# **Non-Normal Super-Strict Implications**

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This paper introduces the logics of super-strict implications that are based on C.I. Lewis' non-normal modal logics S2 and S3. The semantics of these logics is based on Kripke's semantics for non-normal modal logics. This solves a question we left open in a previous paper by showing that these logics are weakly connexive.

### 1 Introduction

It is widely recognised, that implication has a fundamental role in logic and deductive reasoning—see, e.g., [17, 19, 20]—and, hence, in philosophy 'since the essence of philosophy, and especially of dialectics, lies in argumentation and reasoning' [20, p. 1]. Nonetheless, there is no general agreement about the correct formal rendering of implication. The well-known rendering of implication as material implication ( $\supset$ ) has been defined, among others, by Russell [23, p. 75–6]:

The essential property that we require of implication is this: 'What is implied by a true proposition is true'. It is in virtue of this property that implication yields proofs. But this property by no means determines whether anything, and if so what, is implied by a false proposition. What it does determine is that, if p implies q, then it cannot be the case that p is true and q is false, i.e. it must be the case that either p is false or q is true. The most convenient interpretation of implication is to say, conversely, that if either p is false or q is true, then 'p implies q' is to be true. Hence 'p implies q' is to be defined to mean: 'Either p is false or q is true'.

Accordingly, in classical logic  $A \supset B$  is taken to be equivalent with  $\neg A \lor B$ : it is true whenever A is false or B is true. Even if someone agrees with Russell on the essential property of implication, there is room to be dissatisfied with material implications having a false antecedent. Many found this explication of implication wanting because it falls prey to the so-called *paradoxes of material implication*:

$$\neg A \supset (A \supset B) \qquad B \supset (A \supset B) \tag{PMI}$$

C.I. Lewis [9, 10] argued that  $\supset$  with its paradoxes is acceptable for some uses of implication but not for others, in particular for those where implication expresses a relation of logical entailment. Thus, he proposed to supplement classical logic with a stronger implicative operator called *strict implication* ( $\dashv$ ). The formula  $A \dashv B$  is true if it is impossible that A is true while B is false, or equivalently if it is necessary that  $A \supset B$ . Semantically, strict implication can be expressed in Kripke's relational semantics for modal logics by taking  $A \dashv B$  to be equivalent to  $\Box(A \supset B)$ : it is true at a point w if B is true at every point accessible from w where A is true.

Some connexivists [13] and relevantists [1, 20] argued that we should not accept  $\exists$  as a formal explication of entailment-expressing uses of implication because of the so-called *paradoxes of strict* 

implication:

$$\perp \dashv B$$
  $A \dashv \top$  (PSI)

These formulas are valid in Lewis' systems of strict implication. Moreover, also the modalised version of these paradoxes— $\Box \neg A \supset (A \dashv B)$  and  $\Box B \supset (A \dashv B)$ —are valid. Connexivists and relevantists quarrel with these formulas because, roughly, they take A to entail—and thus imply—B only if the truth of B is connected to/dependent on the truth of A.

One way to resist this line of thought is to claim that the entailment relation holds whenever an argument is such that it is impossible for its premisses to be true while its conclusion is false, cf. [4, p. 203]. From this perspective the paradoxes of strict implication should be accepted as sound principles and -3 can be taken as a correct explication of entailment. Lewis [10, p. 250] proposed also a more formal argument—his so-called *independent proof*—for the soundness of PSI. This proof is based on accepting the following inferential principles:

 $\wedge E$ . From a conjunction we can derive each one of its conjuncts.

 $\vee I$ . From a formula A we can derive each disjunction having A as one of its disjuncts.

DisjSill. From a disjunction and the negation of one of its disjuncts we can derive the other disjunct.

These principles are all the ingredient needed for the following derivation of an arbitrary formula *B* from a contradiction  $A \land \neg A$  (i.e., they are sufficient to validate the *ex falso quodlibet*):

$$\frac{A \wedge \neg A}{A \vee B} \wedge E \qquad A \wedge \neg A \wedge E \\ A \vee B \qquad A \wedge \neg A \qquad A \wedge E \\ B \qquad DisjSill$$

Moreover, if we take strict implication to be an object language representation of the underlying derivability relation—i.e., if we assume the deduction theorem for  $\neg$ —then we must accept the following version of the first paradox of strict implication:  $(A \land \neg A) \neg B$ . Neither connexivists nor relevantists are convinced by these arguments. First, they do not accept that A entails B whenever it is impossible for A to be true and B false: this explication of entailment doesn't account for the fact that an entailment needs a connection between its antecedent(s) and its consequent. Second, they reject the *ex falso quodlibet* and at least one of the principles used in Lewis' independent proof: connexivists usually reject  $\land E$  and/or the law of *simplification*:  $(A \land B) \neg A$ ; relevantists usually reject *DisjSill*.

