

Evaluating Hypotheses

May 6, 2009

Acknowledgement: Material derived from slides for the book Machine Learning, Tom M. Mitchell, McGraw-Hill, 1997 <http://www-2.cs.cmu.edu/~tom/mlbook.html> and the book Data Mining, Ian H. Witten and Eibe Frank, Morgan Kaufmann, 2000. <http://www.cs.waikato.ac.nz/ml/weka>

Aims

This lecture will enable you to apply statistical and graphical methods to the evaluation of hypotheses in machine learning. Following it you should be able to:

- describe the problem of estimating hypothesis accuracy (error)
- define sample error and true error
- derive confidence intervals for observed hypothesis error
- compare learning algorithms using paired t -test
- define and use common evaluation measures
- generate lift charts and ROC curves

[Recommended reading: Mitchell, Chapter 5]
[Recommended exercises: 5.2 – 5.4]

Relevant WEKA programs:
`weka.gui.experiment.Experimenter`

Estimating Hypothesis Accuracy

- how well does a hypothesis generalize *beyond* the training set ?
 - need to estimate off-training-set error
- what is the probable error in this estimate ?
- if one hypothesis is more accurate than another on a data set, how probable is this difference in general ?

Estimators

Experiment:

1. choose sample S of size n according to distribution \mathcal{D}
2. measure $error_S(h)$

$error_S(h)$ is a random variable (i.e., result of an experiment)

$error_S(h)$ is an unbiased *estimator* for $error_{\mathcal{D}}(h)$

Given observed $error_S(h)$ what can we conclude about $error_{\mathcal{D}}(h)$?

Two Definitions of Error

The **sample error** of h with respect to target function f and data sample S is the proportion of examples h misclassifies

$$error_S(h) \equiv \frac{1}{n} \sum_{x \in S} \delta(f(x) \neq h(x))$$

Where $\delta(f(x) \neq h(x))$ is 1 if $f(x) \neq h(x)$, and 0 otherwise (cf. 0 – 1 loss).

The **true error** of hypothesis h with respect to target function f and distribution \mathcal{D} is the probability that h will misclassify an instance drawn at random according to \mathcal{D} .

$$error_{\mathcal{D}}(h) \equiv \Pr_{x \in \mathcal{D}}[f(x) \neq h(x)]$$

Question: How well does $error_S(h)$ estimate $error_{\mathcal{D}}(h)$?

Problems Estimating Error

1. *Bias:* If S is training set, $error_S(h)$ is optimistically biased

$$bias \equiv E[error_S(h)] - error_{\mathcal{D}}(h)$$

For unbiased estimate, h and S must be chosen independently

2. *Variance:* Even with unbiased S , $error_S(h)$ may still vary from $error_{\mathcal{D}}(h)$

Problems Estimating Error

Note: *Estimation bias* not to be confused with *Inductive bias* – former is a numerical quantity [comes from statistics], latter is a set of assertions [comes from concept learning].

More on this in the lecture on *ensemble* methods.

Example

Hypothesis h misclassifies 12 of the 40 examples in S

$$error_S(h) = \frac{12}{40} = .30$$

What is $error_{\mathcal{D}}(h)$?

Confidence Intervals

If

- S contains n examples, drawn independently of h and each other
- $n \geq 30$

Then

- With approximately 95% probability, $error_{\mathcal{D}}(h)$ lies in interval

$$error_S(h) \pm 1.96 \sqrt{\frac{error_S(h)(1 - error_S(h))}{n}}$$

Confidence Intervals

If

- S contains n examples, drawn independently of h and each other
- $n \geq 30$

Then

- With approximately $N\%$ probability, $error_{\mathcal{D}}(h)$ lies in interval

$$error_S(h) \pm z_N \sqrt{\frac{error_S(h)(1 - error_S(h))}{n}}$$

Confidence Intervals

Where do the z_N values come from ? Statistical tables, e.g.

$N\%$:	50%	68%	80%	90%	95%	98%	99%
z_N :	0.67	1.00	1.28	1.64	1.96	2.33	2.58

Confidence Intervals

Example:

Hypothesis h misclassifies 12 of the 40 examples in S

$$error_S(h) = \frac{12}{40} = .30$$

What is $error_{\mathcal{D}}(h)$?

Given no other information, our best estimate is .30

...

