COMP4161 Advanced Topics in Software Verification





based on slides by J. Blanchette, L. Bulwahn and T. Nipkow

Thomas Sewell, Miki Tanaka, Rob Sison T3/2024



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^aa1 due; ^ba2 due; ^ca3 due

Part 1: Automatic Proof and Disproof

→ Sledgehammer: automatic proofs

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→ Quickcheck: counter example by testing



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→ Quickcheck: counter example by testing

→ Nitpick: counter example by SAT



Part 1: Automatic Proof and Disproof

→ Sledgehammer: automatic proofs

→ Quickcheck: counter example by testing

→ Nitpick: counter example by SAT

Based on ancient slides by Jasmin Blanchette, Lukas Bulwahn, and Tobias Nipkow (TUM).



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The key:

Efficient reasoning engines, and restricted logics.



Automation in Isabelle

1980s rule applications, write ML code



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Automation in Isabelle

```
1980s rule applications, write ML code
1990s simplifier, automatic provers (blast, auto), arithmetic
2000s embrace external tools, but don't trust them (ATP/SMT/SAT)
```



Sledgehammer

Sledgehammer:

→ Connects Isabelle with ATPs and SMT solvers: E, SPASS, Vampire, CVC4, Yices, Z3



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- → Connects Isabelle with ATPs and SMT solvers: E, SPASS, Vampire, CVC4, Yices, Z3
- → Simple invocation:
 - → Users don't need to select or know facts
 - → or ensure the problem is first-order
 - → or know anything about the automated prover



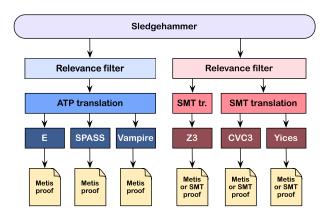
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- → Simple invocation:
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 - → or know anything about the automated prover
- → Exploits local parallelism and remote servers

DEMO: SLEDGEHAMMER

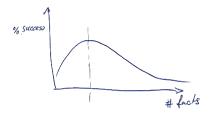
Sledgehammer Architecture



Fact Selection

Provers perform poorly if given 1000s of facts.

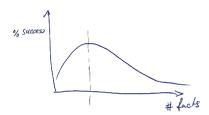
- → Best number of facts depends on the prover
- → Need to take care which facts we give them
- → Idea: order facts by relevance, give top n to prover (n = 250,1000,...)



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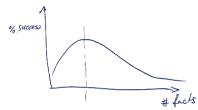


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- → Idea: order facts by relevance, give top n to prover (n = 250,1000,...)
- → Meng & Paulson method: lightweight, symbol-based filter
- → Machine learning method:

 look at previous proofs to get a probability of relevance



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Source: higher-order, polymorphism, type classes

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→ First-order:

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→ Encode types:

- → Monomorphise (generate multiple instances), or
- → Encode polymorphism on term level

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Need to check/reconstruct proof.

→ Re-find using Metis Usually fast and reliable (sometimes too slow)

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- → Rerun external prover for trusted replay Used for SMT. Re-runs prover each time!
- → Recheck stored explicit external representation of proof Used for SMT, no need to re-run. Fragile.
- → Recast into structured Isar proof Fast, not always readable.



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- → How many can sledgehammer solve?

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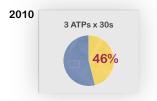
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- → 2012: Better integration with SPASS. 64% SPASS best (small margin)
- → 2013: Machine learning for fact selection. 69% Improves a few percent across provers.



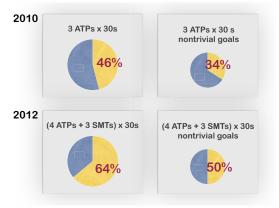
Evaluation



Evaluation



Evaluation





Judgement Day (2016)

Prover	MePo	MaSh	MeSh	Any selector
CVC4 1.5pre	679	749	783	830
E 1.8	622	601	665	726
SPASS 3.8ds	678	684	739	789
Vampire 3.0	703	698	740	789
veriT 2014post	543	556	590	655
Z3 4.3.2pre	638	668	703	788
Any prover	801	885	919	943

Fig. 15 Number of successful Sledgehammer invocations per prover on 1230 Judgment Day goals

919/1230 = 74%

Sledgehammer rules!

