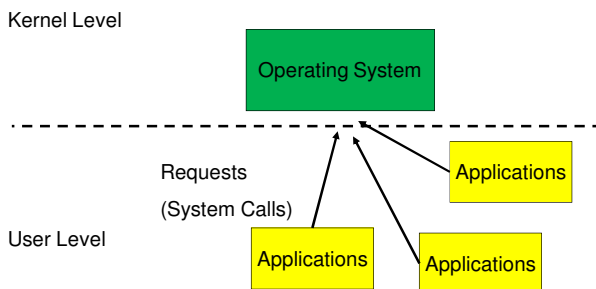


System Calls

Learning Outcomes

- A high-level understanding of System Calls
 - Mostly from the user's perspective
 - From textbook (section 1.6)
- Exposure architectural details of the MIPS R3000
 - Detailed understanding of the of exception handling mechanism
 - From "Hardware Guide" on class web site
- Understanding of the existence of compiler function calling conventions
 - Including details of the MIPS 'C' compiler calling convention
- Understanding of how the application kernel boundary is crossed with system calls in general
 - Including an appreciation of the relationship between a case study (OS/161 system call handling) and the general case.

Operating System System Calls



System Calls

- Can be viewed as special function calls
 - Provides for a controlled entry into the kernel
 - While in kernel, they perform a privileged operation
 - Returns to original caller with the result
- The system call interface represents the abstract machine provided by the operating system.

A Brief Overview of Classes System Calls

- From the user's perspective
 - Process Management
 - File I/O
 - Directories management
 - Some other selected Calls
 - There are many more
 - On Linux, see `man syscalls` for a list

Some System Calls For Process Management

Process management	
Call	Description
<code>pid = fork()</code>	Create a child process identical to the parent
<code>pid = waitpid(pid, &statloc, options)</code>	Wait for a child to terminate
<code>s = execve(name, argv, envp)</code>	Replace a process' core image
<code>exit(status)</code>	Terminate process execution and return status

Some System Calls For File Management

Call	Description
<code>fd = open(file, how, ...)</code>	Open a file for reading, writing or both
<code>s = close(fd)</code>	Close an open file
<code>n = read(fd, buffer, nbytes)</code>	Read data from a file into a buffer
<code>n = write(fd, buffer, nbytes)</code>	Write data from a buffer into a file
<code>position = lseek(fd, offset, whence)</code>	Move the file pointer
<code>s = stat(name, &buf)</code>	Get a file's status information

Some System Calls For Directory Management

Call	Description
<code>s = mkdir(name, mode)</code>	Create a new directory
<code>s = rmdir(name)</code>	Remove an empty directory
<code>int = opendir(path, mode)</code>	Open a directory stream
<code>int = readdir(DIR)</code>	Read an entry from a directory stream
<code>int = closedir(DIR)</code>	Close a directory stream
<code>int = scandir(path, dirent)</code>	Scan a file system
<code>int = readdir_r(DIR, dirent, dirent)</code>	Read an entry from a directory stream

Some System Calls For Miscellaneous Tasks

Call	Description
<code>int = chdir(path)</code>	Change the working directory
<code>int = chmod(path, mode)</code>	Change a file's protection bits
<code>int = kill(pid, signal)</code>	Send a signal to a process
<code>int = time(NULL)</code>	Get the current time since Jan. 1, 1970

System Calls

- A stripped down shell:

```

while (TRUE) {
    type_prompt( );          /* repeat forever */
    read_command (command, parameters) /* display prompt */
                                /* input from terminal */

    if (fork() != 0) {      /* fork off child process */
        /* Parent code */
        waitpid(-1, &status, 0); /* wait for child to exit */
    } else {
        /* Child code */
        execve (command, parameters, 0); /* execute command */
    }
}
    
```

System Calls

UNIX	Win32	UNIX description
fork	CreateProcess	Create a new process
waitpid	WaitForSingleObject	Can wait for a process to exit
execve	exe	Execute process = fork + exe
exit	_Exit	Terminate execution
open	CreateFile	Creates a file or opens an existing file
close	CloseHandle	Close a file
read	ReadFile	Read data from a file
write	WriteFile	Write data to a file
lseek	SetFilePointer	Move the file pointer
stat	GetFileAttributes	Get system file attributes
mkdir	mkdir	Create a new directory
rmdir	RemoveDirectory	Remove an empty directory
readdir	FindFirstFile	Return first directory entry
readdir_r	FindNextFile	Return next directory entry
closedir	FindClose	Close directory handle
chdir	GetCurrentDirectory	Get current working directory
chmod	SetFileAttributes	Set file attributes
kill	TerminateProcess	Terminate process
time	GetSystemTime	Get system time

The MIPS R2000/R3000

- Before looking at system call mechanics in some detail, we need a basic understanding of the MIPS R3000