Confidence Intervals

Example (continued):

..., but for repeated samples of 40 examples, expect some variation in the sample error. With approximately 95% probability, $error_{\mathcal{D}}(h)$ lies in interval

$$\begin{aligned} error_S(h) \pm 1.96 \sqrt{\frac{error_S(h)(1 - error_S(h))}{n}} \\ = .30 \pm 1.96 \sqrt{\frac{.30 \times .70}{40}} \\ = .30 \pm 1.96 \times .072 \\ = .30 \pm .14 \end{aligned}$$

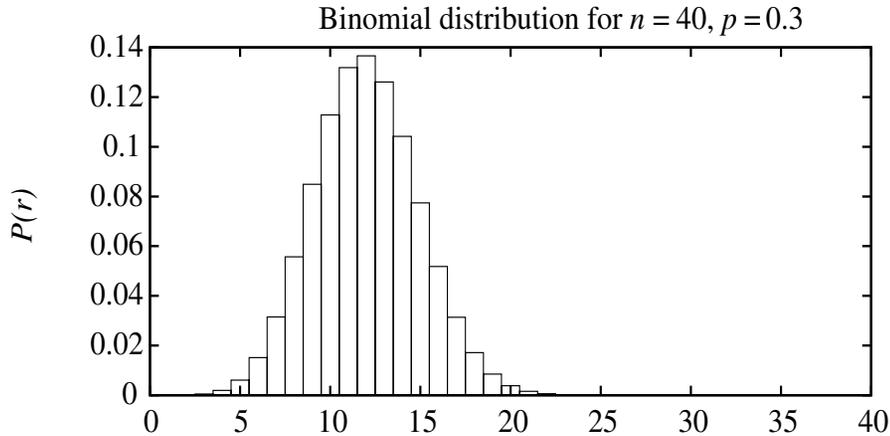
$error_S(h)$ is a Random Variable

Rerun the experiment with different randomly drawn S (of size n)

Probability of observing r misclassified examples:

$$P(r) = \frac{n!}{r!(n-r)!} error_{\mathcal{D}}(h)^r (1 - error_{\mathcal{D}}(h))^{n-r}$$

Binomial Probability Distribution



Binomial Probability Distribution

Probability $P(r)$ of r heads in n coin flips, if $p = \Pr(\text{heads})$

$$P(r) = \frac{n!}{r!(n-r)!} p^r (1-p)^{n-r}$$

Binomial Probability Distribution

- Expected, or mean value of X , $E[X]$, is

$$E[X] \equiv \sum_{i=0}^n iP(i) = np$$

- Variance of X is

$$\text{Var}(X) \equiv E[(X - E[X])^2] = np(1-p)$$

- Standard deviation of X , σ_X , is

$$\sigma_X \equiv \sqrt{E[(X - E[X])^2]} = \sqrt{np(1-p)}$$

Examples

Suppose you test a hypothesis h and find that it commits $r = 12$ errors on a sample S of $n = 40$ randomly drawn test examples. An unbiased estimate for $\text{error}_{\mathcal{D}}(h)$ is given by $\text{error}_S(h) = r/n = 0.3$.

The variance in this estimate arises from r alone (n is a constant).

From the Binomial distribution, this variance is $np(1-p)$.

We can substitute r/n as an estimate for p . Then the variance for r is estimated to be $40 \times 0.3(1-0.3) = 8.4$ and the standard deviation is $\sqrt{8.4} \approx 2.9$.

Therefore the standard deviation in $\text{error}_S(h) = r/n$ is approximately $2.9/40 = 0.07$.

$\text{error}_S(h)$ is observed to be 0.30 with standard deviation of approximately 0.07.

Examples

Suppose you test a hypothesis h and find that it commits $r = 300$ errors on a sample S of $n = 1000$ randomly drawn test examples. What is the standard deviation in $error_S(h)$?

The standard deviation for r is estimated to be $\sqrt{1000 \times 0.3(1 - 0.3)} \approx 14.5$.

Therefore the standard deviation in $error_S(h) = r/n$ is approximately $14.5/1000 = .0145$.

$error_S(h)$ is observed to be 0.30 with standard deviation of approximately .0145.