Example application:

- → Large Isabelle/HOL repository of algebras for modelling imperative programs (Kleene Algebra, Hoare logic, . . . , \approx 1000 lemmas)
- → Intricate refinement and termination theorems
- → Sledgehammer and Z3 automate algebraic proofs at textbook level.



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"The integration of ATP, SMT, and Nitpick is for our purposes very very helpful." – G. Struth

DISPROOF

Testing can show only the presence of errors, but not their absence. (Dijkstra)

Testing cannot prove theorems



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Sad facts of life:

- → Most lemma statements are wrong the first time.
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Find counter examples automatically!



Quickcheck

Lightweight validation by testing.



Quickcheck

Lightweight validation by testing.

- → Motivated by Haskell's QuickCheck
- → Uses Isabelle's code generator
- → Fast
- → Runs in background, proves you wrong as you type.
 - → You have probably seen this already!

Quickcheck

Covers a number of testing approaches:

- → Random and exhaustive testing.
- → Smart test data generators.
- → Narrowing-based (symbolic) testing.

Creates test data generators automatically.



DEMO: QUICKCHECK

Test generators for datatypes

Fast iteration in continuation-passing-style

datatype
$$\alpha$$
 list = Nil | Cons α (α list)

Test function:

$$test_{\alpha \ list} P = P \ Nil \ and also \ test_{\alpha} \ (\lambda x. \ test_{\alpha \ list} \ (\lambda xs. \ P \ (Cons \ x \ xs)))$$



distinct $xs \Longrightarrow distinct (remove1 x xs)$

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test-distinct $_{\alpha}$ $_{list}$ P = P Nil andalso $test_{\alpha}$ $(\lambda x. \ test$ -distinct $_{\alpha}$ $_{list}$ $(if \ x \notin xs \ then \ (\lambda xs. \ P \ (Cons \ x \ xs))$ else True))

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test-distinct_{α list} P = P Nil andalso $test_{\alpha}$ (λx . test-distinct_{\alpha} list (if $x \notin x$ s then (λx s. P (Cons x xs)) else True))

Use data flow analysis to figure out which variables must be computed and which generated.



Narrowing

Symbolic execution with demand-driven refinement

- → Test cases can contain variables
- → If execution cannot proceed: instantiate with further symbolic terms

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False for any x, no further instantiations for x necessary.



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Symbolic execution with demand-driven refinement

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Implementation:

Lazy execution with outer refinement loop. Many re-computations, but fast.



Quickcheck Limitations

Only executable specifications!

- → No equality on functions with infinite domain
- → No axiomatic specifications



NITPICK

Nitpick

Finite model finder

- → Based on SAT via Kodkod (backend of Alloy prover)
- → Soundly approximates infinite types



Nitpick Successes

- → Algebraic methods
- → C++ memory model
- → Found soundness bugs in TPS and LEO-II

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Fan mail:

"Last night I got stuck on a goal I was sure was a theorem. After 5–10 minutes I gave Nitpick a try, and within a few secs it had found a splendid counterexample—despite the mess of locales and type classes in the context!"



DEMO: NITPICK

Automation Summary

→ Proof: Sledgehammer



Automation Summary

→ Proof: Sledgehammer

→ Counter examples: Quickcheck



Automation Summary

→ Proof: Sledgehammer

→ Counter examples: Quickcheck

→ Counter examples: Nitpick



ISAR (PART 1)

A LANGUAGE FOR STRUCTURED PROOFS

Motivation

Is this true:
$$(A \longrightarrow B) = (B \lor \neg A)$$
 ?

