DPST1092 24T3 — MIPS Basics

<https://www.cse.unsw.edu.au/~dp1092/24T3/>

Computer Architecture

In 1092 we run a compiler and produce a executable file.

We run a compiler (dcc or gcc)

- an executable file hello is stored on the hard drive
- We then run ./hello

What happens when you run this program? Where does it go?

How does it get executed? How does the CPU interact with hello?

Memory

Lets take this step by step

We have a hard drive

- Hard drives are refered to as secondary storage
- \bullet they usually have a large capacity
- they are non volatile memory (doesnt get erased when you turn off computer)

We have RAM(which for us is primary memory)

- **•** primary memory
- very fast, traditionally closer to the CPU
- **•** lower capacity

A program needs to be 'in memory' in order for it to run

- 'memory' typically refers to RAM
- Communicating between the CPU and drives is too slow

Our executiable file contains information on how to set up memory

- What instructions does the CPU need to follow?
- What strings do we need loaded into memory?

Our file is stored in RAM as 1's and 0's it is in machine code.

Machine code and Assembly

001000010000100100000000000001100 addi \$t1, \$t0, 12

Figure 1: Encoding

Why Study Assembler?

Useful to know assembly language because …

- sometimes you are *required* to use it:
	- \triangleright e.g., low-level system operations, device drivers
- improves your understanding of how compiled programs execute
	- \blacktriangleright very helpful when debugging
	- ▶ understand performance issues better
- performance tweaking ... squeezing out last pico-second
	- \blacktriangleright re-write that performance critical code in assembler!

Trivia:

- there are games created in pure assembler
	- ▶ e.g., [RollerCoaster Tycoon](https://en.wikipedia.org/wiki/RollerCoaster_Tycoon_(video_game))

CPU Architecture Families Used in Game Consoles

What A CPU Looks Like

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CPU Components

A typical modern CPU has:

- a set of *data* registers
- a set of *control* registers (including PC)
- a *control unit* (CU)
- an *arithmetic-logic unit* (ALU)
- a *floating-point unit* (FPU)
- access to *memory* (RAM)
- a set of simple (or not so simple) instructions
	- ▶ transfer data between memory and registers
	- ▶ compute values using ALU/FPU
	- ▶ make tests and transfer control of execution

Figure 3: A Simple CPU

Different types of processors have different configurations of the above

Fetch-Execute Cycle

● typical CPU program execution pseudo-code:

```
uint32 t program counter = START ADDRESS;
while (1) {
    uint32 t instruction = memory[program counter];
```

```
// move to next instruction
program_counter++;
```
// branches and jumps instruction may change program_counter execute(instruction, &program counter);

}

Fetch-Execute Cycle

Executing an instruction involves:

- determine what the *operator* is
- determine if/which *register(s)* are involved
- determine if/which *memory location* is involved \bullet
- carry out the operation with the relevant operands
- \bullet store result, if any, in appropriate register / memory location

Example instruction encodings (not from a real machine):

Figure 4: Fake Instructions

Assembly Language

Instructions are simply bit patterns

Could write **machine code** program just by specifying bit-patterns e.g as a sequence of hex digits:

0x3c041001 0x34840000 0x20020004 0x0000000c 0x20020000 0x03e00008

- ▶ unreadable!
- ▶ difficult to maintain!

Solution: **assembly language**, a symbolic way of specifying machine code

- write instructions using names rather than bit-strings
- refer to registers using either numbers or names
- allow names (labels) associated with memory addresses

MIPS Instructions

MIPS has several classes of instructions:

- *load and store* … transfer data between registers and memory
- *computational* … perform arithmetic/logical operations
- *jump and branch* … transfer control of program execution
- *coprocessor* … standard interface to various co-processors
	- ▶ coprocessors implement floating-point operations
	- ▶ wont be covered in DPST1092
- *special* … miscellaneous tasks (e.g. syscall)