The rejection of ex falso quodlibet, be it based on the rejection of  $\land E$  or of DisjSill, involves a major departure from classical logic since it means that at least one of  $\land$ ,  $\lor$ , and  $\neg$  does not satisfy its Boolean semantics. Thus neither connexivism nor relevantism can be seen as supplementation of classical logic. In [6] we proposed an alternative solution that sides with connexivists and relevantists in claiming that there are entailment-related uses of implication where PSI are not acceptable while at the same time siding with Lewis in expressing these uses of implication in a supplementation of classical logic. This proposal is based on introducing two strengthenings of normal strict implication called, respectively, weak ( $\triangleright$ ) and strong ( $\blacktriangleright$ ) super-strict implication (SSI). The formula  $A \triangleright B$  is defined to be true at a point w of a relational model if both  $A \rightarrow B$  and  $\Diamond A$  are true at w. Intuitively,  $\triangleright$  has been introduced

<sup>&</sup>lt;sup>1</sup>Routley takes the failure of simplification as a distinctive feature of connexive logics, but this is not so since, e.g., Wansing's system C rejects *DisjSill* but accepts simplification and conjunctive elimination. The system C is interesting from the present perspective because its implication is both connexive and strict, cf. [14]. We are grateful to a reviewer for highlighting this connection.

<sup>&</sup>lt;sup>2</sup>If, moreover,  $\lozenge \neg B$  is true at w then  $A \triangleright B$  is true therein. We will focus on  $\triangleright$  since  $\triangleright$  can be taken as a defined symbol.

in [6] as expressing implications where the truth of the succedent depends, in some minimal sense, on that of the antecedent and it accords with the following amendment of Russell's essential property of implication:

what is implied by a true and possible proposition is true. It is in virtue of this property that implication yields truths.

Neither PSI nor their modalised version are valid if we replace  $\neg$ 3 with  $\triangleright$  given that the antecedent of these formulas is either impossible (for the first paradox) or possibly contingent (for the second one). What becomes valid, instead, is the negation of the first paradox:  $\neg(\bot \triangleright B)$ . Moreover, as shown in [6], all normal SSI are weakly connexive in that they validate *Aristotle's Theses*:

$$\neg (A \rhd \neg A) \qquad \neg (\neg A \rhd A) \tag{AT}$$

and weak Boethius' Theses:

$$(A \rhd B) \supset \neg(A \rhd \neg B) \qquad (A \rhd \neg B) \supset \neg(A \rhd B) \tag{wBT}$$

SSI are a supplementation of classical logic just like strict implication and modal logics. This means that the *ex falso quodlibet* and all the principles used to derive it in Lewis' independent proof hold in logics of SSI. The difference with  $\neg$ 3 is that neither the deduction theorem nor the law of simplification holds for  $\triangleright$ . In these respects logics of SSI differ from most other connexive logics. Another striking difference is that, just like for Pizzi's [16] *consequential implication*, strong Boethius' thesis does not hold for  $\triangleright$ : the formula  $(A \triangleright B) \triangleright \neg (A \triangleright \neg B)$  is not valid in general and we don't know whether it is valid in some class of relational frames. This is a price we paid to have a paradox-free and weakly connexive implication that is a simple modal supplementation of classical logic.

One question that was left open in [6] is whether non-normal logics of SSI are connexive and well-behaved like the normal ones. This question is interesting from both a logical and a philosophical perspective. Logically, it is interesting because, as far as we know, all modally definable connexive implications are based on the relational semantics for normal modalities even if the necessitation rule— which allows to infer  $\Box A$  from A—doesn't seem to have any relation with connexivity. Philosophically, it is interesting because  $\rhd$  can be seen as an amended version of Lewis'  $\dashv$ , and it is well-known that—even if he introduced both the normal systems of  $\dashv$  S4 and S5 and the non-normal ones S1, S2 and S3—Lewis' favourite systems of strict implication were the non-normal systems S2 and, to a lesser extent, S1. System S3 and its extensions validate the following form of transitivity  $(A \dashv B) \dashv ((B \dashv C) \dashv (A \dashv C))$  that Lewis [10, p. 496] did not accept as a valid principle of implication. *Mutatis mutandis*, cf. Sect. 4, this can be used as a motivation to choose S2 as the best system of SSI. This paper solves the question in [6] to the affirmative by introducing the S2- and S3-based logics of SSI and by showing that they are weakly connexive and well-behaved like the normal ones.