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Is this true:
$$(A \longrightarrow B) = (B \lor \neg A)$$
 ?
YES!

```
apply (rule iffI)
apply (cases A)
apply (rule disjI1)
apply (erule impE)
apply assumption
apply assumption
apply (rule disjI2)
apply assumption
apply (rule impI)
apply (erule disjE)
apply assumption
apply (erule notE)
apply assumption
apply (erule notE)
apply assumption
done
```



Motivation

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apply (rule iffI)
 apply (cases A)
  apply (rule disjI1)
  apply (erule impE)
  apply assumption
  apply assumption
 apply (rule disjI2)
                                   by blast
                             or
 apply assumption
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OK it's true. But WHY? This doesn't look like typical maths proofs.

done



apply scripts

→ hard to read



apply scripts

- → hard to read
- → hard to maintain

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- → hard to read
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No explicit structure.



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apply scripts

What about...

- → hard to read
- → hard to maintain

- → Elegance?
- → Explaining deeper insights?

No explicit structure.



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Isar!



A typical Isar proof

```
proof
   assume formula<sub>0</sub>
  have formula<sub>1</sub> by simp
  have formula<sub>n</sub> by blast
   show formula<sub>n+1</sub> by . . .
qed
```



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proves formula_0 \Longrightarrow formula_{n+1}
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              qed
             proves formula_0 \Longrightarrow formula_{n+1}
(analogous to assumes/shows in lemma statements)
```

```
\begin{split} & \mathsf{proof} = \mathbf{proof} \; [\mathsf{method}] \; \mathsf{statement}^* \; \mathbf{qed} \\ & | \; \mathbf{by} \; \mathsf{method} \\ & \mathsf{method} = (\mathsf{simp} \; \dots) \; | \; (\mathsf{blast} \; \dots) \; | \; (\mathsf{rule} \; \dots) \; | \; \dots \end{split}
```

proof [method] statement* qed

lemma " $[A; B] \Longrightarrow A \wedge B$ "

proof [method] statement* qed

lemma " $[A; B] \Longrightarrow A \wedge B$ " proof (rule conjl)

proof [method] statement* qed

lemma "[A; B]] ⇒ A ∧ B"
proof (rule conjl)
 assume A: "A"
from A show "A" by assumption

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lemma "[A; B]] ⇒ A ∧ B"
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lemma " $[A; B] \Longrightarrow A \wedge B$ "
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assume B: "B"
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→ proof (<method>) applies method to the stated goal



proof [method] statement* qed

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qed
```

- → proof (<method>) applies method to the stated goal
- → proof applies a single rule that fits

proof [method] statement* qed

```
lemma "[A; B] \Longrightarrow A \wedge B"
proof (rule conjl)
assume A: "A"
from A show "A" by assumption
next
assume B: "B"
from B show "B" by assumption
qed
```

→ proof (<method>) applies method to the stated goal

→ proof applies a single rule that fits

→ proof - does nothing to the goal

Look at the proof state!

lemma " $[A; B] \Longrightarrow A \wedge B$ " proof (rule conjl)

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 - 1. $\llbracket A; B \rrbracket \Longrightarrow A$
 - $2. \, \llbracket A;B \rrbracket \Longrightarrow B$

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- → so we need 2 shows: show "A" and show "B"

Look at the proof state!

lemma "
$$[A; B] \Longrightarrow A \wedge B$$
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- → proof (rule conjl) changes proof state to
 - 1. $\llbracket A; B \rrbracket \Longrightarrow A$
 - 2. $[\![A;B]\!] \Longrightarrow B$
- → so we need 2 shows: show "A" and show "B"
- → We are allowed to assume A, because A is in the assumptions of the proof state.

