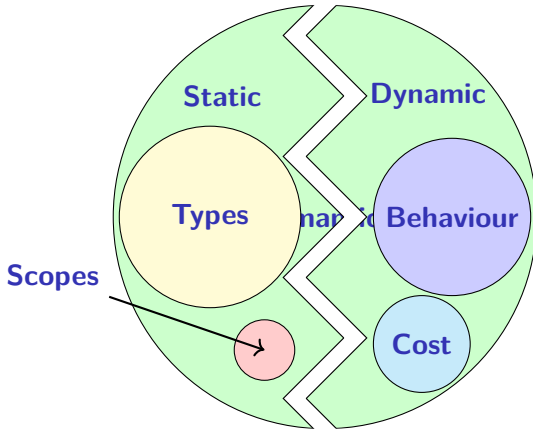


## Semantics

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Term 3 2025

# Semantics

*σημαντικως*



# Static Semantics

## Definition

The *static semantics* of a program is those significant aspects of the meaning of  $P$  that can be determined by the compiler (or an external lint tool) **without running the program**.

Recall our language of arithmetic expressions and let-bindings. What properties might we derive **statically** about those terms? The only thing we can check is that the program is **well-scoped** (assuming FOAS).

# Scope-Checking

$$\begin{array}{c}
 \frac{}{\Gamma \vdash (\text{Num } n) \text{ ok}} \quad \frac{\Gamma \vdash e_1 \text{ ok} \quad \Gamma \vdash e_2 \text{ ok}}{\Gamma \vdash (\text{Times } e_1 e_2) \text{ ok}} \quad \frac{\Gamma \vdash e_1 \text{ ok} \quad \Gamma \vdash e_2 \text{ ok}}{\Gamma \vdash (\text{Plus } e_1 e_2) \text{ ok}} \\
 \frac{(x \text{ bound}) \in \Gamma}{\Gamma \vdash (\text{Var } x) \text{ ok}} \quad \frac{\Gamma \vdash e_1 \text{ ok} \quad x \text{ bound}, \Gamma \vdash e_2 \text{ ok}}{\Gamma \vdash (\text{Let } x e_1 e_2) \text{ ok}}
 \end{array}$$

## Key Idea

We keep a *context*  $\Gamma$ , a set of assumptions, on the LHS of our judgement, indicating what is required in order for  $e$  to be *well-scoped*.

This could be read as **hypothetical derivations** for the judgement  $e$  **ok** or as a **binary judgement**  $\Gamma \vdash e$  **ok**; whichever you prefer.

## Scope-Checking Example

$$\begin{array}{c}
 \frac{}{\Gamma \vdash (\text{Num } n) \text{ ok}} \quad \frac{\Gamma \vdash e_1 \text{ ok} \quad \Gamma \vdash e_2 \text{ ok}}{\Gamma \vdash (\text{Times } e_1 e_2) \text{ ok}} \quad \frac{\Gamma \vdash e_1 \text{ ok} \quad \Gamma \vdash e_2 \text{ ok}}{\Gamma \vdash (\text{Plus } e_1 e_2) \text{ ok}} \\
 \frac{(x \text{ bound}) \in \Gamma}{\Gamma \vdash (\text{Var } x) \text{ ok}} \quad \frac{\Gamma \vdash e_1 \text{ ok} \quad x \text{ bound}, \Gamma \vdash e_2 \text{ ok}}{\Gamma \vdash (\text{Let } x e_1 e_2) \text{ ok}} \\
 \\
 \frac{}{\vdash (\text{Num } 3)} \quad \frac{\frac{}{\text{"x"} \vdash (\text{Num } 4)}{\text{"x"} \vdash (\text{Let "y" (Num 4) (Plus (Var "x") (Var "y")))} \quad \frac{\frac{}{\text{"y"}, \text{"x"} \vdash (\text{Var "x"})} \quad \frac{}{\text{"y"}, \text{"x"} \vdash (\text{Var "y"})}}{\text{"y"}, \text{"x"} \vdash (\text{Plus (Var "x") (Var "y")})}}{\vdash (\text{Let "x" (Num 3) (Let "y" (Num 4) (Plus (Var "x") (Var "y"))))}
 \end{array}$$

# Dynamic Semantics

Dynamic Semantics can be specified in many ways:

- 1 *Denotational Semantics* is the *compositional* construction of a *mathematical object* for each form of *syntax*. [COMP6752](#) (briefly)
- 2 *Axiomatic Semantics* is the construction of a *proof calculus* to allow correctness of a program to be verified. [COMP2111](#), [COMP6721](#), [COMP4161](#)
- 3 *Operational Semantics* is the construction of a program-evaluating *state machine* or *transition system*.