The rest of the paper is organised as follows. Section 2 recaps the normal logics of SSI as they have been introduced in [6]. Section 3 sketches Lewis' non-normal logics of strict implication S2 and S3. Section 4 introduces the S2- and S3-based non-normal logics of SSI and discusses some of their features.

<sup>&</sup>lt;sup>3</sup>Another connexive system that rejects simplification while accepting  $\wedge E$  is Nelson's [13] one; nevertheless Nelson's connexive system has a conjunction that is weaker than the classical one, cf. [11].

<sup>&</sup>lt;sup>4</sup>Claudio Pizzi suggested to call *Boethian* logics validating AT and wBT but not strong BT.

<sup>&</sup>lt;sup>5</sup>We won't consider here non-normal logics where at least one direction of  $\Box(A \land B) \supset \subset (\Box A \land \Box B)$  fails.

<sup>&</sup>lt;sup>6</sup>Lewis' system S1 will not be considered here since its treatment requires a much more complicated semantics that is based on a mixture of relational and neighbourhood semantics for non-normal logics, cf [3, 22].

### 2 Normal super-strict implication

We sketch here the logics of normal SSI. For simplicity, we depart from the presentation given in [6] by treating  $\blacktriangleright$  as a defined symbol. The language  $\mathcal{L}^{\triangleright}$  is defined by the following grammar, where  $p \in \mathscr{P}$  for a denumerable set of sentential variables  $\mathscr{P}$ ,

$$A ::= p \mid \bot \mid A \land A \mid A \lor A \mid A \supset A \mid A \rhd A \tag{\mathscr{L}^{\triangleright}}$$

Parentheses follow the usual conventions and  $\triangleright$  binds lighter than other operators. Capital roman letters will be used as metavariables for formulas. The symbol  $\top$  is a short for  $\bot \supset \bot$  and  $\neg A$  is short for  $A \supset \bot$ . Finally,  $\blacktriangleright$  can be expressed in terms of  $\triangleright$  according to the following definition:

$$A \triangleright B \equiv ((A \triangleright B) \land (\neg B \triangleright \top)) \tag{Def.} \triangleright)$$

The semantics of SSI is the usual relational semantics for normal modalities, cf. [5]. In particular a *frame* is a pair  $\mathscr{F} = \langle \mathscr{W}, \mathscr{R} \rangle$ , where  $\mathscr{W}$  is a non-empty set of *points* (or *worlds*) and  $\mathscr{R} \subseteq \mathscr{W} \times \mathscr{W}$  is binary *accessibility relation* on  $\mathscr{W}$ . A model  $\mathscr{M}$  is a frame augmented with an *interpretation function*  $\mathscr{I} : \mathscr{P} \longrightarrow 2^{\mathscr{W}}$  mapping each sentential variables to the set of points where that variable is true.

Truth of a formula A at a point w of a model  $\mathcal{M}$ , to be written as  $\models_w \mathcal{M}$ , or simply as  $\models_w A$  when the model is clear from the context, is defined as usual for sentential variables and for the extensional operators (e.g., a conjunction is true at a point w whenever both conjuncts are true at w). Truth for formulas having  $\triangleright$  as principal operator is defined as follows:

$$\models_{w}^{\mathscr{M}} A \triangleright B$$
 iff for all  $v \in \mathscr{W}$ , if  $w\mathscr{R}v$  and  $\models_{v}^{\mathscr{M}} A$ , then  $\models_{v}^{\mathscr{M}} B$  & some  $v \in \mathscr{W}$  is such that  $w\mathscr{R}v$  and  $\models_{v}^{\mathscr{M}} A$ 

Truth in a model ( $\models^{\mathscr{M}} A$ ) is defined as truth on every point of that model; validity in a frame  $\mathscr{F}$  ( $\mathscr{F} \models A$ ) and validity in a class  $\mathscr{C}$  of frames ( $\mathscr{C} \models A$ ) is defined as truth in every model based either on that frame or in that class of frames, respectively; where a model is based on a frame if it is obtained by adding an interpretation function to that frame.