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lemma " $[A; B] \Longrightarrow A \wedge B$ " [prove]

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lemma " $[A; B] \Longrightarrow A \land B$ " [prove] **proof** (rule conjl) [state]

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```
lemma "[A; B] \implies A \land B" [prove] proof (rule conjl) [state] assume A: "A" [state]
```



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lemma "[A; B] \implies A \land B" [prove] proof (rule conjl) [state] assume A: "A" [state] from A [chain]
```



The Three Modes of Isar

- → [prove]: goal has been stated, proof needs to follow.
- → [state]: proof block has opened or subgoal has been proved, new from statement, goal statement or assumptions can follow.
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lemma "[A; B] \implies A \land B" [prove]
proof (rule conjl) [state]
assume A: "A" [state]
from A [chain] show "A" [prove] by assumption [state]
next [state] ...
```

Have

Can be used to make intermediate steps.

Example:



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lemma "
$$(x :: nat) + 1 = 1 + x$$
"

Have

Can be used to make intermediate steps.

Example:

```
lemma "(x :: nat) + 1 = 1 + x"

proof -

have A: "x + 1 = Suc x" by simp

have B: "1 + x = Suc x" by simp

show "x + 1 = 1 + x" by (simp only: A B)

qed
```

DEMO

Backward reasoning: ... have " $A \wedge B$ " proof

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→ proof picks an intro rule automatically

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- → proof picks an intro rule automatically
- \rightarrow conclusion of rule must unify with $A \wedge B$

Backward reasoning: ... have " $A \wedge B$ " proof

- → proof picks an intro rule automatically
- → conclusion of rule must unify with A \(\times B \)

```
Forward reasoning: ... assume AB: "A \wedge B" from AB have "..." proof
```

Backward reasoning: ... have " $A \wedge B$ " proof

- → proof picks an intro rule automatically
- → conclusion of rule must unify with A \(\times B \)

Forward reasoning: ... assume AB: " $A \land B$ " from AB have "..." proof

→ now proof picks an elim rule automatically



Backward reasoning: ... have " $A \wedge B$ " proof

- → proof picks an intro rule automatically
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Forward reasoning: ...

assume AB: " $A \wedge B$ " from AB have "..." proof

- → now proof picks an elim rule automatically
- → triggered by from

Backward reasoning: ... have " $A \wedge B$ " proof

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Forward reasoning: ...

assume AB: " $A \wedge B$ " from AB have "..." proof

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- first assumption of rule must unify with AB

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Forward reasoning: ...

```
assume AB: "A \wedge B" from AB have "..." proof
```

- → now proof picks an elim rule automatically
- → triggered by from
- first assumption of rule must unify with AB

General case: from $A_1 \dots A_n$ have R proof

- \rightarrow first *n* assumptions of rule must unify with $A_1 \ldots A_n$
- → conclusion of rule must unify with R



fix
$$v_1 \dots v_n$$

fix
$$v_1 \dots v_n$$

Introduces new arbitrary but fixed variables $(\sim parameters, \land)$

fix
$$v_1 \dots v_n$$

Introduces new arbitrary but fixed variables $(\sim parameters, \land)$

obtain $v_1 \dots v_n$ **where** $\langle prop \rangle \langle proof \rangle$

fix
$$v_1 \dots v_n$$

Introduces new arbitrary but fixed variables $(\sim \text{parameters}, \bigwedge)$

obtain
$$v_1 \dots v_n$$
 where $<$ prop $>$ $<$ proof $>$

Introduces new variables together with property

this = the previous fact proved or assumed



this the previous fact proved or assumed

then = from this



this = the previous fact proved or assumed

then = from this thus = then show



this = the previous fact proved or assumed

then = from this thus = then show hence = then have

this = the previous fact proved or assumed

then = from this thus = then show

hence = then have

with $A_1 \dots A_n = \text{from } A_1 \dots A_n \text{ this}$

this = the previous fact proved or assumed

then = from this thus = then show hence = then have

with $A_1 \dots A_n = \text{from } A_1 \dots A_n$ this

?thesis = the last enclosing goal statement

DEMO

Moreover and Ultimately

```
have X_1: P_1 \dots
have X_2: P_2 \dots
:
have X_n: P_n \dots
from X_1 \dots X_n show \dots
```



Moreover and Ultimately

