

COMP2521 24T3

Graphs (VII)

Minimum Spanning Trees

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minimum spanning trees
kruskal's algorithm
prim's algorithm

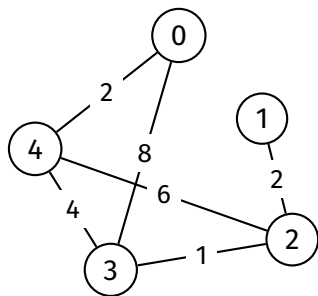
A **spanning tree** of an undirected graph G is a subgraph of G that contains all vertices of G , that is connected and contains no cycles

A **minimum spanning tree** of an undirected weighted graph G is a spanning tree of G that has minimum total edge weight among all spanning trees of G

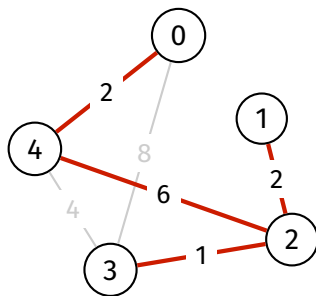
Applications:

Electrical grids, networks

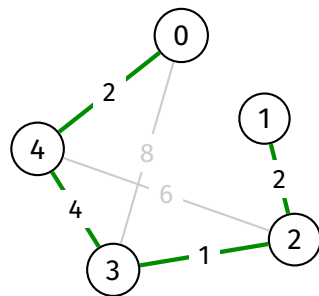
Any situation where we want to connect nodes as cheaply as possible



Original graph



Spanning tree



Minimum spanning tree

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The number of edges in a spanning tree of a graph is always one less than the number of vertices in the graph.

Basic minimum spanning tree algorithms:

- Kruskal's algorithm
- Prim's algorithm

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Invented in 1956 by
American mathematician, statistician, computer scientist
Joseph Kruskal



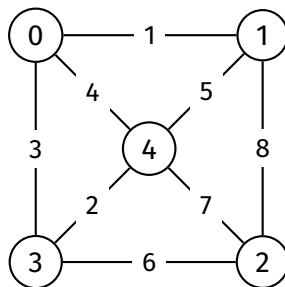
Algorithm:

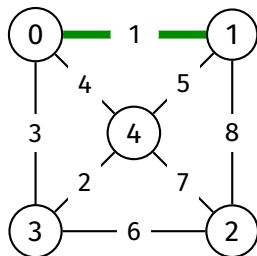
- 1 Start with an empty graph
 - With same vertices as original graph
- 2 Consider edges in increasing weight order
 - Add edge if it does not form a cycle in the MST
- 3 Repeat until $V - 1$ edges have been added

Critical operations:

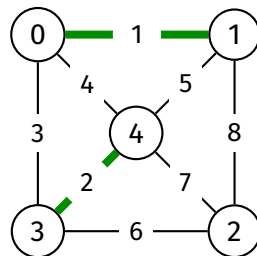
- Iterating over edges in weight order
- Checking if adding an edge would form a cycle

Run Kruskal's algorithm on this graph:

