

Slide 1

COMP3152/9152  
Lecture 1  
Knowledge in Distributed Systems  
(An Introduction)

Ron van der Meyden

Slide 2

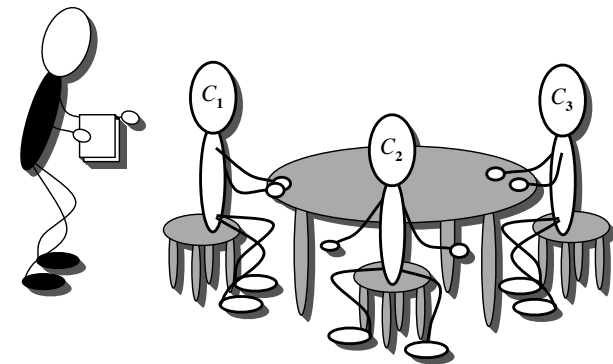
The main problem *unique* to distributed systems is a lack of (global) knowledge. It is difficult (probably impossible) for one node to know everything about the rest of the network. Yet global knowledge seems to be required to answer questions such as “Where is the file A”, “Is there a deadlock”, [or] “What is the best way to answer the question.... ” (Gray, 1979)

“Once the sender receives the acknowledgement, it *knows* that the current packet has been delivered; it can then safely discard the current packet and send the next.”