```
have X_1: P_1 \dots
have X_2: P_2 ...
have X_n: P_n . . .
from X_1 \dots X_n show ...
```

wastes brain power on names $X_1 \dots X_n$



Moreover and Ultimately

```
have X_1: P_1 \dots
have X_2: P_2 \dots
:
have X_n: P_n \dots
from X_1 \dots X_n show \dots
```

wastes brain power on names $X_1 \dots X_n$

```
have P_1 ...
moreover have P_2 ...
:
moreover have P_n ...
ultimately show ...
```

show formula proof -



show formula proof - have $P_1 \lor P_2 \lor P_3$ proof>

```
\begin{array}{l} \textbf{show formula} \\ \textbf{proof -} \\ \textbf{have } P_1 \vee P_2 \vee P_3 \ < \textbf{proof} > \\ \textbf{moreover} \quad \{ \ \textbf{assume} \ P_1 \ \dots \ \textbf{have} \ ? \textbf{thesis} \ < \textbf{proof} > \} \end{array}
```

```
show formula
proof -
  have P_1 \vee P_2 \vee P_3 proof>
  moreover { assume P_1 ... have ?thesis <proof> }
  moreover { assume P_2 ... have ?thesis <proof> }
  moreover { assume P_3 ... have ?thesis <proof> }
```

```
show formula
proof -
  have P_1 \vee P_2 \vee P_3 proof>
  moreover { assume P_1 ... have ?thesis <proof> }
  moreover { assume P_2 ... have ?thesis <proof> }
  moreover { assume P_3 ... have ?thesis <proof> }
  ultimately show ?thesis by blast
qed
      { ...} is a proof block similar to proof ... ged
           { assume P_1 \dots have P proof> }
                   stands for P_1 \Longrightarrow P
```

Mixing proof styles

```
from ...
have ...
apply - make incoming facts assumptions
apply (...)
:
apply (...)
done
```

ISAR

(PART 2)

DATATYPES IN ISAR

Datatype case distinction

```
\begin{array}{c} \textbf{proof} \; (\text{cases} \; \textit{term}) \\ \textbf{case} \; \text{Constructor}_1 \\ \vdots \\ \textbf{next} \\ \vdots \\ \textbf{next} \\ \textbf{case} \; (\text{Constructor}_k \; \vec{x}) \\ \cdots \\ \vec{x} \; \cdots \end{array}
```

Datatype case distinction

```
proof (cases term)
   case Constructor1
next
next
  case (Constructor<sub>k</sub> \vec{x})
qed
          case (Constructor<sub>i</sub> \vec{x}) \equiv
          fix \vec{x} assume Constructor<sub>i</sub>: "term = Constructor<sub>i</sub> \vec{x}"
```

Structural induction for nat