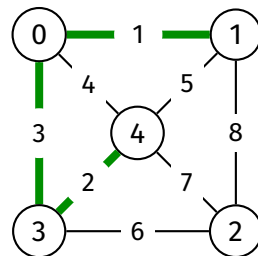




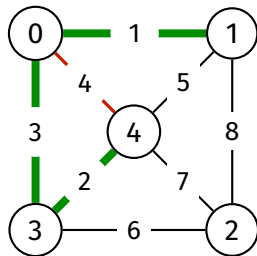
Add 0-1



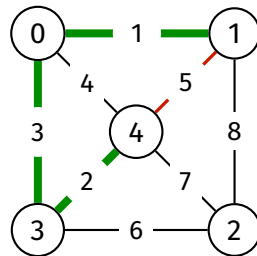
Add 3-4



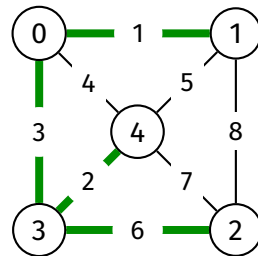
Add 0-3



Don't add 0-4



Don't add 1-4



Add 2-3

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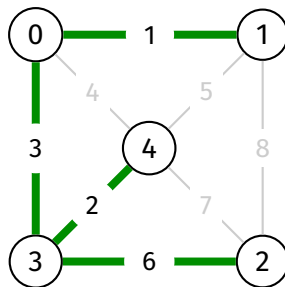
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MST:



```
kruskalMst( $G$ ):
```

```
  Input: graph  $G$  with  $V$  vertices
```

```
  Output: minimum spanning tree of  $G$ 
```

```
  mst = empty graph with  $V$  vertices
```

```
  sortedEdges = sort edges of  $G$  by weight
```

```
  for each edge  $e$  in sortedEdges:
```

```
    add  $e$  to mst
```

```
    if mst has a cycle:
```

```
      remove  $e$  from mst
```

```
  if mst has  $V - 1$  edges:
```

```
    return mst
```

```
kruskalMst( $G$ ):
```

```
  Input: graph  $G$  with  $V$  vertices
```

```
  Output: minimum spanning tree of  $G$ 
```

```
  mst = empty graph with  $V$  vertices
```

```
  sortedEdges = sort edges of  $G$  by weight
```

```
  for each edge  $(v, w, \text{weight})$  in sortedEdges:
```

```
    if there is no path between  $v$  and  $w$  in mst:  
      add edge  $(v, w, \text{weight})$  to mst
```

```
  if mst has  $V - 1$  edges:
```

```
    return mst
```

Proof by exchange argument.

Idea:

- Suppose there exists another algorithm A which makes a different set of choices
 - In this case, chooses a different set of edges for the MST
- Identify *one* choice made by A which is not made by our algorithm
- Show that by exchanging that choice with one of the choices made by our algorithm, the solution does not become worse or less optimal
 - In this case, the “solution” is the spanning tree produced
 - In this case, an “optimal” solution is a spanning tree that costs as little as possible

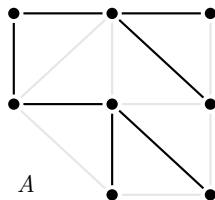
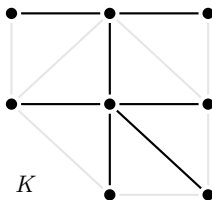
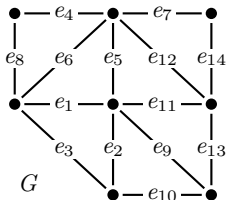
Sort the edges of G in increasing order.

Let K be the set of edges selected by Kruskal's algorithm.
Let A be the set of edges selected by a different algorithm.

edges of G	e_1	e_2	e_3	e_4	e_5	e_6	e_7	e_8	e_9	\dots
edges of K	e_1	e_2		e_4	e_5		e_7		e_9	\dots
edges of A	e_1	e_2		e_4			e_7	e_8	e_9	\dots

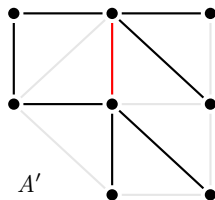
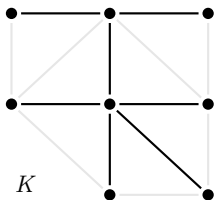
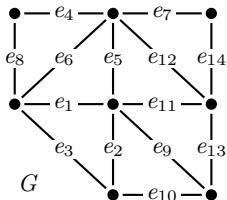
Consider the first edge that is chosen by K but not by A .

edges of G	e_1	e_2	e_3	e_4	e_5	e_6	e_7	e_8	e_9	\dots
edges of K	e_1	e_2		e_4	e_5		e_7		e_9	\dots
edges of A	e_1	e_2		e_4	e_5		e_7	e_8	e_9	\dots



