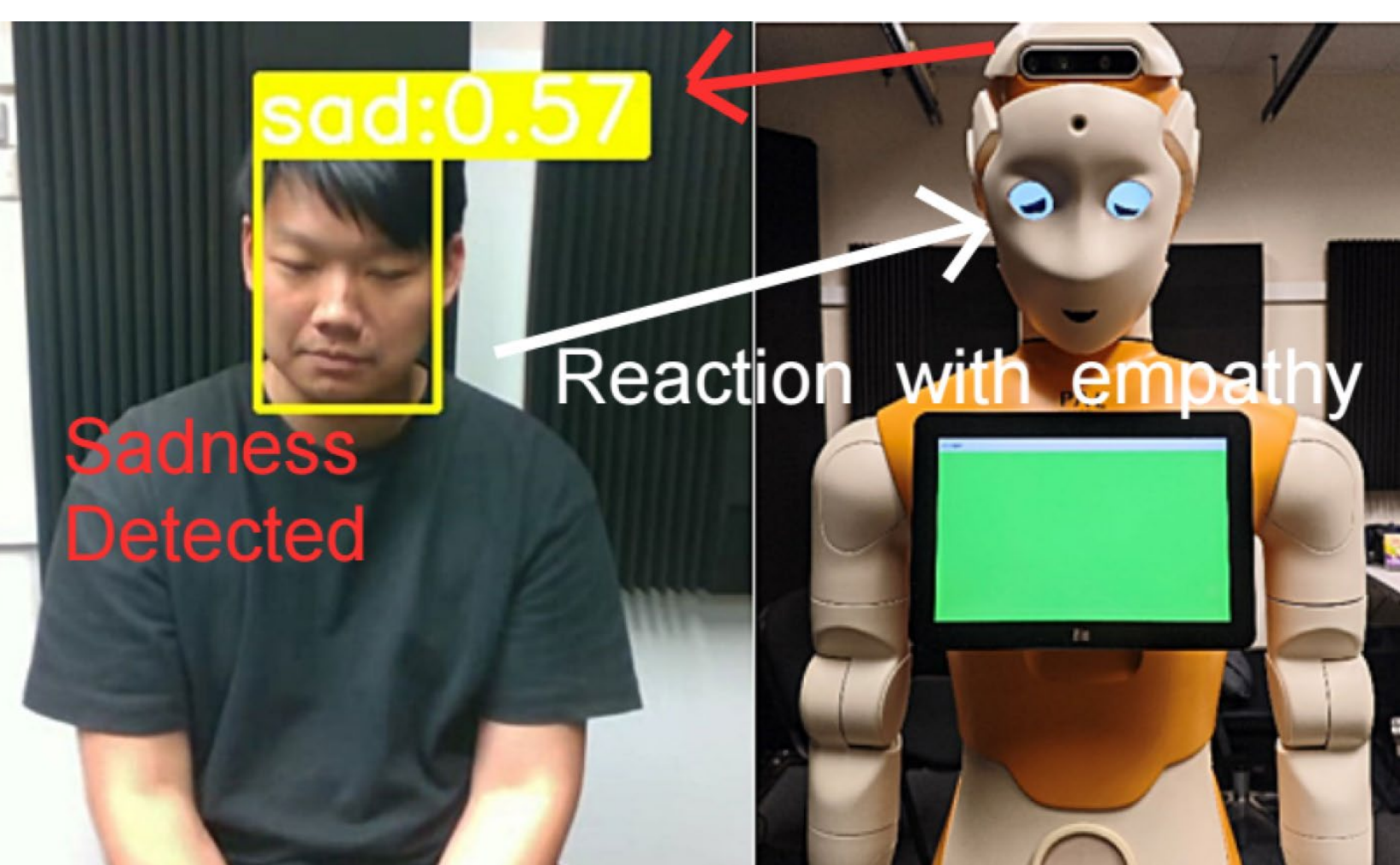
ARI Emotional Responsiveness



Neutral Happy Sad

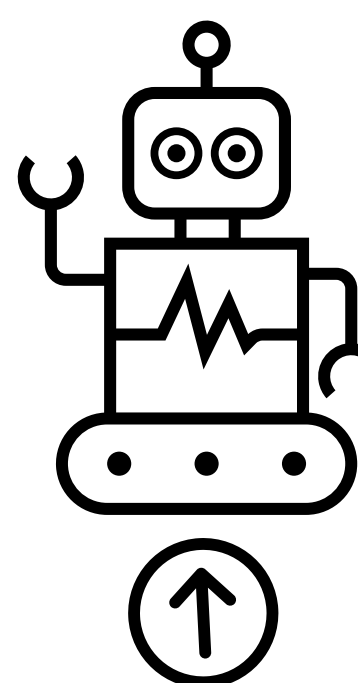
+ Gaze Control

+ Presence Detection



Research Question

How can AI-driven chatbots address self-feedback and latency to create responsive, intuitive, and emotionally intelligent robotic companions?



Video Demonstration

Problems with Robot Chatbots

- **Intuitiveness:** Robot's responses may feel unnatural/disjointed because it needs to wait until it finishes speaking (TTS output) before it can recognize and respond to the user's next input.
- **Emotional Intelligence:** Limited ability to detect/respond appropriately.
- **Monotony:** Robotic voices and repetitive dialogue patterns reduce engagement.
- **Echo Interference:** Robot mistakenly processes its own voice as input, causing conversational errors. Microphone Crosstalk, Self-Voice Recognition Error, Speech-To-Self Error, Audio Loopback.
- **Integration:** Difficulty syncing speech with gestures/non-verbal communication.
- **Hardware:** Limited local processing power (complex AI models).
- **Latency:** Delays in generating responses, especially when dependent on cloud-based LLMs.
- **Data Privacy Concerns:** Risk of user data leakage when relying on cloud services for processing.

NAO Conversational Intuition

- **Sensor-Based Trigger Mechanism:** Utilizing bumper, sonar, camera, and tactile sensors to stop or activate robot functionality.
- Leveraging light advanced AI and minimizing delays or awkward pauses
- Allowing the robot to listen while speaking
- Lightweight GUI web application for displaying chatbot dialogue
- Detecting an open palm gesture to signal the robot to stop its action.