```
show P n
proof (induct n)
  case 0
                   \equiv let ?case = P 0
  show ?case
next
  case (Suc n) \equiv fix n assume Suc: P n
                       let ?case = P (Suc n)
  ... n ...
  show ?case
qed
```

Structural induction: \Longrightarrow and \land

DEMO: DATATYPES IN ISAR

CALCULATIONAL REASONING

Prove:

$$x \cdot x^{-1} = 1$$
 using: assoc: $(x \cdot y) \cdot z = x \cdot (y \cdot z)$

left_inv: $x^{-1} \cdot x = 1$ left_one: $1 \cdot x = x$

Prove:

Prove:

$$x \cdot x^{-1} = 1 \cdot (x \cdot x^{-1})$$

 $\dots = 1 \cdot x \cdot x^{-1}$
 $\dots = (x^{-1})^{-1} \cdot x^{-1} \cdot x \cdot x^{-1}$
 $\dots = (x^{-1})^{-1} \cdot (x^{-1} \cdot x) \cdot x^{-1}$
 $\dots = (x^{-1})^{-1} \cdot 1 \cdot x^{-1}$
 $\dots = (x^{-1})^{-1} \cdot (1 \cdot x^{-1})$
 $\dots = (x^{-1})^{-1} \cdot x^{-1}$

assoc:
$$(x \cdot y) \cdot z = x \cdot (y \cdot z)$$

left_inv: $x^{-1} \cdot x = 1$
left_one: $1 \cdot x = x$

Prove:

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 $\dots = (x^{-1})^{-1} \cdot x^{-1} \cdot x \cdot x^{-1}$
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 $\dots = (x^{-1})^{-1} \cdot (1 \cdot x^{-1})$
 $\dots = (x^{-1})^{-1} \cdot x^{-1}$

assoc:
$$(x \cdot y) \cdot z = x \cdot (y \cdot z)$$

left_inv: $x^{-1} \cdot x = 1$
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Can we do this in Isabelle?

Prove:

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 $\dots = (x^{-1})^{-1} \cdot (1 \cdot x^{-1})$
 $\dots = (x^{-1})^{-1} \cdot x^{-1}$

assoc:
$$(x \cdot y) \cdot z = x \cdot (y \cdot z)$$

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Can we do this in Isabelle?

→ Simplifier: too eager

Prove:

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 $\dots = 1 \cdot x \cdot x^{-1}$
 $\dots = (x^{-1})^{-1} \cdot x^{-1} \cdot x \cdot x^{-1}$
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assoc:
$$(x \cdot y) \cdot z = x \cdot (y \cdot z)$$

left_inv: $x^{-1} \cdot x = 1$
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Can we do this in Isabelle?

- → Simplifier: too eager
- → Manual: difficult in apply style

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Prove:
$$x \cdot x^{-1} = 1 \cdot (x \cdot x^{-1})$$
 assoc:
$$(x \cdot y) \cdot z = x \cdot (y \cdot z)$$
 left.inv:
$$x^{-1} \cdot x = 1$$
 left.one:
$$1 \cdot x = x$$
 left.one:
$$1 \cdot x$$

Can we do this in Isabelle?

- → Simplifier: too eager
- → Manual: difficult in apply style
- → Isar: with the methods we know, too verbose



The Problem

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Each step usually nontrivial (requires own subproof)

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Each step usually nontrivial (requires own subproof) **Solution in Isar:**

→ Keywords also and finally to delimit steps

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- → ...: predefined schematic term variable, refers to right hand side of last expression

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Each step usually nontrivial (requires own subproof) **Solution in Isar:**

- → Keywords also and finally to delimit steps
- → ...: predefined schematic term variable, refers to right hand side of last expression
- → Automatic use of transitivity rules to connect steps

have " $t_0 = t_1$ " [proof] also



have "
$$t_0 = t_1$$
" [proof] also

calculation register $"t_0 = t_1"$

have "
$$t_0 = t_1$$
" [proof] also have "... = t_2 " [proof]

calculation register $"t_0 = t_1"$

have "
$$t_0 = t_1$$
" [proof] also have "... = t_2 " [proof] also

calculation register $"t_0 = t_1"$

"
$$t_0 = t_2$$
"

```
have "t_0 = t_1" [proof] also have "... = t_2" [proof] also : also
```

```
calculation register "t_0 = t_1" "t_0 = t_2" \vdots "t_0 = t_{n-1}"
```

```
have "t_0 = t_1" [proof] also have "... = t_2" [proof] also : also have "... = t_n" [proof]
```

```
calculation register "t_0 = t_1" "t_0 = t_2" \vdots "t_0 = t_{n-1}"
```

```
have "t_0 = t_1" [proof] also have "... = t_2" [proof] also : also have "... = t_n" [proof] finally
```

```
calculation register "t_0 = t_1" "t_0 = t_2" \vdots "t_0 = t_{n-1}" t_0 = t_n
```