Normal Distribution Approximates Binomial

$error_S(h)$ follows a *Binomial* distribution, with

- mean $\mu_{error_S(h)} = error_{\mathcal{D}}(h)$
- standard deviation $\sigma_{error_S(h)}$

$$\sigma_{error_S(h)} = \sqrt{\frac{error_{\mathcal{D}}(h)(1 - error_{\mathcal{D}}(h))}{n}}$$

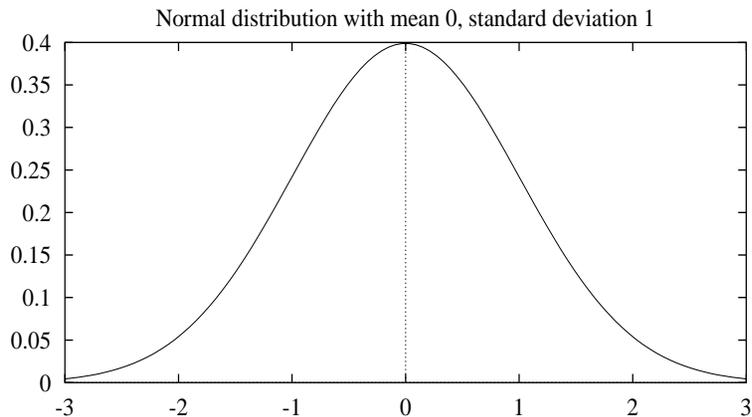
Normal Distribution Approximates Binomial

Approximate this by a *Normal* distribution with

- mean $\mu_{error_S(h)} = error_{\mathcal{D}}(h)$
- standard deviation $\sigma_{error_S(h)}$

$$\sigma_{error_S(h)} \approx \sqrt{\frac{error_S(h)(1 - error_S(h))}{n}}$$

Normal Probability Distribution



$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$$

Normal Probability Distribution

The probability that X will fall into the interval (a, b) is given by

$$\int_a^b p(x)dx$$

- Expected, or mean value of X , $E[X]$, is

$$E[X] = \mu$$

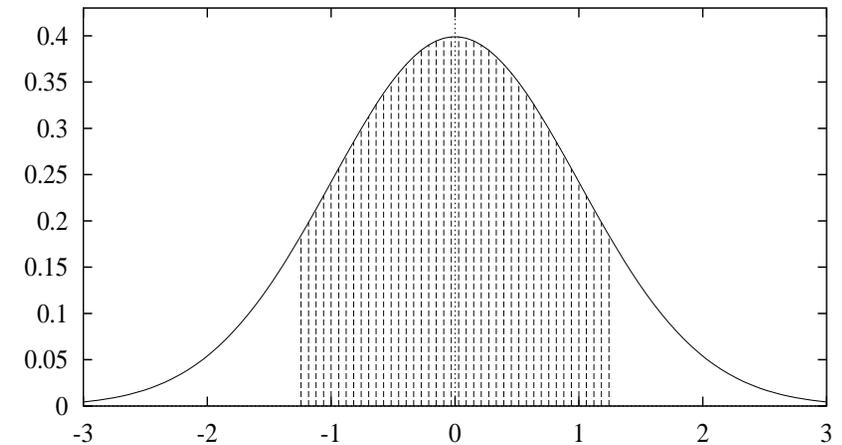
- Variance of X is

$$\text{Var}(X) = \sigma^2$$

- Standard deviation of X , σ_X , is

$$\sigma_X = \sigma$$

Normal Probability Distribution



Normal Probability Distribution

80% of area (probability) lies in $\mu \pm 1.28\sigma$

N% of area (probability) lies in $\mu \pm z_N\sigma$

N%:	50%	68%	80%	90%	95%	98%	99%
z_N :	0.67	1.00	1.28	1.64	1.96	2.33	2.58

Note: with 80% confidence the value of the random variable will lie in the two-sided interval $[-1.28, 1.28]$.

With 10% confidence it will lie to the right of this interval (resp. left).

With 90% confidence it will lie in the one-sided interval $[-\infty, 1.28]$

Let α be the probability that the value lies *outside* the interval.

Then a $100(1 - \alpha)\%$ two-sided confidence interval with lower-bound L and upper-bound U can be converted into a $100(1 - (\alpha/2))\%$ one-sided confidence interval with lower bound L and no upper bound (resp. upper bound U and no lower bound).

