

**COMP 4161**  
NICTA Advanced Course

**Advanced Topics in Software Verification**

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$\{P\} \dots \{Q\}$

- Syntax of a simple imperative language
- Operational semantics
- Program proof on operational semantics
- Hoare logic rules
- Soundness of Hoare logic

- Intro & motivation, getting started [1]
  
- Foundations & Principles
  - ▶ Lambda Calculus, natural deduction [1,2]
  - ▶ Higher Order Logic [3<sup>a</sup>]
  - ▶ Term rewriting [4]
  
- Proof & Specification Techniques
  - ▶ Inductively defined sets, rule induction [5]
  - ▶ Datatypes, recursion, induction [6, 7]
  - ▶ Hoare logic, proofs about programs, C verification [8<sup>b</sup>,9]
  - ▶ (mid-semester break)
  - ▶ Writing Automated Proof Methods [10]
  - ▶ Isar, codegen, typeclasses, locales [11<sup>c</sup>,12]

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<sup>a</sup>a1 due; <sup>b</sup>a2 due; <sup>c</sup>a3 due

**Last time:** Hoare rule application is nicer than using operational semantic.

**BUT:**

- it's still kind of tedious
- it seems boring & mechanical

**Automation?**

**Problem:** While – need creativity to find right (invariant)  $P$

**Solution:**

- annotate program with invariants
- then, Hoare rules can be applied automatically

**Example:**

$$\{M = 0 \wedge N = 0\}$$
$$\text{WHILE } M \neq a \text{ INV } \{N = M * b\} \text{ DO } N := N + b; M := M + 1 \text{ OD}$$
$$\{N = a * b\}$$

**pre**  $c$   $Q$  = **weakest**  $P$  **such that**  $\{P\} c \{Q\}$

With annotated invariants, easy to get:

$$\begin{aligned} \text{pre SKIP } Q &= Q \\ \text{pre } (x := a) Q &= \lambda\sigma. Q(\sigma(x := a\sigma)) \\ \text{pre } (c_1; c_2) Q &= \text{pre } c_1 (\text{pre } c_2 Q) \\ \text{pre } (\text{IF } b \text{ THEN } c_1 \text{ ELSE } c_2) Q &= \lambda\sigma. (b \longrightarrow \text{pre } c_1 Q \sigma) \wedge \\ &\quad (\neg b \longrightarrow \text{pre } c_2 Q \sigma) \\ \text{pre } (\text{WHILE } b \text{ INV } I \text{ DO } c \text{ OD}) Q &= I \end{aligned}$$

# Verification Conditions

$\{\text{pre } c \ Q\} \ c \ \{Q\}$  **only true under certain conditions**

These are called **verification conditions**  $\text{vc } c \ Q$ :

$\text{vc SKIP } Q$	$=$	True
$\text{vc } (x := a) \ Q$	$=$	True
$\text{vc } (c_1; c_2) \ Q$	$=$	$\text{vc } c_2 \ Q \wedge (\text{vc } c_1 \ (\text{pre } c_2 \ Q))$
$\text{vc } (\text{IF } b \ \text{THEN } c_1 \ \text{ELSE } c_2) \ Q$	$=$	$\text{vc } c_1 \ Q \wedge \text{vc } c_2 \ Q$
$\text{vc } (\text{WHILE } b \ \text{INV } I \ \text{DO } c \ \text{OD}) \ Q$	$=$	$(\forall \sigma. I \sigma \wedge b \sigma \longrightarrow \text{pre } c \ I \ \sigma) \wedge$ $(\forall \sigma. I \sigma \wedge \neg b \sigma \longrightarrow Q \ \sigma) \wedge$ $\text{vc } c \ I$

$$\text{vc } c \ Q \wedge (P \Longrightarrow \text{pre } c \ Q) \Longrightarrow \{P\} \ c \ \{Q\}$$

- $x := \lambda\sigma. 1$  instead of  $x := 1$  sucks
- $\{\lambda\sigma. \sigma x = n\}$  instead of  $\{x = n\}$  sucks as well

**Problem:** program variables are functions, not values

**Solution:** distinguish program variables syntactically

**Choices:**

- declare program variables with each Hoare triple
  - ▶ nice, usual syntax
  - ▶ works well if you state full program and only use vcg
- separate program variables from Hoare triple (use extensible records),  
indicate usage as function syntactically
  - ▶ more syntactic overhead
  - ▶ program pieces compose nicely



# DEMO

## Depending on language, model arrays as functions:

- Array access = function application:

$$a[i] = a \ i$$

- Array update = function update:

$$a[i] := v = a := a(i := v)$$

## Use lists to express length:

- Array access = nth:

$$a[i] = a \ ! \ i$$

- Array update = list update:

$$a[i] := v = a := a[i := v]$$

- Array length = list length:

$$a.length = length \ a$$

## Choice 1

**datatype** ref = Ref int | Null

**types** heap = int  $\Rightarrow$  val

**datatype** val = Int int | Bool bool | Struct\_x int int bool | ...

→ hp :: heap, p :: ref

→ Pointer access: \*p = the\_Int (hp (the\_addr p))

→ Pointer update: \*p ::= v = hp ::= hp ((the\_addr p) := v)

→ a bit klunky

→ gets even worse with structs

→ lots of value extraction (the\_Int) in spec and program

## Choice 2 (Burstall '72, Bornat '00)

**Example:** struct with next pointer and element

**datatype** ref = Ref int | Null

**types** next\_hp = int  $\Rightarrow$  ref

**types** elem\_hp = int  $\Rightarrow$  int

→ next :: next\_hp, elem :: elem\_hp, p :: ref

→ Pointer access:  $p \rightarrow \text{next} = \text{next} (\text{the\_addr } p)$

→ Pointer update:  $p \rightarrow \text{next} ::= v = \text{next} ::= \text{next} ((\text{the\_addr } p) := v)$

**In general:**

→ a separate heap for each struct field

→ buys you  $p \rightarrow \text{next} \neq p \rightarrow \text{elem}$  automatically (aliasing)

→ still assumes type safe language

# DEMO

## We have seen today ...

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- Weakest precondition
- Verification conditions
- Example program proofs
- Arrays, pointers