An easy calculation shows that the truth-clause for  $A \triangleright B$  would be as follows:

$$\models_{w}^{\mathscr{M}} A \triangleright B$$
 iff for all  $v \in W$ , if  $wRv$  and  $\models_{v}^{\mathscr{M}} A$ , then  $\models_{v}^{\mathscr{M}} B$  & some  $v \in W$  is such that  $wRv$  and  $\models_{v}^{\mathscr{M}} A$  & some  $v \in W$  is such that  $wRv$  and  $\not\models_{v}^{\mathscr{M}} B$ 

Moreover, it is possible to express all of  $\Diamond$ ,  $\Box$ , and  $\dashv$  in terms of  $\triangleright$  according to these definitions:

$$\lozenge A \equiv A \rhd \top$$
 (Def.  $\lozenge$ )

$$\Box A \equiv \neg(\neg A \rhd \top) \tag{Def. } \Box)$$

$$A \dashv B \equiv \neg((A \land \neg B) \rhd \top) \tag{Def. \dashv}$$

Over models based on a serial frame (i.e., such that  $\forall w \in \mathcal{W} . \exists v \in \mathcal{W} . w \Re v$ ) we can simplify the definition of  $\Box A$  by expressing it as  $\top \rhd A$ .

By a SSI-logic we mean the set of all  $\mathscr{L}^{\triangleright}$ -formulas that are valid in some given class of frames. In [6] we studied the SSI-logics that are definable by some combination of the following properties of  $\mathscr{R}$ : seriality, reflexivity, transitivity, symmetry, and Euclideaness—i.e., for the modal logics in the cube of normal modalities [5].

A proof-theoretic characterization of SSI-logics has been given in [6] by means of labelled sequent calculi in the style of [12]. Alternatively, it is possible to use existing axiomatizations of normal modal logics, see [5], to give a proof-theoretic characterization of SSI-logics since  $A \triangleright B$  be can be expressed in modal terms as  $\Diamond A \land \Box (A \supset B)$ . This fact has been exploited in [6] to show that the complexity of the satisfiability problem in a SSI-logic is equivalent to that in the corresponding modal logic (where the modal logics S5 and KD45 are NP-complete and most of the other logics are PSPACE-complete).

We end this section by presenting some facts about SSI-logics [6].

#### Lemma 1.

- 1. Neither the paradoxes of material implication nor those of strict implication are valid for >.
- 2. The negation of the first paradox of strict implication is valid for  $\triangleright$ .
- 3. Aristotle's theses and weak Boethius' theses are valid for  $\triangleright$ .
- *4.* Strong Boethius' theses are not valid for  $\triangleright$ .
- 5. Neither reflexivity  $A \triangleright A$  nor contraposition  $(A \triangleright B) \supset (\neg B \triangleright \neg A)$  hold.
- 6. Modus ponens holds for  $\triangleright$  only over classes of frames that are reflexive: the following rule

$$\frac{\mathscr{C} \models A \rhd B \qquad \mathscr{C} \models A}{\mathscr{C} \models B}$$

preserves validity only if  $\mathscr{C}$  is a class of reflexive frames.

# 3 Non-normal strict implication

The language of strict implication  $(\mathcal{L}^{\dashv})$  is determined by the following grammar (where  $p \in \mathcal{P}$ ):

$$A ::= p \mid \bot \mid A \land A \mid A \lor A \mid A \supset A \mid A \dashv A \tag{\mathscr{L}^{\dashv}}$$

We use the same conventions we introduced for  $\mathcal{L}^{\triangleright}$ ; and we define the normal modalities as follows:

$$\Box A \equiv \top \neg \exists A \tag{Def.} \neg \Box$$

$$\Diamond A \equiv \neg(\top \dashv \neg A) \tag{Def.}^{\dashv} \Diamond)$$

In talking about Lewis' systems we will often move from the language  $\mathcal{L}^{\dashv}$  to the standard modal language  $\mathcal{L}^{\square}$  having  $\square$  and  $\lozenge$  as primitive operators and  $\dashv$  as an abbreviation for  $\square(A \supset B)$ .