Confidence Intervals, More Correctly

If

- S contains n examples, drawn independently of h and each other
- $n \geq 30$

Then

- With approximately 95% probability, $error_S(h)$ lies in interval

$$error_{\mathcal{D}}(h) \pm 1.96 \sqrt{\frac{error_{\mathcal{D}}(h)(1 - error_{\mathcal{D}}(h))}{n}}$$

equivalently, $error_{\mathcal{D}}(h)$ lies in interval

$$error_S(h) \pm 1.96 \sqrt{\frac{error_{\mathcal{D}}(h)(1 - error_{\mathcal{D}}(h))}{n}}$$

which is approximately

$$error_S(h) \pm 1.96 \sqrt{\frac{error_S(h)(1 - error_S(h))}{n}}$$

Calculating Confidence Intervals

1. Pick parameter p to estimate
 - $error_{\mathcal{D}}(h)$
2. Choose an estimator
 - $error_S(h)$
3. Determine probability distribution that governs estimator
 - $error_S(h)$ governed by Binomial distribution, approximated by Normal when $n \geq 30$
4. Find interval (L, U) such that N% of probability mass falls in the interval
 - Use table of z_N values

Consider a set of independent, identically distributed random variables $Y_1 \dots Y_n$, all governed by an arbitrary probability distribution with mean μ and finite variance σ^2 . Define the sample mean,

$$\bar{Y} \equiv \frac{1}{n} \sum_{i=1}^n Y_i$$

Central Limit Theorem. As $n \rightarrow \infty$, the distribution governing \bar{Y} approaches a Normal distribution, with mean μ and variance $\frac{\sigma^2}{n}$.

the sum of a large number of independent, identically distributed (i.i.d) random variables follows a distribution that is approximately Normal.

Difference Between Hypotheses

Two classifiers h_1, h_2 . Test h_1 on sample S_1 , test h_2 on S_2 .

Apply the four-step procedure:

1. Pick parameter to estimate

$$d \equiv error_{\mathcal{D}}(h_1) - error_{\mathcal{D}}(h_2)$$

2. Choose an estimator

$$\hat{d} \equiv error_{S_1}(h_1) - error_{S_2}(h_2)$$

Difference Between Hypotheses

3. Determine probability distribution that governs estimator

$$\sigma_{\hat{d}} \approx \sqrt{\frac{\text{error}_{S_1}(h_1)(1 - \text{error}_{S_1}(h_1))}{n_1} + \frac{\text{error}_{S_2}(h_2)(1 - \text{error}_{S_2}(h_2))}{n_2}}$$

4. Find interval (L, U) such that $N\%$ of probability mass falls in the interval

$$\hat{d} \pm z_N \sqrt{\frac{\text{error}_{S_1}(h_1)(1 - \text{error}_{S_1}(h_1))}{n_1} + \frac{\text{error}_{S_2}(h_2)(1 - \text{error}_{S_2}(h_2))}{n_2}}$$

Paired t test to compare h_A, h_B

1. Partition data into k disjoint test sets T_1, T_2, \dots, T_k of equal size, where this size is at least 30.

2. For i from 1 to k , do

$$\delta_i \leftarrow \text{error}_{T_i}(h_A) - \text{error}_{T_i}(h_B)$$

3. Return the value $\bar{\delta}$, where

$$\bar{\delta} \equiv \frac{1}{k} \sum_{i=1}^k \delta_i$$

sample mean of the difference in error between the 2 learning methods.

Paired t test to compare h_A, h_B

$N\%$ confidence interval estimate for d (difference between the true errors of the hypotheses):

$$\bar{\delta} \pm t_{N, k-1} s_{\bar{\delta}}$$

$$s_{\bar{\delta}} \equiv \sqrt{\frac{1}{k(k-1)} \sum_{i=1}^k (\delta_i - \bar{\delta})^2}$$

where $s_{\bar{\delta}}$ is the estimated standard deviation.

Note δ_i approximately Normally distributed

Comparing learning algorithms L_A and L_B

What we'd like to estimate:

$$E_{S \subset \mathcal{D}}[\text{error}_{\mathcal{D}}(L_A(S)) - \text{error}_{\mathcal{D}}(L_B(S))]$$

where $L(S)$ is the hypothesis output by learner L using training set S

i.e., the expected difference in true error between hypotheses output by learners L_A and L_B , when trained using randomly selected training sets S drawn according to distribution \mathcal{D} .

Comparing learning algorithms L_A and L_B

But, given limited data D_0 , what is a good estimator?