Consider the first edge that is chosen by K but not by A .
Add this edge to a copy of A (call it A'). This forms a cycle in A' .

edges of G	e_1	e_2	e_3	e_4	e_5	e_6	e_7	e_8	e_9	\dots
edges of K	e_1	e_2		e_4	e_5		e_7		e_9	\dots
edges of A'	e_1	e_2		e_4	e_5		e_7	e_8	e_9	\dots

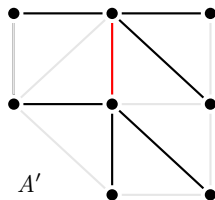
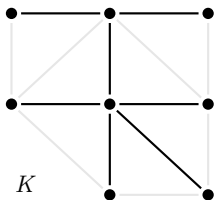
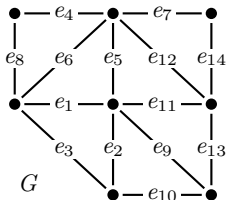


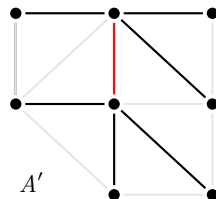
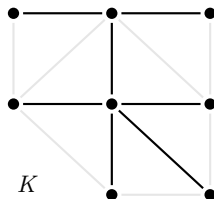
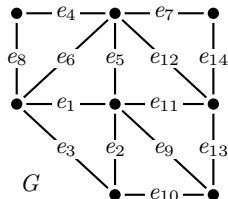
Consider the first edge that is chosen by K but *not* by A .

Add this edge to a copy of A (call it A'). This forms a cycle in A' .

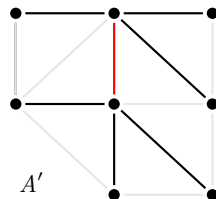
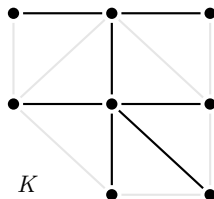
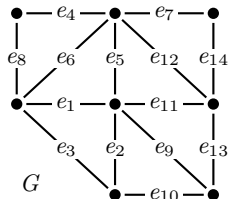
Now find the highest-weight edge in this cycle and *remove* it from A' .

edges of G	e_1	e_2	e_3	e_4	e_5	e_6	e_7	e_8	e_9	\dots
edges of K	e_1	e_2		e_4	e_5		e_7		e_9	\dots
edges of A'	e_1	e_2		e_4	e_5		e_7	e_8	e_9	\dots





Now A' is once again a spanning tree, *but* it is more similar to K than A and it costs no more than A .



Now A' is once again a spanning tree, *but* it is more similar to K than A and it costs no more than A .

Repeat until A' is identical to K . Each time we perform an exchange, the spanning tree does not increase in cost.

Therefore, K is an optimal spanning tree (MST).

Analysis:

- Sorting edges is $O(E \cdot \log E)$
- Main loop has at most E iterations
- Checking if adding an edge would form a cycle
 - There are different ways to implement this
 - Cycle/path checking is $O(V)$ in the worst case (adjacency list)
 \Rightarrow overall cost = $O(E \cdot \log E + E \cdot V) = O(E \cdot V)$
 - Note: The typical cycle checking is $O(V + E)$. But in spanning tree, the max number of edges is $V - 1$. Hence, cycle checking is $O(V)$.
 - Using union-find data structure (Disjoint-Set) is close to $O(1)$ in the worst case
 \Rightarrow overall cost = $O(E \cdot \log E + E) = O(E \cdot \log E) = O(E \cdot \log V)$ (since $E < V^2$)

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Developed by Vojtěch Jarník in 1930
and rediscovered by Robert C. Prim in 1957



Vojtěch Jarník



Robert C. Prim

Algorithm:

- 1 Start with an empty graph
- 2 Start from any vertex, add it to the MST
- 3 Choose cheapest edge $s-t$ such that:
 - s has been added to the MST, and
 - t has not been added to the MSTand add this edge and the vertex t to the MST
- 4 Repeat previous step until $V - 1$ edges have been added
 - Or until all vertices have been added

Critical operations:

- Finding the cheapest edge $s-t$ such that s has been added to the MST and t has not been added to the MST

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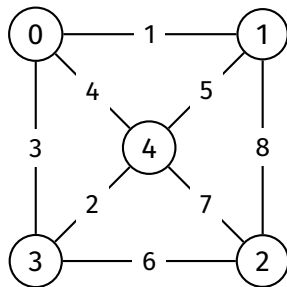
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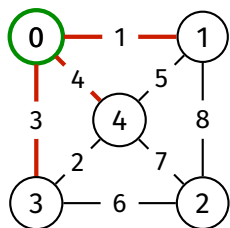
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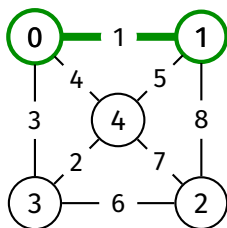
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Run Prim's algorithm on this graph (starting at 0):

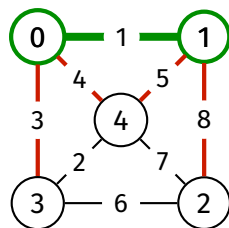




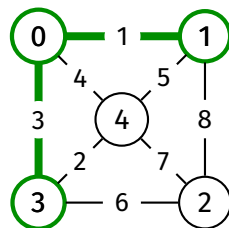
Start of step 1



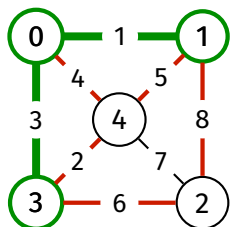
End of step 1



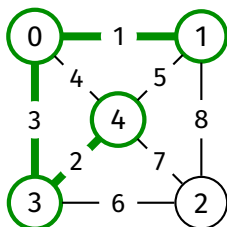
Start of step 2



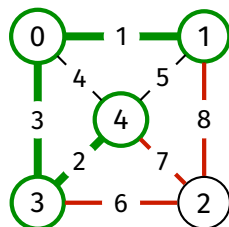
End of step 2



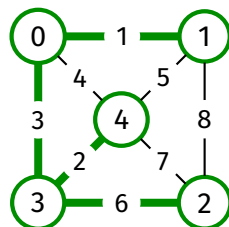
Start of step 3



End of step 3



Start of step 4



End of step 4

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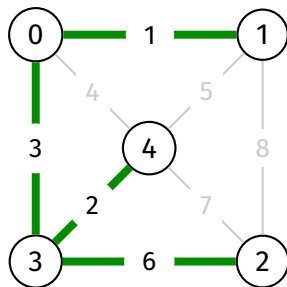
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MST:



```
primMst( $G$ ):
```

```
  Input: graph  $G$  with  $V$  vertices
```

```
  Output: minimum spanning tree of  $G$ 
```

```
  mst = empty graph with  $V$  vertices
```

```
  usedV = {0}
```

```
  unusedE = edges of  $G$ 
```

```
  while |usedV| <  $V$ :
```

```
    find cheapest edge  $e$  ( $s, t, \text{weight}$ ) in unusedE such that  
       $s \in \text{usedV}$  and  $t \notin \text{usedV}$ 
```

```
    add  $e$  to mst
```

```
    add  $t$  to usedV
```

```
    remove  $e$  from unusedE
```

```
  return mst
```

Analysis:

- Algorithm considers at most E edges $\Rightarrow O(E)$
- Loop has V iterations
- In each iteration, finding the minimum-weighted edge:
 - With set of edges is $O(E)$
 \Rightarrow overall cost = $O(E + V \cdot E) = O(V \cdot E)$
 - With Fibonacci heap is $O(\log E) = O(\log V)$
 \Rightarrow overall cost = $O(E + V \cdot \log V)$

Kruskal's algorithm...