Lewis' systems S2 and S3 are not normal systems of modal logic in that they do not validate the unrestricted necessitation rule

$$\frac{A}{\Box A}$$
 (RN)

but only a restricted version thereof, called  $RN^{rest}$ , where A has to be a theorem of the classical propositional calculus PC. Consequently, these systems contain no theorem of shape  $\Box\Box A$  and we must use

a semantics that is a generalisation of the relational semantics for normal modalities. A simple relational semantics for Lewis' non-normal systems S2 and S3 has been introduced in [7]. It is based on the fact that these systems can be consistently extended with the formula  $\Diamond \Diamond A$ : we can have S2- and S3-models with points where every formula,  $\bot$  included, is possible. Kripke used this fact to extend the well-known relational semantics for normal modalities with so-called *non-normal points* where every formula is possible and no formula is necessary, see [2, 4, 7, 21].

Formally, this means that a non-normal frame is a triple  $\mathbf{F} = \langle \mathcal{W}, \mathcal{R}, \mathcal{N} \rangle$  where  $\mathcal{W}$  and  $\mathcal{R}$  are as for normal modalities, see §2, and  $\mathcal{N}$  is a subset of  $\mathcal{W}$  (containing the *normal points* of the model).<sup>7</sup> A non-normal model  $\mathbf{M}$  is a frame together with an interpretation function  $\mathcal{I}$  mapping propositional variables to subsets of  $\mathcal{W}$ . Truth of a formula at a point of a model is defined as usual for extensional formulas and it is defined as follows for  $\exists$ :

$$\models_{w}^{\mathbf{M}} A \ni B$$
 iff  $w \in \mathcal{N}$  and for all  $v \in \mathcal{W}$ , if  $w \mathcal{R} v$  and  $\models_{v}^{\mathbf{M}} A$ , then  $\models_{v}^{\mathbf{M}} B$ 

Given Definitions Def.  $\dashv$   $\square$  and Def.  $\dashv$   $\lozenge$ , we have the following truth clauses for  $\square$  and  $\lozenge$ :

$$\models_{w}^{\mathbf{M}} \Box A$$
 iff  $w \in \mathcal{N}$  and for all  $v \in \mathcal{W}$ , if  $w \mathcal{R} v$  then  $\models_{v}^{\mathbf{M}} A$   
 $\models_{w}^{\mathbf{M}} \Diamond A$  iff  $w \notin \mathcal{N}$  or some  $v \in \mathcal{W}$  is such that  $w \mathcal{R} v$  and  $\models_{v}^{\mathbf{M}} A$ 

The definition of truth in a model, and consequently that of validity in a (class of) frame(s), differs from the usual one, see  $\S 2$ , in that we restrict quantification to normal points: a formula is true in  $\mathbf{M}$  if it is true in all normal points of the model (so that whether A is true in a non-normal point is irrelevant for evaluating its truth in a model and its validity).

The logic S2 is defined as the set of all formulas that are valid in reflexive non-normal frames and S3 as the set of formulas valid in reflexive and transitive non-normal frames. The logic defined by the class of all non-normal frames is called S2<sup>0</sup>. We refer the reader to [4] for other logics defined in terms of classes of non-normal frames.

As we have already anticipated the rule RN does not preserve validity in these classes of frames. To illustrate, the formula  $\Box \top$  is valid in S2<sup>0</sup>-frames but  $\Box \Box \top$  is not valid: a frame  $\mathbf{F}$  containing both a normal point w and a non-normal point that is accessible from w is such that  $\mathbf{F} \models \Box \top$  and  $\mathbf{F} \not\models \Box \Box \top$ .

A proof-theoretic characterization of S2 and S3 in terms of labelled sequent calculi defined over the language  $\mathcal{L}^{\square}$  has been given in [21]. Lewis' [10] axiomatization of S2 is as follows (taking  $\vee$ ,  $\supset$ , and  $\dashv$  as defined symbols and using A[B/p] (A[B//p]) for the formula obtained by replacing, every (some, resp.) occurrence of p in A with an occurrence of B).

**Definition 2** (Lewis' axiomatisation of S2).

<sup>&</sup>lt;sup>7</sup>As in [2, 21], we lift the restrictions given in [4, 7] that (i) a frame must contain some normal point and that (ii)  $\forall w \in \mathcal{W} / \mathcal{N} : \exists u \in \mathcal{N} . u \mathcal{R} w$ .

