



COMP 4161
NICTA Advanced Course

Advanced Topics in Software Verification

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C

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Last Time

- Weakest preconditions
- Verification conditions
- Arrays, pointers
- Hard part: finding invariants

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Content

- Intro & motivation, getting started [1]
- Foundations & Principles
 - Lambda Calculus, natural deduction [1,2]
 - Higher Order Logic [3]
 - Term rewriting [4^a]
- Proof & Specification Techniques
 - Inductively defined sets, rule induction [5]
 - Datatypes, recursion, induction [6, 7]
 - Automated proof and disproof [7]
 - Hoare logic, proofs about programs, refinement [8^b,9^c,10]
 - Isar, locales [11^d,12]

^aa1 due; ^ba2 due; ^csession break; ^da3 due

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Program Verification

So far:

- have verified functional programs written in HOL
- learned about verifying imperative programs with Hoare Logic

Next few lectures:

- real C programs

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Main new problems in verifying C programs:

- expressions with side effects
- more control flow (do/while, for, break, continue, return)
- local variables and blocks
- functions & procedures
- concrete C data types
- C memory model and C pointers

C is not a nice language for reasoning.

Things are going to get ugly.

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Approach



Approach for verifying C programs:

Translate into existing, clean imperative language in Isabelle.

Simpl:

- generic imperative language by Norbert Schirmer, TU Munich
- state space and basic expressions/statements can be instantiated
- has operational semantics
- Hoare logic with soundness and completeness proof
- automated vcg
- available from the Archive of Formal Proofs <http://afp.sf.net>

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Commands in Simpl



```
type_synonym 's bexp = "'s set"
```

```
datatype ('s, 'p, 'f) com =
  Skip
| Basic "'s => 's"
| Spec "'s * 's) set"
| Seq "'s, 'p, 'f) com" "'s, 'p, 'f) com"
| Cond "'s bexp" "'s, 'p, 'f) com" "'s, 'p, 'f) com"
| While "'s bexp" "'s, 'p, 'f) com"
| Call 'p
| DynCom "'s => ('s, 'p, 'f) com"
| Guard 'f "'s bexp" "'s, 'p, 'f) com"
| Throw
| Catch "'s, 'p, 'f) com" "'s, 'p, 'f) com"
```

's = state, 'p = procedure names, 'f = faults

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DEMO: SIMPL



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Plan



Almost all of C can be translated into Simpl.

This is the plan for today.

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Expressions with side effects



```
a = a * b;   x = f(h);   i = ++i - i++;   x = f(h) + g(x);
```

→ `a = a * b` — Fine: easy to translate into Isabelle

→ `x = f(h)` — Fine: may have side effects, but can be translated sanely.

→ `i = ++i - i++` — Seriously? What does that even mean?

Make this an error, force programmer to write instead:

```
i0 = i; i++; i = i - i0; (or just i = 1)
```

→ `x = f(h) + g(x)` — Ok if `g` and `h` do not have any side effects

⇒ Prove all functions in expressions are side-effect free

Alternative: explicitly model nondeterministic order of execution in expressions.

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Control flow



```
do { c } while (condition);
```

Already can treat normal while-loops! Automatically translate into:

```
c; while (condition) { c }
```

Similarly:

```
for (init; condition; increment) { c }
```

becomes

```
init; while (condition) { c; increment; }
```

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More control flow: break/continue



```
while (condition) {  
    foo;  
    if (Q) continue;  
    bar;  
    if (P) break;  
}
```

Non-local control flow: `continue` goes to condition, `break` goes to end.

Can be modelled with exceptions:

→ throw exception `continue`, catch at end of body.

→ throw exception `break`, catch after loop.

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Exceptions



Do not exist in C, but can be used to model C constructs.

Exceptions can be modelled with two kinds of state:

- **normal** states as before
- **abrupt** states — an exception was raised, normal commands are skipped.

Simpl commands:

- **throw**: switch to abrupt state
- **try { c1 } catch { c2 }**:
if c1 terminates abruptly, execute c2, otherwise execute only c1.