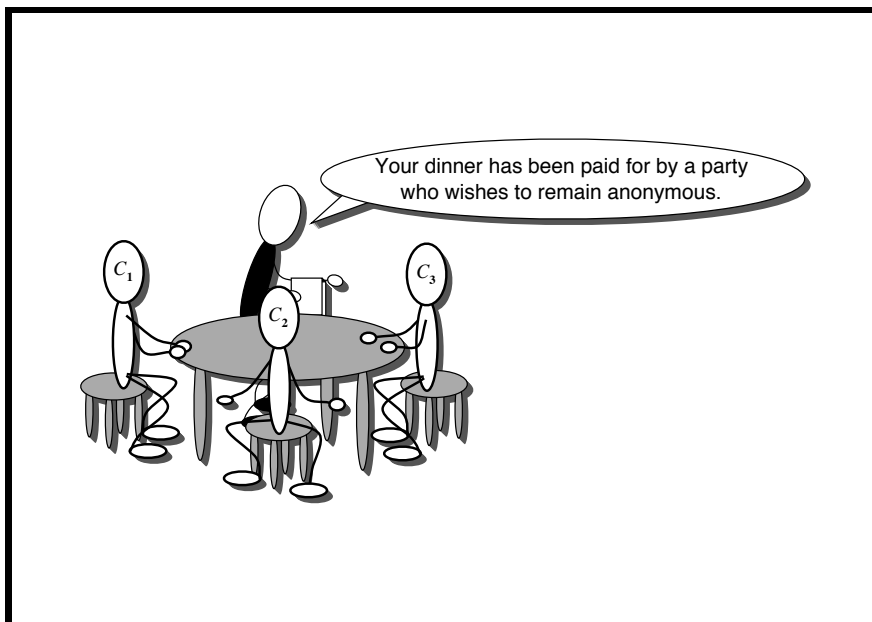
Slide 3

Chaum’s Dining Cryptographers protocol

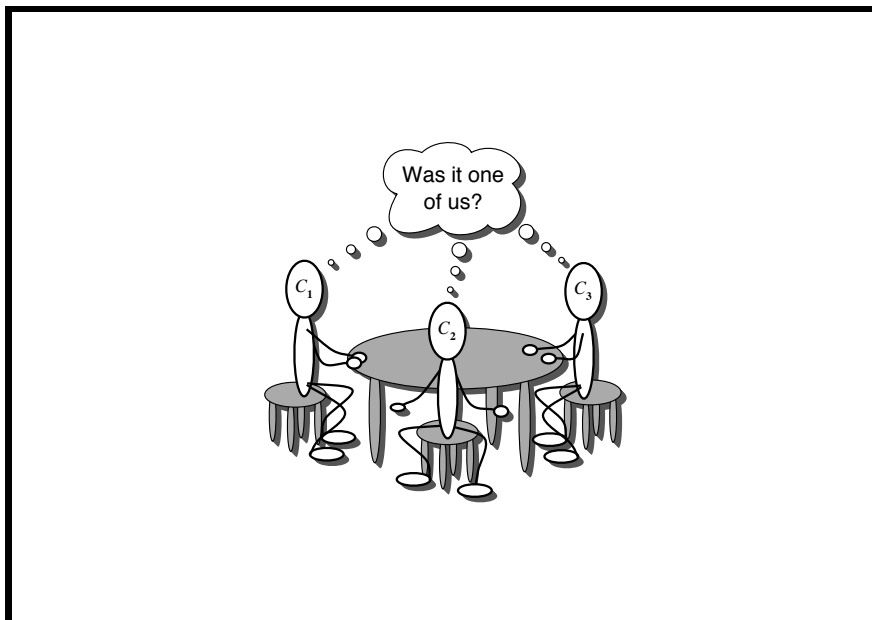
Slide 4



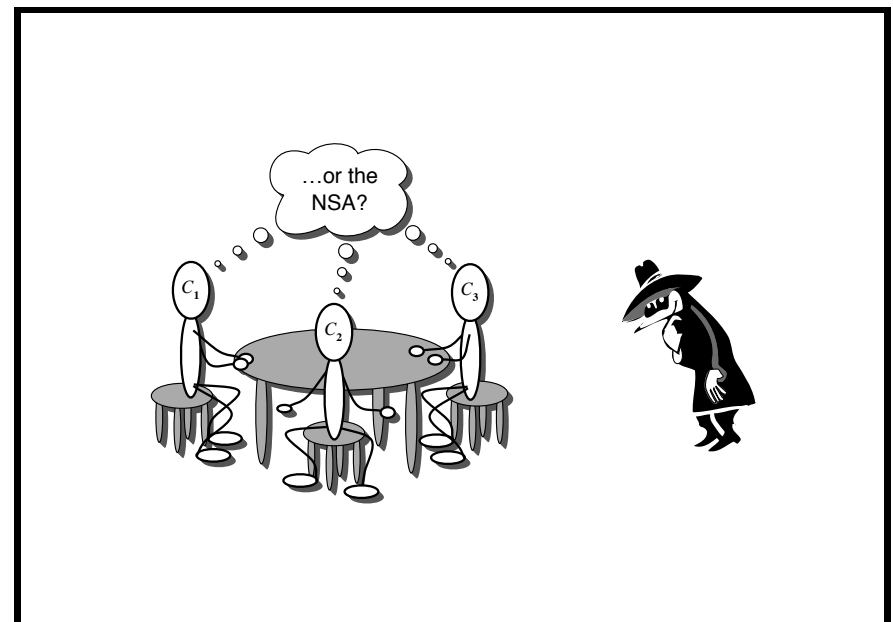
Slide 5



Slide 6



Slide 7



Slide 8

### Knowledge Theoretic Specification

We want a protocol that will get us to a state where...

If  $C_1$  did not pay, then either

1.  $C_1$  knows that the NSA paid, or
2.  $C_1$  knows that either  $C_2$  or  $C_3$  paid, but does not know which one.

Similarly for the others ...

Slide 9

## Knowledge Based Programs



A knowledge-based program:

```
wait until Know(position in Goal);
halt.
```

Slide 10

## The Muddy Children

$n$  (very smart) children have been out playing in the garden. They were supposed to keep clean, but some of them have got mud on their forehead. They can't see their own forehead, but can see the forehead of every other child. Father comes along ....

Slide 11

Version 1: Father asks "Which of you know whether you have mud on your forehead?" Repeats the question....