7

• Axioms:

1. 
$$(p \land q) \dashv (q \land p)$$

2. 
$$(p \land q) \dashv p$$

3. 
$$p \rightarrow (p \land p)$$

4. 
$$((p \land q) \land r) \rightarrow (p \land (q \land r))$$

5. 
$$((p \rightarrow q) \land (q \rightarrow r)) \rightarrow (p \rightarrow r)$$

6. 
$$(p \land (p \dashv q)) \dashv q$$

7. 
$$\Diamond(p \land q) \dashv \Diamond p$$

· Rules:

1. Uniform substitution: 
$$\frac{A}{A[B/p]}$$

2. Substitution of strict equivalents:

$$\frac{A \qquad (B \dashv C) \land (C \dashv B)}{A[B//C]}$$

3. Adjunction: 
$$\frac{A \quad B}{A \wedge B}$$

4. Strict detachment: 
$$\frac{A \rightarrow B}{B} = \frac{A}{B}$$

The calculus S3 is obtained by replacing axiom 7 with:  $(p \dashv q) \dashv (\neg \Diamond q \dashv \neg \Diamond p)$ .<sup>8</sup> One peculiarity of Lewis' axiomatic systems is that they are not given as extensions of the classical propositional calculus PC (even if they contain it). A more customary axiomatization of S2, based on PC and taking  $\square$  as primitive modal operator, has been given by Lemmon [8].

**Definition 3** (Lemmon's axiomatisation of S2).

• Axioms:

*PC*. All theorems of PC   
*K*. 
$$\Box (A \supset B) \supset (\Box A \supset \Box B)$$
   
*T*.  $\Box A \supset A$ 

• Rules:

MP. Modus Ponends: 
$$\frac{A \supset B \qquad A}{B}$$

$$\Box (A \supset B)$$
RR. Recker's rule: 
$$\Box (\Box A \supset \Box R)$$

*BR*. Becker's rule: 
$$\Box(\Box A \supset \Box B)$$

 $N^{rest}$ . Restricted necessitation:  $\Box A$  provided A is a theorem of PC

Lemmon's axiomatization of S3 is obtained by replacing axiom K with  $\Box(A \supset B) \supset \Box(\Box A \supset \Box B)$  and by dropping Becker's rule. An axiomatization of the logic S2<sup>0</sup> is obtained by dropping the reflexivity axiom T from Lemmon's axiomatization of S2.

# 4 Non-normal super-strict implication

We are now in a position to introduce non-normal logics of SSI. We will use the language  $\mathscr{L}^{\triangleright}$  and, as will be clear from the semantics, we can still define all of  $\triangleright$ ,  $\square$ ,  $\lozenge$ , and  $\dashv$  in terms of  $\triangleright$  as we did in  $\S 2.^{10}$  The *weight* of a formula, w(A), is defined as the number of binary operators occurring therein; the *modal depth* of a formula, m(A), is defined as the maximal nesting of modalitites— $\triangleright$ ,  $\triangleright$ ,  $\square$ ,  $\lozenge$ , and  $\dashv$ —in A.

The semantics for non-normal SSI is based on Kripke's one for the logics S2 and S3. In particular, a *frame* is a triple  $\mathbf{F} = \langle \mathcal{W}, \mathcal{R}, \mathcal{N} \rangle$ , where  $\mathcal{W} \neq \emptyset$ ,  $\mathcal{R} \subseteq \mathcal{W} \times \mathcal{W}$ , and  $\mathcal{N} \subseteq \mathcal{W}$ ; a *model*  $\mathbf{M}$  is a frame augmented with an interpretation function  $\mathcal{I} : \mathcal{P} \longrightarrow \mathcal{W}$ . The truth clause for  $A \rhd B$  is as follows:

$$\models_{w}^{\mathbf{M}} A \rhd B$$
 iff for all  $v \in W$ , if  $wRv$  and  $\models_{v}^{\mathbf{M}} A$ , then  $\models_{v}^{\mathbf{M}} B$  & some  $v \in W$  is such that  $wRv$  and  $\models_{v}^{\mathbf{M}} A$  &  $w \in \mathcal{N}$ 

<sup>&</sup>lt;sup>8</sup>Axiom 7 is a theorem of S3; if we remove axiom 7 we obtain Lewis' system S1.

<sup>&</sup>lt;sup>9</sup>Axiom *K* is derivable and Becker's rule is admissible in S3.

<sup>&</sup>lt;sup>10</sup>And, *vice versa*,  $\triangleright$  is definable in terms of any one of  $\square$ ,  $\lozenge$  and  $\dashv$ , but not in terms of  $\triangleright$ .