MIPS Architecture: Registers

MIPS CPU has

- 32 general purpose registers
	- \blacktriangleright Every register that we will be dealing with is 32-bits
- Registers are located on the actual CPU which makes them very fast
	- \triangleright We will be working with these registers
- The PC register is a special 32-bit register
	- \blacktriangleright used to keep track of which instruction needs to be executed next
	- ▶ modified by *branch* and *jump* instructions
- *Hi* and *Lo* store results of mult and div
	- \blacktriangleright these are used when we have a result that doesnt fit a single register
	- ▶ accessed by mthi and mflo instructions only

Registers can be referred to as numbers (\$0…\$31), or by symbolic names (\$zero…\$ra)

Some registers have special uses:

- register \$0 (\$zero) always has value 0, can not be changed
- **•** register \$31 (\$ra) is changed by jal and jalr instructions
- registers \$1 (\$at) reserved for mipsy to use in pseudo-instructions
- FOR NOW: we are going to be using $(\text{$\frac{1}{2}$}t0) (\text{$\frac{1}{2}$}t0)$ and $(\text{$\frac{1}{2}$}a0)$

MIPS Architecture: Integer Registers

MIPS Architecture: Integer Registers … Usage Convention

- Except for registers zero and ra (0 and 31), these uses are *only* programmer's conventions
	- \blacktriangleright no difference between registers 1..30 in the silicon
- Some of these conventions are irrelevant when writing tiny assembly programs
	- \blacktriangleright follow them anyway
	- ▶ it's good practice
- \bullet for general use, keep to registers $t0..t9$, s0..s7
- use other registers only for conventional purpose
	- \blacktriangleright e.g. only, and always, use a0..a3 for arguments
- *never* use registers at, k0,k1

System Calls

- None of the instructions we have access to can interact with the outside world (eg. printing, scanning)
- This is done for security reasons so users cannot interact with the Operating System We ask the operating system to perform these tasks for us - this process is called a system call
- The operating system can access privileged instructions on the CPU (eg. communicating to other devices)
- mipsy simulates a very basic operating system
- There are many types of system calls. MIPS has several that you will use.

System calls

These are some of the most popular system calls for MIPS.

Figure 5: Systems calls

System calls (How to use them)

Using system calls varies depending on what you want to do.

- We specify which system call we want in Sv0 \bullet
	- \circ eq.print_int is syscall 1:

$1i$ $Sv0$ 1

 \bullet We specify arguments (if any)

li \$a0 42

- We transfer execution to the operating system \bullet
	- The OS will fulfil our request if it looks sane \circ

syscall

Some syscalls may return a value - check syscall table

MIPS Architecture

MIPS is a well-known and simple architecture

- historically used everywhere from supercomputers to game consoles
- **o** still popular in some embedded fields: e.g., modems/routers, TVs
- but being out-competed by ARM and, more recently, RISC-V

DPST1092 uses the MIPS32 version of the MIPS family.

DPST1092 uses simulators, not real MIPS hardware:

- mipsy ... command-line-based emulator written by Zac
	- ▶ source code: *<https://github.com/insou22/mipsy>*
- mipsy-web … web (WASM) GUI-based version of mipsy written by Shrey
	- ▶ *<https://cgi.cse.unsw.edu.au/~cs1521/mipsy/>*

MIPS vs mipsy

MIPS is a machine architecture, including instruction set mipsy is an *simulator* for the MIPS instruction set

- reads text files containing instruction + directives
- converts to machine code and loads into "memory"
- **•** provides some debugging capabilities
	- \triangleright single-step, breakpoints, view registers/memory, ...
- provides mechanism to interact with operating system (syscall)

Also provides extra instructions, mapped to MIPS core set:

- **•** provide convenient/mnemonic ways to do common operations
	- ▶ e.g. move \$s0, \$v0 rather than addu \$s0, \$v0, \$0

Using Mipsy

How to to execute MIPS code without a MIPS

- \bullet 1092 mipsy
	- ▶ command line tool on CSE systems
	- ▶ load programs using command line arguments
	- \blacktriangleright interact using stdin/stdout via terminal
- mipsy_web
	- ▶ *<https://cgi.cse.unsw.edu.au/~cs1521/mipsy/>*
	- ▶ runs in web browser, load programs with a button
	- \blacktriangleright visual environment for debugging
- spim, xspim, qtspim
	- ▶ older widely used MIPS simulator
	- ▶ beware: missing some pseudo-instructions used in 1521 for function calls