MIPS R3000

- Load/store architecture
 - No instructions that operate on memory except load and store
 - Simple load/stores to/from memory from/to registers
 - Store word: `sw r4, (r5)`
 - Store contents of r4 in memory using address contained in register r5
 - Load word: `lw r3, (r7)`
 - Load contents of memory into r3 using address contained in r7
 - Delay of one instruction after load before data available in destination register
 - » Must always an instruction between a load from memory and the subsequent use of the register.
 - `lw, sw, lb, sb, lh, sh, ...`

MIPS R3000

- Arithmetic and logical operations are register to register operations
 - E.g., `add r3, r2, r1`
 - No arithmetic operations on memory
- Example
 - `add r3, r2, r1` ⇒ $r3 = r2 + r1$
- Some other instructions
 - `add, sub, and, or, xor, sll, srl`
 - `move r2, r1` ⇒ $r2 = r1$

MIPS R3000

- All instructions are encoded in 32-bit
- Some instructions have *immediate* operands
 - Immediate values are constants encoded in the instruction itself
 - Only 16-bit value
 - Examples
 - Add Immediate: `addi r2, r1, 2048`
 - ⇒ $r2 = r1 + 2048$
 - Load Immediate: `li r2, 1234`
 - ⇒ $r2 = 1234$

Example code

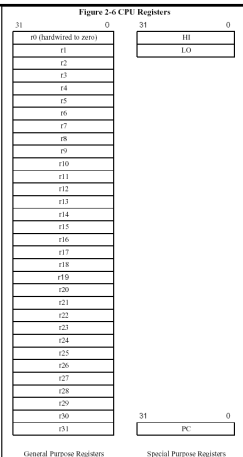
Simple code example: `a = a + 1`

```
lw  r4, 32(r29)    // r29 = stack pointer
li  r5, 1
add r4, r4, r5
sw  r4, 32(r29)
```

Offset(Address)

MIPS Registers

- User-mode accessible registers
 - 32 general purpose registers
 - r0 hardwired to zero
 - r31 the *link* register for jump-and-link (JAL) instruction
 - HI/LO
 - 2 * 32-bits for multiply and divide
 - PC
 - Not directly visible
 - Modified implicitly by jump and branch instructions



Branching and Jumping

- Branching and jumping have a *branch delay slot*
 - The instruction following a branch or jump is always executed prior to destination of jump

```
li  r2, 1
sw  r0, (r3)
j   1f
li  r2, 2
li  r2, 3
1:  sw r2, (r3)
```

MIPS R3000

- RISC architecture – 5 stage pipeline
 - Instruction partially through pipeline prior to jmp having an effect

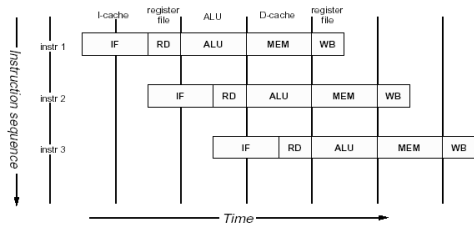
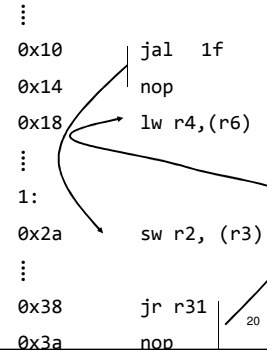


Figure 1.1. MIPS 5-stage pipeline

Jump and Link Instruction

- JAL is used to implement function calls
 - $r31 = PC+8$
- Return Address register (RA) is used to return from function call



Coprocessor 0

- The processor control registers are located in CP0
 - Exception/Interrupt management registers
 - Translation management registers
- CP0 is manipulated using mtc0 (move to) and mfc0 (move from) instructions
 - mtc0/mfc0 are only accessible in kernel mode.

CP0
CP1 (floating point)
PC: 0x0300
HI/LO
R1
↑
Rn

CP0 Registers

- Exception Management
 - c0_cause
 - Cause of the recent exception
 - c0_status
 - Current status of the CPU
 - c0_epc
 - Address of the instruction that caused the exception
 - c0_badvaddr
 - Address accessed that caused the exception
- Miscellaneous
 - c0_prid
 - Processor Identifier
- Memory Management
 - c0_index
 - c0_random
 - c0_entryhi
 - c0_entrylo
 - c0_context
 - More about these later in course

c0_status

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
CU3	CU2	CU1	CU0	0	RE	0	BEV	TS	PE	CM	PZ	SwC	IsC		
15						8	7	6	5	4	3	2	1	0	
IM				0	KUo	IEo	KUp	IEp	KUc	IEc					

Figure 3.2. Fields in status register (SR)

- For practical purposes, you can ignore most bits
 - Green background is the focus

c0_status

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
CU3	CU2	CU1	CU0	0	RE	0	BEV	TS	PE	CM	PZ	SwC	IsC		
15						8	7	6	5	4	3	2	1	0	
IM				0	KUo	IEo	KUp	IEp	KUc	IEc					

Figure 3.2. Fields in status register (SR)