- is $O(E \cdot \log V)$
- uses array-based data structures
- performs better on sparse graphs

Prim's algorithm...

- is $O(E + V \cdot \log V)$
- uses complex linked data structures
 - in its most efficient implementation (Fibonacci heap)
- performs better on dense graphs

- Boruvka's algorithm
 - Oldest MST algorithm
 - Start with V separate components
 - Join components using min cost links
 - Continue until only a single component
 - Worst-case time complexity: $O(E \cdot \log V)$
- Karger, Klein and Tarjan
 - Based on Boruvka's algorithm, but non-deterministic
 - Randomly selects subset of edges to consider
 - Time complexity: $O(E)$ on average

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<https://forms.office.com/r/zEqxUXvmLR>



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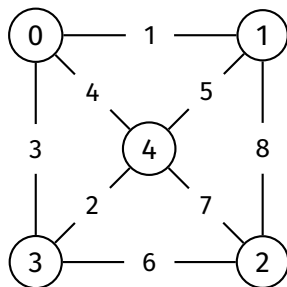
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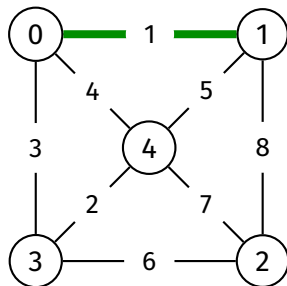
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Adding 0-1 would not create a cycle



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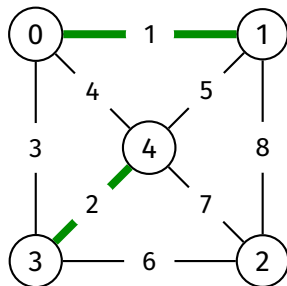
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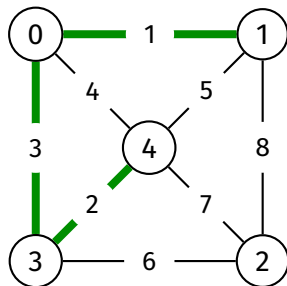
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Adding 3-4 would not create a cycle



Adding 0-3 would not create a cycle



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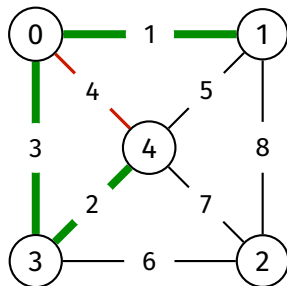
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Adding 0-4 would create a cycle



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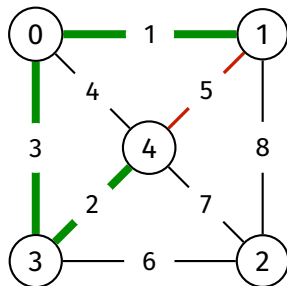
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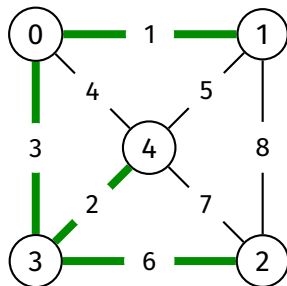
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Adding 1-4 would create a cycle



Adding 2-3 would not create a cycle



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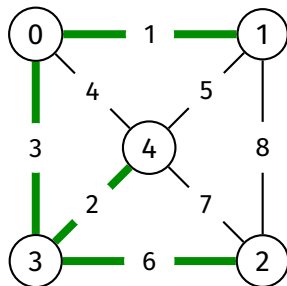
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Done - MST has 4 edges



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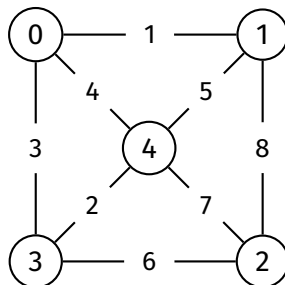
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Original graph