```
have "t_0 = t_1" [proof]
                                                     calculation register
                                                     "t_0 = t_1"
also
have "... = t_2" [proof]
also
                                                    "t_0 = t_2"
                                                    "t_0 = t_{n-1}"
also
have "\cdots = t_n" [proof]
                                                     t_0 = t_n
finally
show P
— 'finally' pipes fact "t_0 = t_0" into the proof
```

More about also

 \rightarrow Works for all combinations of =, \leq and <.

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- → Uses all rules declared as [trans].



More about also

- \rightarrow Works for all combinations of =, \leq and <.
- → Uses all rules declared as [trans].
- → To view all combinations: print_trans_rules



have = " $I_1 \odot r_1$ " [proof] also have "... $\odot r_2$ " [proof] also



```
have = "I_1 \odot r_1" [proof] also have "... \odot r_2" [proof] also
```

Anatomy of a [trans] rule:

→ Usual form: plain transitivity $\llbracket l_1 \odot r_1; r_1 \odot r_2 \rrbracket \Longrightarrow l_1 \odot r_2$

```
have = "I_1 \odot r_1" [proof] also have "... \odot r_2" [proof] also
```

Anatomy of a [trans] rule:

- → Usual form: plain transitivity $[l_1 \odot r_1; r_1 \odot r_2] \Longrightarrow l_1 \odot r_2$
- → More general form: $\llbracket P \ l_1 \ r_1; Q \ r_1 \ r_2; A \rrbracket \Longrightarrow C \ l_1 \ r_2$



```
have = "I_1 \odot r_1" [proof] also have "... \odot r_2" [proof] also
```

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Examples:

→ pure transitivity: $[a = b; b = c] \implies a = c$

```
have = "I_1 \odot r_1" [proof] also have "... \odot r_2" [proof] also
```

Anatomy of a [trans] rule:

- → Usual form: plain transitivity $[l_1 \odot r_1; r_1 \odot r_2] \Longrightarrow l_1 \odot r_2$
- → More general form: $\llbracket P \ l_1 \ r_1; Q \ r_1 \ r_2; A \rrbracket \Longrightarrow C \ l_1 \ r_2$

- → pure transitivity: $[a = b; b = c] \implies a = c$
- \rightarrow mixed: $[a \le b; b < c] \implies a < c$

```
have = "I_1 \odot r_1" [proof] also have "... \odot r_2" [proof] also
```

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- → pure transitivity: $[a = b; b = c] \implies a = c$
- \rightarrow mixed: $[a \le b; b < c] \implies a < c$
- → substitution: $\llbracket P \ a; a = b \rrbracket \Longrightarrow P \ b$

```
have = "I_1 \odot r_1" [proof] also have "... \odot r_2" [proof] also
```

Anatomy of a [trans] rule:

- → Usual form: plain transitivity $[l_1 \odot r_1; r_1 \odot r_2] \Longrightarrow l_1 \odot r_2$
- → More general form: $\llbracket P \ l_1 \ r_1; Q \ r_1 \ r_2; A \rrbracket \Longrightarrow C \ l_1 \ r_2$

- → pure transitivity: $[a = b; b = c] \implies a = c$
- \rightarrow mixed: $[a \le b; b < c] \implies a < c$
- → substitution: $[P \ a; a = b] \implies P \ b$
- → antisymmetry: $[a < b; b < a] \implies False$

```
have = "I_1 \odot r_1" [proof] also have "... \odot r_2" [proof] also
```

Anatomy of a [trans] rule:

- → Usual form: plain transitivity $[l_1 \odot r_1; r_1 \odot r_2] \Longrightarrow l_1 \odot r_2$
- → More general form: $\llbracket P I_1 r_1; Q r_1 r_2; A \rrbracket \Longrightarrow C I_1 r_2$

- → pure transitivity: $[a = b; b = c] \implies a = c$
- \rightarrow mixed: $[a \le b; b < c] \implies a < c$
- → substitution: $[P \ a; a = b] \implies P \ b$
- → antisymmetry: [a < b; b < a] \Longrightarrow False
- → monotonicity: $[a = f b; b < c; \land x y. x < y \Longrightarrow f x < f y]] \Longrightarrow a < f c$

DEMO