COMP 4161
NICTA Advanced Course

Advanced Topics in Software Verification

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$$\{P\} \ldots \{Q\}$$

Slide 1

Last Time

- ➜ Syntax of a simple imperative language
- ➜ Operational semantics
- ➜ Program proof on operational semantics
- ➜ Hoare logic rules
- ➜ Soundness of Hoare logic

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Content

- ➜ Intro & motivation, getting started [1]
- ➜ Foundations & Principles
  - Lambda Calculus, natural deduction [1,2]
  - Higher Order Logic [3[a]]
  - Term rewriting [4]
- ➜ Proof & Specification Techniques
  - Isar [5]
  - Inductively defined sets, rule induction [6[b]]
  - Datatypes, recursion, induction [7[c], 8]
  - Calculational reasoning, code generation [9]
  - Hoare logic, proofs about programs [10[d],11,12]

[a] a1 due; [b] a2 due; [c] session break; [d] a3 due

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Automation?

Last time: Hoare rule application is nicer than using operational semantic.

BUT:

- ➜ it's still kind of tedious
- ➜ it seems boring & mechanical

Automation?

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Invariant

Problem: While – need creativity to find right (invariant) P

Solution:

- ➜ annotate program with invariants
- ➜ then, Hoare rules can be applied automatically

Example:

$\{M = 0 \wedge N = 0\}$
WHILE $M \neq a$ INV $\{N = M * b\}$ DO $N := N + b; M := M + 1$ OD
$\{N = a * b\}$

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Weakest Preconditions

pre $c\ Q$ **= weakest** P **such that** $\{P\}\ c\ \{Q\}$

With annotated invariants, easy to get:

pre SKIP Q	$=$	Q
pre $(x := a)\ Q$	$=$	$\lambda\sigma.\ Q(\sigma(x := a\sigma))$
pre $(c_1; c_2)\ Q$	$=$	pre c_1 (pre $c_2\ Q$)
pre (IF b THEN c_1 ELSE c_2) Q	$=$	$\lambda\sigma.\ (b \longrightarrow$ pre $c_1\ Q\ \sigma) \wedge$ $(\neg b \longrightarrow$ pre $c_2\ Q\ \sigma)$
pre (WHILE b INV I DO c OD) Q	$=$	I

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Verification Conditions

$\{\text{pre}\ c\ Q\}\ c\ \{Q\}$ **only true under certain conditions**

These are called **verification conditions** vc $c\ Q$:

vc SKIP Q	$=$	True
vc $(x := a)\ Q$	$=$	True
vc $(c_1; c_2)\ Q$	$=$	vc $c_2\ Q \wedge$ (vc c_1 (pre $c_2\ Q$))
vc (IF b THEN c_1 ELSE c_2) Q	$=$	vc $c_1\ Q \wedge$ vc $c_2\ Q$
vc (WHILE b INV I DO c OD) Q	$=$	$(\forall\sigma.\ I\sigma \wedge b\sigma \longrightarrow$ pre $c\ I\ \sigma) \wedge$ $(\forall\sigma.\ I\sigma \wedge \neg b\sigma \longrightarrow Q\ \sigma) \wedge$ vc $c\ I$

$$\text{vc}\ c\ Q \wedge (P \Longrightarrow \text{pre}\ c\ Q) \Longrightarrow \{P\}\ c\ \{Q\}$$

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Syntax Tricks

- ➜ $x := \lambda\sigma.\ 1$ instead of $x := 1$ sucks
- ➜ $\{\lambda\sigma.\ \sigma\ x = n\}$ instead of $\{x = n\}$ sucks as well

Problem: program variables are functions, not values

Solution: distinguish program variables syntactically

Choices:

- ➜ declare program variables with each Hoare triple
  - nice, usual syntax
  - works well if you state full program and only use vcg
- ➜ separate program variables from Hoare triple (use extensible records), indicate usage as function syntactically
  - more syntactic overhead
  - program pieces compose nicely

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Records in Isabelle

Records are a tuples with named components

Example:

record A = a :: nat
b :: int

- Selectors: a :: A ⇒ nat, b :: A ⇒ int, a r = Suc 0
- Constructors: ⦇ a = Suc 0, b = −1 ⦈
- Update: r⦇ a := Suc 0 ⦈

Records are extensible:

record B = A +
c :: nat list

⦇ a = Suc 0, b = −1, c = [0, 0] ⦈

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Arrays

Depending on language, model arrays as functions:

- Array access = function application:
  a[i] = a i
- Array update = function update:
  a[i] :== v = a :== a(i:= v)

Use lists to express length:

- Array access = nth:
  a[i] = a ! i
- Array update = list update:
  a[i] :== v = a :== a[i:= v]
- Array length = list length:
  a.length = length a

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Pointers

Choice 1

datatype ref = Ref int | Null
types heap = int ⇒ val
datatype val = Int int | Bool bool | Struct_x int int bool | . . .

- hp :: heap, p :: ref
- Pointer access: *p = the_Int (hp (the_addr p))
- Pointer update: *p :== v = hp :== hp ((the_addr p) := v)

- a bit klunky
- gets even worse with structs
- lots of value extraction (the_Int) in spec and program

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Pointers

Choice 2 (Burstall '72, Bornat '00)

struct with next pointer and element

datatype ref = Ref int | Null
types next_hp = int ⇒ ref
types elem_hp = int ⇒ int

- next :: next_hp, elem :: elem_hp, p :: ref
- Pointer access: p→next = next (the_addr p)
- Pointer update: p→next :== v = next :== next ((the_addr p) := v)

- a separate heap for each struct field
- buys you p→next ≠ p→elem automatically (aliasing)
- still assumes type safe language

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DEMO

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We have seen today ...

- Weakest precondition
- Verification conditions
- Example program proofs
- Arrays, pointers

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