Version 2: Father says "At least one of you has a dirty forehead." then asks "Which of you know whether you have mud on your forehead?" Repeats the question....

What happens? Why is there a difference?

Slide 12

## Plan

- Introduction, Semantic models for Knowledge
- Logics of Knowledge - Axioms and Model Checking
- Semantic Models for Knowledge and Time
- Properties of Knowledge and Time
- Dynamics of Common Knowledge
- Model Checking Knowledge and Time
- Knowledge-based programs
- Applications to Distributed Algorithms
- Applications to computer security
- Variants of Common Knowledge
- The logic of knowledge and probability
- Connections to economics: epistemic game theory

Slide 13

### Textbook

Reasoning about Knowledge, Fagin, Halpern, Moses and Vardi, MIT Press, 2nd edition, 2003.

### Assessment

6 problem sets, due weeks 2,4,6,8,10,12

Final Mark = best 5/6 each worth 20%

Slide 14

### Semantic Models for Knowledge

Reading, FHMV Ch 1 & 2

Slide 15

### Propositional (Boolean) Logic

Let  $\Phi$  be a set of atomic propositions, each intended to represent a sentence.

E.g.

$\text{muddy}_k$  representing “Child  $k$  is muddy”

$\text{holds}_a(c)$  representing “player  $a$  holds card  $c$ ”

Slide 16

### Logical operators

$\neg$  - Not

$\wedge$  - And

$\vee$  - Or

$\Rightarrow$  - implies, if ... then ...

$\Longleftrightarrow$  - if and only if

Slide 17

## Formulas of Propositional Logic

The set of formulas of propositional logic are defined by

1. If  $p \in \Phi$  then  $p$  is a formula.
2. If  $\phi$  is a formula then  $\neg\phi$  is a formula
3. If  $\phi_1, \phi_2$  are formulas then so is  $\phi_1 \wedge \phi_2$ .
4. Nothing is a formula unless it can be shown to be a formula using the above.

Slide 18

All other boolean operators can be defined using only  $\neg$  and  $\wedge$

$\phi_1 \vee \phi_2$  is  $\neg((\neg\phi_1) \wedge (\neg\phi_2))$

$\phi_1 \Rightarrow \phi_2$  is  $(\neg\phi_1) \vee \phi_2$

$\phi_1 \iff \phi_2$  is  $(\phi_1 \Rightarrow \phi_2) \wedge (\phi_2 \Rightarrow \phi_1)$

Slide 19

Examples:

$p$

$p \wedge \neg p$

$(p \wedge q) \Rightarrow p$

Slide 20

## Semantics of Propositional Logic

A *state of the world* determines which sentences are true.

Represent this by an *assignment*  $\alpha : \Phi \rightarrow \{\text{true}, \text{false}\}$

Write  $\alpha \models \phi$  for “ $\phi$  is true with respect to assignment  $\alpha$ ”

$\alpha \models p$  if  $\alpha(p) = \text{true}$ , for  $p \in \Phi$

$\alpha \models \neg\phi$  if not  $\alpha \models \phi$

$\alpha \models \phi_1 \wedge \phi_2$  if  $\alpha \models \phi_1$  and  $\alpha \models \phi_2$

Slide 21

## Validity

A formula  $\phi$  of propositional logic is *valid*, (or *a tautology*), written  $\models \phi$ , if  $\alpha \models \phi$  for all assignments  $\alpha$ .

Examples:

$$\models p \Rightarrow p$$

$$\models \phi \vee \neg\phi \text{ ( for all formulas } \phi \text{)}$$

$$\models ((p \wedge q) \Rightarrow r) \iff (p \Rightarrow (q \Rightarrow r))$$

Slide 22

## A Language for Knowledge

Suppose that there are  $n$  agents.