*Truth in a model* is defined as truth in every normal point of that model and *validity* in a (class of) frame(s) is defined as truth in every model based on that (class of) frame(s).

As for Lewis' systems we will consider the non-normal  $\mathcal{L}^{\triangleright}$ -logics S2<sup>0</sup>, S2, and S3, which are defined as the set of formulas valid in the class of all frames, all reflexive frames and all preordered frames, respectively.

As we have already anticipated, in non-normal logics  $\triangleright$  is interdefinable with any one of  $\exists$ ,  $\square$  and  $\lozenge$  just like in normal logics, cf. Section 2. As a consequence we have that Lewis' and Lemmon's axiomatisations of S2<sup>0</sup>, S2 and S3 are axiomatisations of the corresponding non-normal logics of SSI (over the  $\mathcal{L}^{\exists}$ - and the  $\mathcal{L}^{\square}$ -language, respectively) and that these logics of SSI are decidable, cf. [15] for the decidability of S2 and S3.

We move on to present some interesting features of logics on non-normal SSI which, all in all, will show that these logics have a behaviour that resembles that of normal ones. We begin by listing some important formulas that do not belong to these logics.

**Lemma 4.** None of the following formulas is valid in classes of non-normal frames:

- 1. The paradoxes of material implication:  $\neg A \rhd (A \rhd B)$  and  $B \rhd (A \rhd B)$ ;
- 2. The paradoxes of strict implication:  $\bot \rhd B$  and  $A \rhd \top$ ;
- *3. Reflexivity:*  $A \triangleright A$ ;
- *4. Contraposition:*  $(A \triangleright B) \supset (\neg B \triangleright \neg A)$ .

*Proof.* These formulas are not valid in normal frames, cf. Lemma 1, and, hence, cannot be valid in frames generalising them such as non-normal frames.  $\Box$ 

Next we show that these logics are weakly connexive in that they validate Aristotle's and weak Boethius' theses, though in general they do not validate strong Boethius' thesis.

**Theorem 5.** Aristotle's and weak Boethius' theses belong to the  $\mathcal{L}^{\triangleright}$ -logic  $S2^0$ .

*Proof.* The lemma follows from the fact that AT and wBT are valid in all normal frames, cf. Lemma 1. These theses have modal depth 1 and for formulas of modal depth 1 validity in non-normal frames coincide with validity in normal ones (since we are restricting attention to normal points).  $\Box$ 

Next, we consider the status of Lewis' axioms, see Definition 2, when we replace  $\neg 3$  with  $\triangleright$ . This is important to better understand how  $\triangleright$  differs from  $\neg 3$ .

**Lemma 6.** None of the axioms of Lewis' axiomatization of S2 (nor of S3) is valid if we replace (all) instances of  $\rightarrow$ 3 with instances of  $\triangleright$ . 11

*Proof.* It is immediate to notice that the antecedent of each one of Lewis' axioms is such that we can easily define a point of a model—be it reflexive or not—where one of its instances is not possible, and this is enough to conclude that these formulas are not valid if we replace  $\neg 3$  with  $\triangleright$ .

Things goes differently with Lewis' rules since all of them preserve validity over reflexive frames, where reflexivity is needed only for super-strict detachment (just as for strict detachment).

The results in Lemma 6 might appear rather disappointing and at first glance they can be taken as a reason to dismiss SSI as an interesting explication of entailment-related implications. Even if it might be acceptable that simplification (Axiom 2) does not hold, it would be difficult to argue that entailment

<sup>&</sup>lt;sup>11</sup>Nonetheless,  $\triangleright$  is transitive in that the formula  $((A \triangleright B) \land (B \triangleright C)) \supset (A \triangleright C)$  is valid in every non-normal frame.