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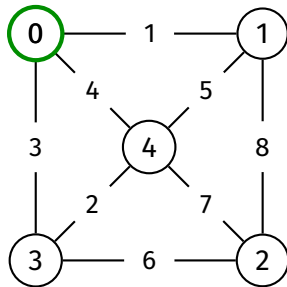
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Start at vertex 0



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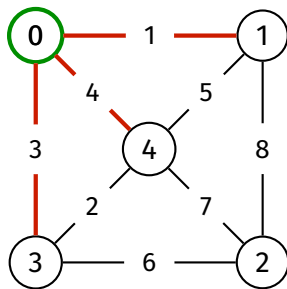
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Choose cheapest edge out of these (in red)



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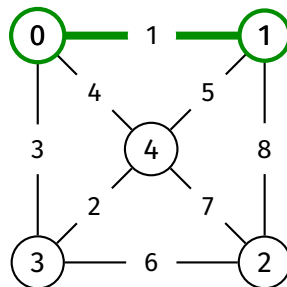
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Add 0-1 to MST



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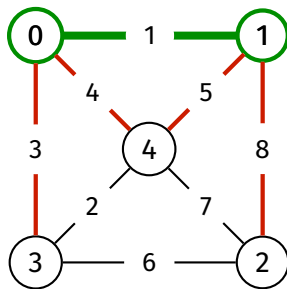
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Choose cheapest edge out of these (in red)



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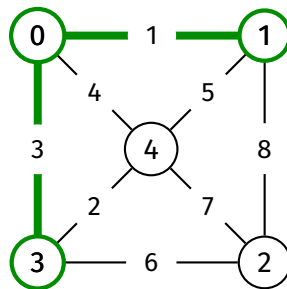
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Add 0-3 to MST



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Algorithm

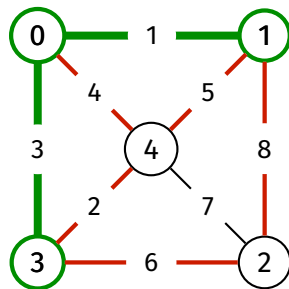
Comparison

Other
Algorithms

Appendix

Kruskal's Algorithm
ExamplePrim's Algorithm
Example

Choose cheapest edge out of these (in red)



Minimum
Spanning
Trees

Kruskal's
Algorithm

Prim's
Algorithm

Comparison

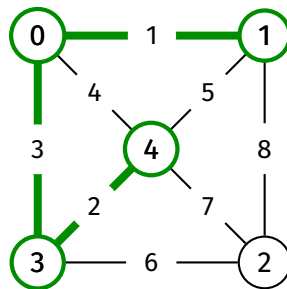
Other
Algorithms

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Example

Add 3-4 to MST



Minimum
Spanning
TreesKruskal's
AlgorithmPrim's
Algorithm

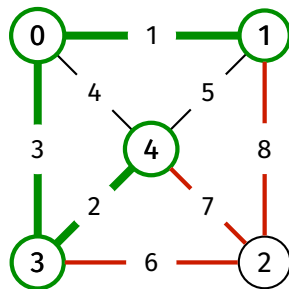
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Example

Choose cheapest edge out of these (in red)



Minimum
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Trees

Kruskal's
Algorithm

Prim's
Algorithm

Comparison

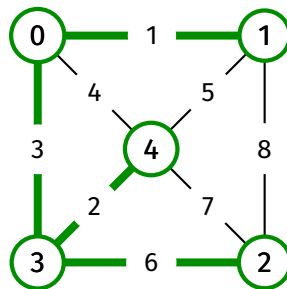
Other
Algorithms

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Kruskal's Algorithm
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Prim's Algorithm
Example

Add 3-2 to MST



Done - MST has 4 edges