The formulas of the logic of knowledge are defined by

1. If  $p \in \Phi$  then  $p$  is a formula
2. If  $\phi$  is a formula then  $\neg\phi$  is a formula
3. If  $\phi_1, \phi_2$  are formulas then  $\phi_1 \wedge \phi_2$ , is a formula
4. **If  $\phi$  is a formula, then so is  $K_i\phi$ , for  $i = 1 \dots n$**
5. Nothing is a formula unless it can be shown to be a formula using the above.

Slide 23

Examples:

$$K_2\text{muddy}_3$$

$$K_1K_2\text{muddy}_3$$

$$K_1\neg K_2\text{muddy}_3$$

$$\neg K_1\neg K_2\text{muddy}_3$$

Slide 24

## Political Knowledge (Donald Rumsfeld, 2003)

As we know

There are known knowns

There are things we know we know

We also know

There are known unknowns

That is to say

We know there are some things

We do not know

But there are also unknown unknowns

The ones we don't know we don't know

Slide 25

## Semantics for Knowledge: Kripke Structures

A *Kripke structure* for  $n$  agents is a tuple  $(S, \pi, \mathcal{K}_1, \dots, \mathcal{K}_n)$  where

1.  $S$  is a set of states,
2.  $\pi : S \rightarrow \Phi \rightarrow \{\mathbf{true}, \mathbf{false}\}$  associates an assignment with every state,
3.  $\mathcal{K}_i \subseteq S \times S$  is an *equivalence relation* on  $S$ , for each  $i = 1 \dots n$

Slide 26

$R \subseteq S \times S$  is an equivalence relation on  $S$  if

1. (Reflexivity)  $(s, s) \in R$  for all  $s \in S$ .
2. (Symmetry) If  $(s, t) \in R$  then  $(t, s) \in R$ , for all  $s, t \in S$ .
3. (Transitivity) If  $(s, t) \in R$  and  $(t, u) \in R$  then  $(s, u) \in R$ , for all  $s, t, u \in S$ .

Slide 27

## Semantics

We now treat formulas as being true/false at a state in a Kripke structure.

Write  $(M, s) \models \phi$  for “ $\phi$  is true at state  $s$  in structure  $M$ .”

$(M, s) \models p$  if  $\pi(s)(p) = \mathbf{true}$ , for  $p \in \Phi$

$(M, s) \models \neg\phi$  if not  $(M, s) \models \phi$

$(M, s) \models \phi_1 \wedge \phi_2$  if  $(M, s) \models \phi_1$  and  $(M, s) \models \phi_2$

$(M, s) \models K_i\phi$  if  $(M, t) \models \phi$  for all  $t$  such that  $(s, t) \in \mathcal{K}_i$

Slide 28

## Example: Cards

Suppose there are three cards  $A, B, C$ . Players 1 and 2 get one card each, the other remains face down.

Represent a state by a tuple  $(x, y)$  where  $x, y \in \{A, B, C\}$  and  $x \neq y$ .

$x$  is the card held by player 1

$y$  is the card held by player 2

Propositions:  $\mathbf{holds}_a(c)$  where  $a \in \{1, 2\}$  is an agent and  $c \in \{A, B, C\}$  is a card.

$\pi((x, y))(\mathbf{holds}_a(c)) = \mathbf{true}$  iff  $(a = 1 \text{ and } c = x) \text{ or } (a = 2 \text{ and } c = y)$

$(x, y)\mathcal{K}_1(x', y')$  iff  $x = x'$

$(x, y)\mathcal{K}_2(x', y')$  iff  $y = y'$

Slide 29

Why not just treat worlds as assignments to the basic propositions?

States also “contain information about what is known.”

Example: suppose player 1 might be blind.