- could partition D_0 into training set S and training set T_0 , and measure

$$error_{T_0}(L_A(S_0)) - error_{T_0}(L_B(S_0))$$

- even better, repeat this many times and average the results (next slide)

Comparing learning algorithms L_A and L_B

1. Partition data D_0 into k disjoint test sets T_1, T_2, \dots, T_k of equal size, where this size is at least 30.

2. For i from 1 to k , do

use T_i for the test set, and the remaining data for training set S_i

- $S_i \leftarrow \{D_0 - T_i\}$
- $h_A \leftarrow L_A(S_i)$
- $h_B \leftarrow L_B(S_i)$
- $\delta_i \leftarrow error_{T_i}(h_A) - error_{T_i}(h_B)$

3. Return the value $\bar{\delta}$, where

$$\bar{\delta} \equiv \frac{1}{k} \sum_{i=1}^k \delta_i$$

Comparing learning algorithms L_A and L_B

Notice we'd like to use the paired t test on $\bar{\delta}$ to obtain a confidence interval

but not really correct, because the training sets in this algorithm are not independent (they overlap!)

more correct to view algorithm as producing an estimate of

$$E_{S \subset D_0}[error_{\mathcal{D}}(L_A(S)) - error_{\mathcal{D}}(L_B(S))]$$

instead of

$$E_{S \subset \mathcal{D}}[error_{\mathcal{D}}(L_A(S)) - error_{\mathcal{D}}(L_B(S))]$$

but even this approximation is better than no comparison

Parameter tuning

- It is important that the test data is not used *in any way* to create the classifier
- Some learning schemes operate in two stages:
 - Stage 1: builds the basic structure
 - Stage 2: optimizes parameter settings
- The test data can't be used for parameter tuning!
- Proper procedure uses *three* sets: *training data*, *validation data*, and *test data*
- Validation data is used to optimize parameters

Making the most of the data

- Once evaluation is complete, *all the data* can be used to build the final classifier
- Generally, the larger the training data the better the classifier (but returns diminish)
- The larger the test data the more accurate the error estimate
- *Holdout* procedure: method of splitting original data into training and test set
 - Dilemma: ideally we want both, a large training and a large test set

Loss functions

- Most common performance measure: predictive accuracy (*cf.* sample error)
- Also called 0 – 1 *loss function*:

$$\sum_i \begin{cases} 0 & \text{if prediction is correct} \\ 1 & \text{if prediction is incorrect} \end{cases}$$

- Classifiers can produce *class probabilities*
- What is the accuracy of the probability estimates ?
- 0-1 loss is not appropriate

Quadratic loss function

- p_1, \dots, p_k are probability estimates of all possible outcomes for an instance
- c is the index of the instance's actual class
- i.e. a_1, \dots, a_k are zero, except for a_c which is 1
- the *quadratic loss* is:

$$E \left[\sum_j (p_j - a_j)^2 \right] = \left(\sum_{j \neq c} p_j^2 \right) + (1 - p_c)^2$$

- leads to preference for predictors giving best guess at true probabilities

Informational loss function

- the informational loss function is $-\log(p_c)$, where c is the index of the actual class of an instance
- number of bits required to communicate the actual class
- if p_1^*, \dots, p_k^* are the true class probabilities
- then the expected value of the informational loss function is:

$$-p_1^* \log_2(p_1) - \dots - p_k^* \log_2(p_k)$$

- which is minimized for $p_j = p_j^*$
- giving the *entropy* of the true distribution

$$-p_1^* \log_2(p_1^*) - \dots - p_k^* \log_2(p_k^*)$$

Which loss function ?

- quadratic loss functions takes into account all the class probability estimates for an instance
- informational loss focuses only on the probability estimate for the actual class
- quadratic loss is bounded by $1 + \sum_j p_j^2$, can never exceed 2
- informational loss can be infinite
- informational loss related to MDL principle (can use bits for complexity as well as accuracy)

Costs of predictions

- In practice, different types of classification errors often incur different costs
- Examples:
 - Medical diagnosis (has cancer vs. not)
 - Loan decisions
 - Fault diagnosis
 - Promotional mailing

Confusion matrix

Two-class prediction case:

Actual Class	Predicted Class	
	Yes	No
Yes	True Positive (TP)	False Negative (FN)
No	False Positive (FP)	True Negative (TN)

Two kinds of error:

False Positive and False Negative may have different costs.

Two kinds of correct prediction:

True Positive and True Negative may have different "benefits".