## In this course

We focus mostly on *operational semantics*. We will use *axiomatic semantics* (Hoare Logic) briefly in the imperative programming topic. *Denotational semantics* are mostly an extension topic, except for the very next slide.

## Denotational Semantics

$$\llbracket \cdot \rrbracket : \mathbf{AST} \rightarrow (\mathbf{Var} \rightarrow \mathbb{Z}) \rightarrow \mathbb{Z}$$

Our **denotation** for arithmetic expressions is functions from **environments** (mapping from variables to their values) to values.

$$\begin{aligned}\llbracket \text{Num } n \rrbracket &= \lambda E. n \\ \llbracket \text{Var } x \rrbracket &= \lambda E. E(x) \\ \llbracket \text{Plus } e_1 \ e_2 \rrbracket &= \lambda E. \llbracket e_1 \rrbracket E + \llbracket e_2 \rrbracket E \\ \llbracket \text{Times } e_1 \ e_2 \rrbracket &= \lambda E. \llbracket e_1 \rrbracket E \times \llbracket e_2 \rrbracket E \\ \llbracket \text{Let } x \ e_1 \ e_2 \rrbracket &= \lambda E. \llbracket e_2 \rrbracket (E[x := \llbracket e_1 \rrbracket E])\end{aligned}$$

Where  $E[x := n]$  is a new environment just like  $E$ , except the variable  $x$  now maps to  $n$ .

## Aside: The Problem of $\infty$

Note programming-language type and the denotational type of a program can't be the same because of non-termination.

```
find_root_2 :: Integer → Integer
find_root_2 i = if (i × i) == 2
  then i
  else find_root_2 (i + 1)
```

# Operational Semantics

There are two main kinds of operational semantics.

## Small Step

- Also called *structural operational semantics (SOS)*.
- A judgement that specifies transitions between *states*:

$$e \mapsto e'$$



## Big Step

- Also called *natural* or *evaluation* semantics.
- One big judgement relating expressions to their values:

$$e \Downarrow v$$

# Big-Step Semantics

We need:

- A set of **evaluable expressions**  $E$
- A set of **values**  $V$
- A relation  $\Downarrow \subseteq E \times V$

## Example (Arithmetic Expressions)

$E$  is the set of all closed expressions  $\{e \mid e \text{ ok}\}$ .  $V$  is the set of integers  $\mathbb{Z}$ .

$$\frac{}{(\text{Num } n) \Downarrow n} \quad \frac{e_1 \Downarrow v_1 \quad e_2[x := (\text{Num } v_1)] \Downarrow v_2}{(\text{Let } e_1 (x. e_2)) \Downarrow v_2}$$

$$\frac{e_1 \Downarrow v_1 \quad e_2 \Downarrow v_2}{(\text{Plus } e_1 e_2) \Downarrow (v_1 + v_2)} \quad \frac{e_1 \Downarrow v_1 \quad e_2 \Downarrow v_2}{(\text{Times } e_1 e_2) \Downarrow (v_1 \times v_2)}$$

**To Code** Let's do it in Haskell!

## Evaluation Strategies

$$\frac{e_1 \Downarrow v_1 \quad e_2[x := (\text{Num } v_1)] \Downarrow v_2}{(\text{Let } e_1 (x. e_2)) \Downarrow v_2}$$

Any other ways to evaluate Let?

The above is called *call-by-value* or *strict* evaluation. Below we have *call-by-name*:

$$\frac{e_2[x := e_1] \Downarrow v_2}{(\text{Let } e_1 (x. e_2)) \Downarrow v_2}$$

This can be computationally very expensive, for example:

`let x = <very expensive computation> in x + x + x + x`

In *confluent* languages like this or  $\lambda$ -calculus, this only matters for performance. In other languages, this is not so. *Why?*

Haskell uses *call-by-need* or *lazy* evaluation, which optimises cases like this.

## Small Step Semantics

For small step semantics, we need:

- A set of **states**  $\Sigma$
- A set of **initial states**  $I \subseteq \Sigma$
- A set of **final states**  $F \subseteq \Sigma$
- A relation  $\mapsto \subseteq \Sigma \times \Sigma$ , which specifies only “one step” of the execution.

An **execution** or **trace**  $\sigma_1 \mapsto \sigma_2 \mapsto \sigma_3 \mapsto \dots \mapsto \sigma_n$  is called **maximal** if there exists no  $\sigma_{n+1}$  such that  $\sigma_n \mapsto \sigma_{n+1}$ ; and is called **complete** if it is maximal and  $\sigma_n \in F$ .