Our First MIPS program

```
C
int main(void) {
    printf("I love MIPS\n");
    return 0;
}
```
MIPS

```
# print a string in MIPS assembly
main:
   # ... pass address of string as argu
   la $a0, string
   # ... 4 is printf "%s" syscall numbe
   li $v0, 4
   syscall
   li $v0, 0 # return 0
   jr $ra
    .data
string:
    .asciiz "I love MIPS\n"
```
[source code for i_love_mips.s](https://cgi.cse.unsw.edu.au/~dp1092/24T3//topic/mips_basics/code/i_love_mips.s)

MIPS Assembly Language

MIPS assembly language programs contain

- assembly language instructions
- labels ... appended with :
- comments … introduced by #
- directives ... symbol beginning with .
- constant definitions, equivalent of #define in C, e.g:

MAX NUMBERS = 1000

Programmers need to specify

- \bullet data objects that live in the data region
- \bullet instruction sequences that live in the code/text region

Each instruction or directive appears on its own line.

A simple MIPS Computation

Data and Addresses

All operations refer to data, either

- **o** in a register
- in memory
- a constant which is embedded in the instruction itself

Computation operations refer to registers or constants.

Only load/store instructions refer to memory.

The syntax for constant value is C-like:

1 3 -1 -2 12345 0x1 0xFFFFFFFF 0b10101010 0123 "a string" 'a' 'b' '1' '\n' '\0'

Describing MIPS Assembly Operations

Registers are denoted:

For example:

$$
\quad \text{add} \quad \$R_d, \$R_s, \$R_t \qquad \Longrightarrow \qquad R_d := R_s + R_t
$$

Integer Arithmetic Instructions

- integer arithmetic is 2's-complement
- **a** also: **addu, subu, mulu, addiu** equivalent instructions which do not stop execution on overflow.
- no *subi* instruction use *addi* with negative constant
- mipsy will translate **add** and **sub** of a constant to **addi**
	- ▶ e.g. mipsy translates **add \$t7, \$t4, 42** to **addi \$t7, \$t4, 42**
	- ▶ for readability use **addi**, e.g. **addi \$t7, \$t4, 42**

Integer Arithmetic Instructions - Example

Extra Integer Arithmetic Instructions (little used in DPST1092)

- **mult** provides multiply with 64-bit result
	- ▶ **mul** instruction provides only 32-bit result (can overflow)
- \textsf{mipsy} translates $\textsf{rem}\, r_d, r_s, r_t$ to $\textsf{div}\, r_s, r_t$ plus $\textsf{mfhi}\, r_d$
- **mipsy** translates $\operatorname{\mathsf{div}} r_d, r_s, r_t$ to $\operatorname{\mathsf{div}} r_s, r_t$ plus <code>mflo</code> r_d

Bit Manipulation Instructions

mipsy translates $\textbf{not}~r_d, r_s$ to $\textbf{nor}~r_d, r_s$, \$0

Shift Instructions

- **srl** and **srlv** shift zeros into most-significant bit
	- ▶ this matches shift in C of **unsigned** value
- **sra** and **srav** propagate most-significant bit
	- ▶ this ensure shifting a negative number divides by 2
- **slav** and **sla** don't exist as arithmetic and logical left shifts are the same
- mipsy provides **rol** and **ror** pseudo-instructions which rotate bits
	- ▶ real instructions on some MIPS versions
	- \triangleright no simple C equivalent

Arithmatic shift is used when are dealing with a signed number.

- If 11010100 (-42 in 2s compliment) is shifted 2 bytes to the right
- We get 11110101 which is -11 in 2s compliment. (this is division by 2^n)
- When right shift it pads left most bits (MSB) with 1
- When left shift it pads right most bits (LSB) with 1

Logic shifts just simply pad both sides with 0s.