Note: total number of test set examples $N = TP + FN + FP + TN$

Common evaluation measures

Accuracy

$$\frac{TP + TN}{N}$$

Error rate

equivalent to $1 - \text{Accuracy}$, i.e.,

$$\frac{FP + FN}{N}$$

Precision

$$\frac{TP}{TP + FP}$$

(also called: **Correctness, Positive Predictive Value**)

Recall

$$\frac{TP}{TP + FN}$$

(also called: *TP* rate, **Hit rate, Sensitivity, Completeness**)

Sensitivity

$$\frac{TP}{TP + FN}$$

Specificity

equivalent to $1 - FP$ rate

$$\frac{TN}{TN + FP}$$

(also called: *TN* rate)

True Positive (*TP*) Rate

$$\frac{TP}{TP + FN}$$

False Positive (*FP*) Rate

equivalent to $1 - \text{Specificity}$, i.e.,

$$\frac{FP}{FP + TN}$$

(also called: **False alarm rate**)

Negative Predictive Value

$$\frac{TN}{TN + FN}$$

Coverage

$$\frac{TP + FP}{N}$$

Note:

- this is not an exhaustive list ...
- same measures used under different names in different disciplines

Common evaluation measures

Actual Class	Predicted Class	
	Yes	No
Yes	TP	FN
No	FP	TN

E.g., in concept learning, the number of instances in a sample predicted to be in (resp. not in) the concept is the sum of the first (resp. second) column.

The number of positive (resp. negative) examples of the concept in a sample is the sum of the first (resp. second) row.

$$\begin{aligned} N_{\text{pred}} &= TP + FP & N_{\text{not_pred}} &= FN + TN \\ N_{\text{pos}} &= TP + FN & N_{\text{neg}} &= FP + TN \end{aligned}$$

Trade-off

Trade-off

good coverage of positive examples: increase TP at risk of increasing FP
i.e. increase generality

good proportion of positive examples: decrease FP at risk of decreasing TP
i.e. decrease generality, i.e. increase specificity

Different techniques give different trade-offs and can be plotted as *two different lines* on any of the graphical charts: Lift, ROC or recall-precision curves.

Common evaluation measures

We can treat the evaluation measures as conditional probabilities:

$$P(\text{pred} \mid \text{pos}) = \frac{TP}{TP+FN} \quad (\text{Sensitivity})$$

$$P(\text{pred} \mid \text{neg}) = \frac{FP}{FP+TN} \quad (\text{FP rate})$$

$$P(\text{not_pred} \mid \text{pos}) = \frac{FN}{TP+FN} \quad (\text{FN rate})$$

$$P(\text{not_pred} \mid \text{neg}) = \frac{TN}{FP+TN} \quad (\text{Specificity})$$

$$P(\text{pos} \mid \text{pred}) = \frac{TP}{TP+FP} \quad (\text{Pos. Pred. Value})$$

$$P(\text{neg} \mid \text{pred}) = \frac{FP}{TP+FP}$$

$$P(\text{pos} \mid \text{not_pred}) = \frac{FN}{FN+TN} \quad (\text{FN rate})$$

$$P(\text{neg} \mid \text{not_pred}) = \frac{TN}{FN+TN} \quad (\text{Neg. Pred. Value})$$