# Example

## Example (Arithmetic Expressions)

$\Sigma$  and  $I$  are the set of all closed expressions  $\{e \mid e \text{ ok}\}$ ,  $F$  is the set of evaluated expressions  $\{(\text{Num } n) \mid n \in \mathbb{Z}\}$ .

$$\frac{e_1 \mapsto e'_1}{(\text{Plus } e_1 \ e_2) \mapsto (\text{Plus } e'_1 \ e_2)} \quad \frac{e_2 \mapsto e'_2}{(\text{Plus } (\text{Num } n) \ e_2) \mapsto (\text{Plus } (\text{Num } n) \ e'_2)}$$

$$\frac{}{(\text{Plus } (\text{Num } n) \ (\text{Num } m)) \mapsto (\text{Num } (n + m))}$$

(Similarly for Times)

$$\frac{e_1 \mapsto e'_1}{(\text{Let } e_1 \ (x. \ e_2)) \mapsto (\text{Let } e'_1 \ (x. \ e_2))}$$

$$\frac{}{(\text{Let } (\text{Num } n) \ (x. \ e_2)) \mapsto e_2[x := \text{Num } n]}$$

**To Code** Let's do it in Haskell!

## ∞ in Small-Step and Big-Step

Where does the problem of non-termination go in small-step style and big-step style?

Small step: from some starting state  $\sigma_1$  we have an infinite trace  $\sigma_2, \sigma_3 \dots$  of small steps. No finite subtrace is *maximal*.

Big step: for some  $e$ , the judgement  $e \Downarrow v$  is false for every  $v$ .

# Equivalence

## Comparing small step and big step

Small step semantics are **lower-level**, they clearly specify the **order of evaluation**. Big step semantics give us a **result** without telling us explicitly **how it was computed**.

Having specified the dynamic semantics in these two ways, it becomes desirable to show they are **equivalent**, that is:

*If there exists a trace  $e \mapsto \dots \mapsto (\text{Num } n)$ , then  $e \Downarrow n$ , and vice versa.*

We will need to define some notation to remove those blasted **magic dots**.

# Notation

Let  $\mapsto^*$  be the *reflexive, transitive closure* of  $\mapsto$ .

$$\frac{}{e \mapsto^* e} \quad \frac{e_1 \mapsto e_2 \quad e_2 \mapsto^* e_n}{e_1 \mapsto^* e_n}$$

We can now state our property formally as:

$$e \mapsto^* (\text{Num } n) \iff e \Downarrow n$$

## Doing the Proof

The proof will be done on the “board”, with typeset versions uploaded later.

The big-step to small-step direction can be proven by reasonably straightforward rule induction:

$$\frac{e \Downarrow n}{e \mapsto^* (\text{Num } n)}$$

The other direction requires the lemma:

$$\frac{e \mapsto e' \quad e' \Downarrow n}{e \Downarrow n}$$

The abridged proof is presented in this lecture, with all cases left for the course website.

## Big and small (eliding some small-step rules)

$$\begin{array}{c}
 \frac{e_1 \mapsto e'_1}{(\text{Plus } e_1 \ e_2) \mapsto (\text{Plus } e'_1 \ e_2)} \quad \frac{e_2 \mapsto e'_2}{(\text{Plus } (\text{Num } n) \ e_2) \mapsto (\text{Plus } (\text{Num } n) \ e'_2)} \\
 \\
 \frac{}{(\text{Plus } (\text{Num } n) \ (\text{Num } m)) \mapsto (\text{Num } (n + m))} \\
 \\
 \frac{e_1 \mapsto e'_1}{(\text{Let } e_1 \ (x. \ e_2)) \mapsto (\text{Let } e'_1 \ (x. \ e_2))} \\
 \\
 \frac{}{(\text{Let } (\text{Num } n) \ (x. \ e_2)) \mapsto e_2[x := \text{Num } n]} \\
 \\
 \frac{}{(\text{Num } n) \Downarrow n} \quad \frac{e_1 \Downarrow v_1 \quad e_2[x := (\text{Num } v_1)] \Downarrow v_2}{(\text{Let } e_1 \ (x. \ e_2)) \Downarrow v_2} \\
 \\
 \frac{e_1 \Downarrow v_1 \quad e_2 \Downarrow v_2}{(\text{Plus } e_1 \ e_2) \Downarrow (v_1 + v_2)} \quad \frac{e_1 \Downarrow v_1 \quad e_2 \Downarrow v_2}{(\text{Times } e_1 \ e_2) \Downarrow (v_1 \times v_2)}
 \end{array}$$