Use state to store which exception was thrown.

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Break/continue



Break/continue example becomes:

```
try {
  while (condition) {
    try {
      foo;
      if (Q) { exception = 'continue'; throw; }
      bar;
      if (P) { exception = 'break'; throw; }
    } catch { if (exception == 'continue') SKIP else throw; }
  }
} catch { if (exception == 'break') SKIP else throw; }
```

This is not C any more. But it models C behaviour!

Need to be careful that only the translation has access to exception state.

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Return



```
if (P) return x;
foo;
return y;
```

Similar non-local control flow. **Similar solution**: use throw/try/catch

```
try {
  if (P) { return_val = x; exception = 'return'; throw; }
  foo;
  return_val = y; exception = 'return'; throw;
} catch {
  SKIP
}
```

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Hoare Rules for Exceptions



Need new kind of Hoare triples to model normal and abrupt state:

$$\{P\} f \{Q, \{E\}$$

If P holds initially, and

- f terminates in state Normal s , then Q s ;
- f terminates in state Abrupt s , then E s

Hoare Rules:

$$\frac{\{Q\} \text{throw } \{P\}, \{Q\}}{\{P\} \text{try } c_1 \text{ catch } c_2 \{Q\}, \{E\}} \quad \frac{\{P\} c_1 \{Q\}, \{R\} \quad \{R\} c_2 \{Q\}, \{E\}}{\{P\} \text{try } c_1 \text{ catch } c_2 \{Q\}, \{E\}}$$

$$\frac{\{P\} c_1 \{R\}, \{E\} \quad \{R\} c_2 \{Q\}, \{E\}}{\{P\} c_1; c_2 \{Q\}, \{E\}}$$

(the other rules analogous)

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DEMO: CONTROL FLOW

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Procedures in Simpl

Simpl com datatype

- has Call command
- but no procedure declaration
- and no local variables or parameters!

They can be simulated.

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Operational Semantics of Simpl

(types s, p, f as before, Semantic.thy)

datatype xstate = Normal s | Abrupt s | Fault f | Stuck

type_synonym procs = $p \Rightarrow \text{com option}$

inductive exec :: procs \Rightarrow com \Rightarrow xstate \Rightarrow xstate \Rightarrow bool

$\Gamma \vdash (\text{Skip}, \text{Normal } s) \Rightarrow \text{Normal } s$

$\Gamma \vdash (\text{Throw}, \text{Normal } s) \Rightarrow \text{Abrupt } s$

...

$\llbracket \Gamma p = \text{Some } c; \Gamma \vdash (c, \text{Normal } s) \Rightarrow s' \rrbracket \Longrightarrow \Gamma \vdash (\text{Call } p, \text{Normal } s) \Rightarrow s'$

$\Gamma p = \text{None} \Longrightarrow \Gamma \vdash (\text{Call } p, \text{Normal } s) \Rightarrow \text{Stuck}$

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Formal procedure parameters and local variables

Simpl only has one global state space.

Basic idea:

- separate all locals and all globals
- keep both in one state space record
- on procedure entry, set formal parameters to actual values
- on procedure exit, restore previous values of all locals

Implemented using DynCom:

call init body restore result =

DynCom ($\lambda s.$ init; body; DynCom ($\lambda t.$ restore s t; result t))

Example: for procedure $f(x) = \{ r = x + 2 \}$

$y = \text{CALL } f(7) \equiv \text{call } (x = 7) (r = x + 2) (\lambda s t. s (| \text{globals} := \text{globals } t |)) (\lambda t. y = r t)$

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Verifying Procedures



Simple idea: replace/inline body. Does not work for recursion.

Instead:

- introduce assumed specifications for procedures
- outside call: no specification known, user provided
- but: can assume current specification for recursive call
- works like induction
- is proved by induction on the recursive call depth

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DEMO: PROCEDURES

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We have seen today ...



- C control flow
- Exceptions with Hoare logic rules
- C functions and procedures with Hoare logic rules

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