is not closed under commutativity and associativity of  $\wedge$  (Axioms 1 and 4) and duplication (Axiom 3); this would be even harder for transitivity of implication (Axiom 5), the formula version of detachment (Axiom 6) and the consistency axiom (Axiom 7). It seems that we amended ∃ in such a way that the price paid to avoid the paradoxes of strict implication is too high. Nevertheless, we believe this conclusion is too fast. In general, we should separate formulas into impossible, necessary and contingent ones. Anyone believing that SIP are not valid principles of entailment should agree that Lewis' axioms should not be accepted when they have an impossible antecedent—e.g., a contradictory conjunction does not entail anything irrespectively of the order of its conjuncts and, hence, entailment is not closed under the commutativity of impossible conjunctions. When, instead, we consider instances of Lewis' axioms with a necessary antecedent then we should accept them as sound principles of entailment. These instances pose no threat since they are valid when we replace ¬3 with ▷ whenever we consider reflexive frames—every necessary formula is also possible over reflexive frames—and there are independent reason to restrict our attention to reflexive frames—e.g., super-strict detachment preserves validity only over reflexive frames and we took the truth of A and of A implies B to yield the truth of B. The problem lies in instances having a contingent antecedent. These instances are sound principles of entailment but they are not valid for >: they are true at worlds where the antecedent is possible and false at worlds where it is not possible. Even if the antecedent in general is contingent, in worlds where it is not possible it expresses a relative impossibility and, hence, the entailment relation should not hold just like instances with an (absolutely) impossible antecedent. Things are different in worlds where the contingent antecedent is possible and its truth necessitates that of the succedent. This is a paradigmatic situation where the antecedent should imply the consequent according to the entailment-related uses of implication we aim at capturing. In this situation Lewis' axioms are true but not valid. Nevertheless we can transform each one of Lewis' axioms into a valid formula governing ⊳ if we restrict our attention to instances having a possible antecedent modulo reflexivity for Axiom 6.

**Lemma 7.** *If*  $A \triangleright B$  *is one of Lewis' axioms given in Definition 2 (with*  $\dashv$  *replaced by*  $\triangleright$ ) *then the formula*  $\Diamond A \supset (A \triangleright B)$  *is valid over reflexive non-normal frames.* 

*Proof.* The definition of  $\triangleright$  coincides with that of  $\dashv$  whenever we have an implication whose antecedent is possible.

This lemma shows that if we replace  $\neg$  with  $\triangleright$  because we don't accept paradoxical instances of PSI then we obtain as valid exactly all and only the non-paradoxical instances of Lewis' implications. <sup>12</sup> It also shows that the correct logic of SSI should be at least as strong as S2 since we must restrict our attention to reflexive frames if we want super-strict detachment—as well as its formula-version—to hold. Moreover, we can use an analogous argument to show that the correct logic of SSI shouldn't be stronger than S2. Indeed, in S3 the formula  $\lozenge(A \triangleright B) \supset ((A \triangleright B) \triangleright (\lozenge(B \triangleright C) \supset ((B \triangleright C) \triangleright (\lozenge(A \supset (A \triangleright C)))))$  is valid, but this formula is not better motivated than  $(A \neg B) \neg ((B \neg C) \neg ((A \neg C)))$  in Lewis' approach.

We conclude this section by noticing that also any dissatisfaction with the non-reflexivity of  $\triangleright$  can be mitigated along the same line since  $\Diamond A \supset (A \triangleright A)$  is valid. What is not valid is  $\neg \Diamond A \supset (A \triangleright A)$ , but instances of reflexivity of  $\triangleright$  with a (locally) impossible antecedent should not be accepted as valid according to the present paradox-free explication of implication and entailment.

<sup>&</sup>lt;sup>12</sup>Observe that  $\Diamond A \supset (A \rhd B)$  can be used as an alternative definition of strict implication in the language  $\mathcal{L}^{\triangleright}$ . Nevertheless, we take the main role of this formula role to be that of separating paradoxical and non paradoxical instances of valid strict implications; where, according to the present perspective, only the latter can be taken to express an entailment related implication.

### 5 Conclusion

This paper presented the non-normal logics of SSI S2 and S3 as a way to amend Lewis' → and express paradox-free notions of implication and entailment. The semantics for these logics is based on Kripke's semantics for non-normal logics and, this paper has shown, non-normal logics of SSI are as well-behaved as normal ones. In particular they validate the same connexive principles and can thus be seen as a simple and natural family of non-normal connexive supplementations of classical logics.

This paper has not addressed the problem of giving a proof-theoretic characterisation of these logics, if not by translating them into the language  $\mathcal{L}^{\exists}$  or  $\mathcal{L}^{\Box}$ . If we want to stay within the language  $\mathcal{L}^{\triangleright}$  then labelled calculi for these logics can be given by a mixture of the calculi in [6] with those in [21]. A characterisation in terms of axiomatic systems can be given by exploiting the techniques used in [18]. We believe this latter problem to be of particular interest given the results of Lemma 6, but we leave it for future research.

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