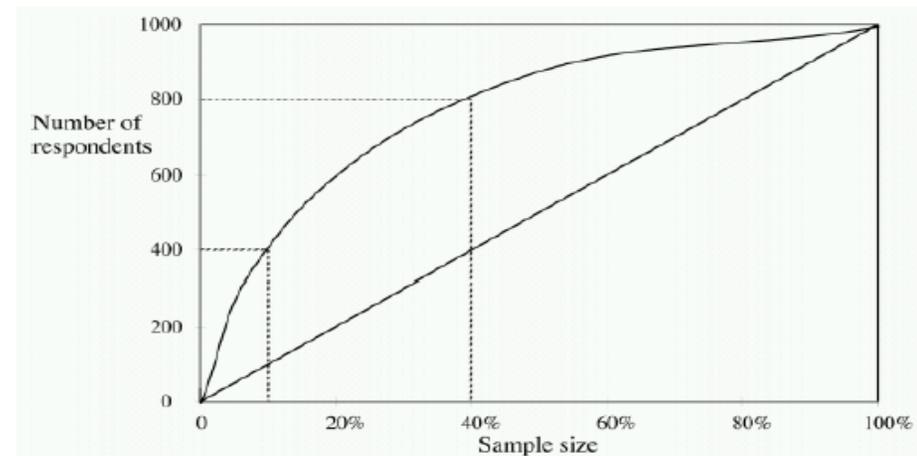
Lift charts

- In practice, costs are rarely known precisely
- Instead decisions often made by comparing possible scenarios
- Lift comes from market research, where a typical goal is to identify a "profitable" target sub-group out of the total population
- Example: promotional mailout to population of 1,000,000 potential respondents
 - Baseline is that 0.1% of all households in total population will respond (1000)
 - Situation 1: classifier 1 identifies target sub-group of 100,000 most promising households of which 0.4% will respond (400)
 - Situation 2: classifier 2 identifies target sub-group of 400,000 most promising households of which 0.2% will respond (800)

Lift charts

- Lift = $\frac{\text{response rate of target sub-group}}{\text{response rate of total population}}$
- Situation 1 gives lift of $\frac{0.4}{0.1} = 4$
- Situation 2 gives lift of $\frac{0.2}{0.1} = 2$
- Note that which situation is more profitable depends on cost estimates
- A lift chart allows for a visual comparison

Hypothetical Lift Chart



Generating a lift chart

Instances are sorted according to their predicted probability of being a true positive:

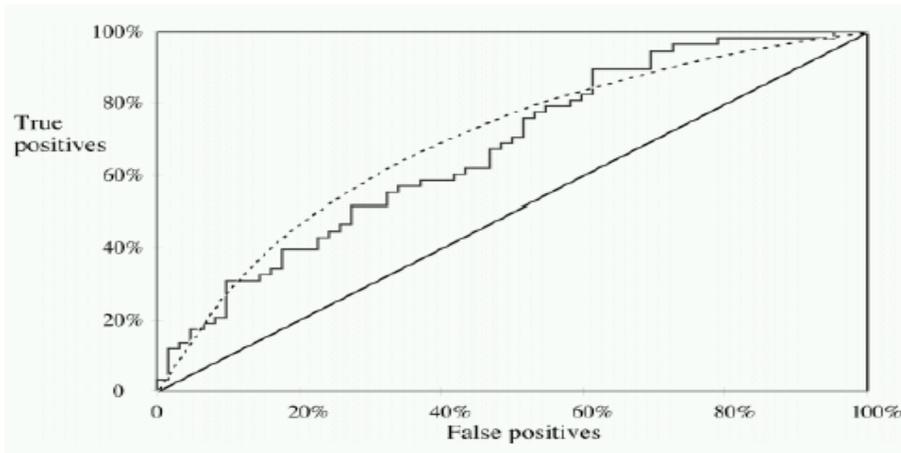
Rank	Predicted probability	Actual class
1	0.95	Yes
2	0.93	Yes
3	0.93	No
4	0.88	Yes
...

In lift chart, x axis is sample size and y axis is number of true positives

ROC curves

- ROC curves are similar to lift charts
 - ROC stands for receiver operating characteristic
 - Used in signal detection to show tradeoff between hit rate and false alarm rate over noisy channel
- Differences to lift chart:
 - y axis shows percentage of true positives in sample (rather than absolute number)
 - x axis shows percentage of false positives in sample (rather than sample size)

A sample ROC curve



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Numeric prediction evaluation measures

Based on differences between predicted (p_i) and actual (a_i) values on a test set of n examples:

Mean squared error

$$\frac{(p_1 - a_1)^2 + \dots + (p_n - a_n)^2}{n}$$

Root mean squared error

$$\sqrt{\frac{(p_1 - a_1)^2 + \dots + (p_n - a_n)^2}{n}}$$

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Numeric prediction evaluation measures

Mean absolute error

$$\frac{|p_1 - a_1| + \dots + |p_n - a_n|}{n}$$

Relative absolute error

$$\frac{|p_1 - a_1| + \dots + |p_n - a_n|}{|a_1 - \bar{a}| + \dots + |a_n - \bar{a}|}, \text{ where } \bar{a} = \frac{1}{n} \sum_i a_i$$

plus others, see, e.g., Weka

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Summary

- Evaluation for machine learning and data mining is a complex issue
- Many accepted methods not theoretically well-founded ...
- ... but have been found to work well in practice, e.g.,
 - 10 × 10-fold cross-validation
 - corrected resampled t-test (Weka)

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