Miscellaneous Instructions

Example Use of Miscellaneous Instructions

Important System Calls

We often rely on system services to do things for us. **syscall** lets us make *system calls* for these services.

mipsy provides a set of system calls for I/O and memory allocation. **\$v0** specifies which system call —

A simple system call Example

```
int main(void) {
    printf("%d", 42);
    return 0;
}
```
MIPS

[source code for print_42.s](https://cgi.cse.unsw.edu.au/~dp1092/24T3//topic/mips_basics/code/print_42.s)

C

Exercise: Add two numbers 1

Write MIPS assembler that behaves like

```
int main(void) {
   int x = 3;
   printf("%d\n", x+5);
   return 0;
}
```
Hints:

- li loads a constant into a register
- the number stored in \$v0 determines what kind of system call it is
- syscall 1 prints the number located in register \$a0
- syscall 11 prints the character located in register \$a0

Exercise: Add two numbers 2

Write MIPS assembler that behaves like

```
int x = 3;
int main(void) {
   printf("%d\n", x+5);
   return 0;
}
```
Hints:

- word allocates 4 bytes in memory and initialises it
- you will need to load the value of X from RAM into a register to do the addition using lw

Exercise: Add two numbers interactively

Write MIPS assembler that behaves like

```
int main(void) {
   int x, y;
   printf("First number: ");
   scanf("%d", &x);
   printf("Second number: ");
   scanf("%d", &y);
   print(f("%d\n', x+v));
   return 0;
}
```
Exercise: Find the average

Modify the code from the previous example so it implements the following:

```
int main(void) {
   int x, y;
   printf("First number: ");
   scanf("%d", &x);
   printf("Second number: ");
   scanf("%d", &y);
   printf("%d\n", (x+y)/2);
   return 0;
}
```
Exercise: Bit operations

Write the following code:

```
int main(void) {
   unsigned int x = 42;
   x = x \gg 1;
   printf("%d\n",x);
   x = x \iff 2;printf("%d\n",x);
   return 0;
}
```
MIPS Programming

Writing correct assembler directly is hard.

Recommended strategy:

- write,test & debug a solution in C
- map down to "simplified" C
- test "simplified" C and ensure correct
- **•** translate simplified C statements to MIPS instructions

Simplified C

- **o** does *not* have complex expressions
- *does* have one-operator expressions

Adding Three Numbers — C to Simplified C

```
int main(void) {
    int w = 3:
    int x = 17:
    int y = 25;
    printf("%d\n", w + x + y);
    return 0;
}
source code for add.c
```
C

Simplified C

```
int main(void) {
   int w, x, y, z;
   w = 3;x = 17;
   y = 25;
   Z = W + X;
   Z = Z + y;printf("%d", z);
   printf("%c", '\n');
   return 0;
}
```
[source code for add.simple.c](https://cgi.cse.unsw.edu.au/~dp1092/24T3//topic/mips_basics/code/add.simple.c)

Adding Two Numbers — Simple C to MIPS **Simplified C MIPS**

add 3, 17 and 25 then print the result main: # w in \$t0, x in \$t0 # y in $$t2$, z in $$t3$ li $$t0, 3$ # $w = 3;$ li $$t1, 17$ # $x = 17;$ li $$t2, 25$ # $y = 25;$ **add** $$t3, $t0, $t1 # z = w + x$ **add** \$t3, \$t3, \$t2 # z = z + y move $\sin 3$ # printf("%d", z); li \$v0, 1 **syscall** \mathbf{li} $\mathsf{5a0}$, $\mathsf{In'}$ # printf("%c", $\mathsf{In'}$); li \$v0, 11 **syscall** li $$v0, 0$ # return 0 **jr** \$ra [source code for add.s](https://cgi.cse.unsw.edu.au/~dp1092/24T3//topic/mips_basics/code/add.s)

MIPS Instructions

Instructions are simply bit patterns. MIPS instructions are 32-bits long, and specify … - an **operation** (e.g. load, store, add, branch, …) - zero or more **operands** (e.g. registers, memory addresses, constants, …)

Some possible instruction formats

bits

Encoding MIPS Instructions as 32 bit Numbers

all instructions are variants of a small number of bit patterns … register numbers always in same place

Pseudo-instructions

Pseudo-instructions are not real MIPS instructions, but are provided by mipsy for our convenience