States are now tuples  $(x, y, b)$  where  $x, y \in \{A, B, C\}$  and  $b \in \{0, 1\}$  represents whether 1 is blind

$\pi((x, y, b))(\text{holds}_a(c)) = \text{true}$  iff  $(a = 1 \text{ and } c = x) \text{ or } (a = 2 \text{ and } c = y)$

$(x, y, b)\mathcal{K}_1(x', y', b')$  iff  $b = b'$  and  $(x = x' \text{ or } b = 1)$

$(x, y, b)\mathcal{K}_2(x', y', b')$  iff  $y = y'$

Note  $\pi((x, y, 0)) = \pi((x, y, 1))$

Slide 30

## Properties of Knowledge

K1.  $K_i\varphi \wedge K_i(\varphi \Rightarrow \psi) \Rightarrow K_i\psi$

K2.  $K_i\varphi \Rightarrow \varphi$

K3.  $K_i\varphi \Rightarrow K_iK_i\varphi$

K4.  $\neg K_i\varphi \Rightarrow K_i\neg K_i\varphi$

Slide 31

## Validity

Write  $\models \phi$  if  $(M, s) \models \phi$  for all structures  $M$  and states  $s$  of  $M$ .

If  $\models \varphi$  then  $\models K_i\varphi$

If  $\models \varphi$  and  $\models \varphi \Rightarrow \psi$  then  $\models \psi$ .

Slide 32

## Common and Distributed Knowledge

Add the following to the language: if  $\phi$  is a formula and  $G \subseteq \{1 \dots n\}$  is a group of agents, then the following are formulas..

$E_G\phi$  — everyone in the group  $G$  knows  $\phi$

$C_G\phi$  — it is common knowledge in the group  $G$  that  $\phi$

$D_G\phi$  — it is distributed knowledge in the group  $G$  that  $\phi$



Slide 33

## Semantics

Define  $E_G^k \phi$  by  $E_G^0 \phi = \phi$  and  $E_G^{k+1} \phi = E_G E_G^k \phi$ .

Extend the semantics by the following clauses:

$(M, s) \models E_G \phi$  if  $(M, s) \models K_i \phi$  for all  $i \in G$

$(M, s) \models C_G \phi$  if  $(M, s) \models E_G^k \phi$  for all  $k = 1, 2, \dots$

$(M, s) \models D_G \phi$  if  $(M, t) \models \phi$  for all  $t$  such that  $(s, t) \in K_i$  for all  $i \in G$

Slide 34

## An alternate formulation of common knowledge

Let  $G$  be a group of agents.

Say state  $t$  is *G-reachable from state  $s$  in  $k$  steps* if there exists a sequence  $s_0, s_1, \dots, s_k$  of states such that  $s_0 = s$ ,  $s_k = t$  and for all  $j = 0 \dots k$  there exists  $i \in G$  such that  $s_j \mathcal{K}_i s_{j+1}$

Say state  $t$  is *G-reachable from state  $s$*  if there exists  $k \geq 0$  such that  $t$  is *G-reachable from  $s$  in  $k$  steps*.

Slide 35

## Lemma:

$(M, s) \models E_G^k \phi$  iff  $(M, t) \models \phi$  for all  $t$  that are  $G$ -reachable from  $s$  in  $k$  steps

$(M, s) \models C_G \phi$  iff  $(M, t) \models \phi$  for all  $t$  that are  $G$ -reachable from  $s$

Slide 36

## Properties of Common Knowledge

Write  $M \models \phi$  if  $(M, s) \models \phi$  for all states  $s$  of  $M$ .

C1.  $M \models E_G \phi \iff \bigwedge_{i=1}^m K_i \phi$

C2.  $M \models C_G \phi \Rightarrow E_G(\phi \wedge C_G \phi)$

RC. If  $M \models \phi \Rightarrow E_G(\psi \wedge \phi)$  then  $M \models \phi \Rightarrow C_G \psi$

lide 37

### Properties of Distributed Knowledge

$$\models D_{\{i\}}\phi \iff K_i\phi$$

$$\models D_G\phi \Rightarrow D_{G'}\phi \text{ if } G \subseteq G'$$

lide 38

### Kripke Structure for Muddy Children