- IM
 - Individual interrupt mask bits
 - 6 external
 - 2 software
- KU
 - 0 = kernel
 - 1 = user mode
- IE
 - 0 = all interrupts masked
 - 1 = interrupts enable
 - Mask determined via IM bits
- c, p, o = current, previous, old

c0_cause

31
30
29
28
27
16
15
8
7
6
2
1
0

BD	0	CE	0	IP	0	ExcCode	0
----	---	----	---	----	---	---------	---

Figure 3.3. Fields in the Cause register

- IP
 - Interrupts pending
 - 8 bits indicating current state of interrupt lines
- CE
 - Coprocessor error
 - Attempt to access disabled Copro.
- BD
 - If set, the instruction that caused the exception was in a branch delay slot
- ExcCode
 - The code number of the exception taken

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Exception Codes

ExcCode Value	Mnemonic	Description
0	Int	Interrupt
1	Mod	"TLB modification"
2	TLBL	"TLB load/TLB store"
3	TLBS	
4	AdEL	Address error (on load/I-fetch or store respectively). Either an attempt to access outside kuseg when in user mode, or an attempt to read a word or half-word at a misaligned address.
5	AdES	

Table 3.2. ExcCode values: different kinds of exceptions

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Exception Codes

ExcCode Value	Mnemonic	Description
6	IBE	Bus error (instruction fetch or data load, respectively). External hardware has signalled an error of some kind; proper exception handling is system-dependent. The R30xx family CPUs can't take a bus error on a store; the write buffer would make such an exception "imprecise".
7	DBE	
8	Syscall	Generated unconditionally by a <i>syscall</i> instruction.
9	Bp	Breakpoint - a <i>break</i> instruction.
10	RI	"reserved instruction"
11	CpU	"Co-Processor unusable"
12	Ov	"arithmetic overflow". Note that "unsigned" versions of instructions (e.g. <i>addu</i>) never cause this exception.
13-31	-	reserved. Some are already defined for MIPS CPUs such as the R6000 and R4xxx

Table 3.2. ExcCode values: different kinds of exceptions

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c0_epc

- The Exception Program Counter
 - Points to address of where to restart execution after handling the exception or interrupt
 - Example
 - Assume `sw r3, (r4)` causes a restartable fault exception

```

nop
sw r3 (r4)
nop
          
```

C0_epc

C0_cause

C0_status

CP1 (floating point)

PC: 0x0300

HI/LO

R1

↓

Rn

Aside: We ignore BD-bit in `c0_cause` which is also used in reality on rare occasions.

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Exception Vectors

Program address	"segment"	Physical Address	Description
0x8000 0000	kseg0	0x0000 0000	TLB miss on <i>kuseg</i> reference only.
0x8000 0080	kseg0	0x0000 0080	All other exceptions.
0xbf00 0100	kseg1	0x1fc0 0100	Uncached alternative <i>kuseg</i> TLB miss entry point (used if SR bit BEV set).
0xbf00 0180	kseg1	0x1fc0 0180	Uncached alternative for all other exceptions, used if SR bit BEV set).
0xbf00 0000	kseg1	0x1fc0 0000	The "reset exception".

Table 4.1. Reset and exception entry points (vectors) for R30xx family

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Simple Exception Walk-through

User Mode

Application

Kernel Mode

Interrupt Handler

Interrupt

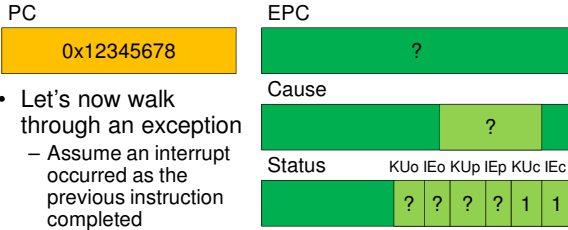
↓

Return from Int

↑

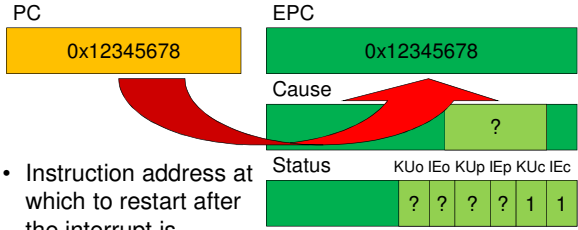
30

Hardware exception handling



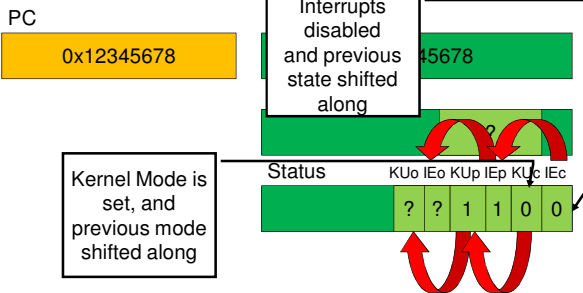
- Let's now walk through an exception
 - Assume an interrupt occurred as the previous instruction completed
 - Note: We are in user mode with interrupts enabled

Hardware exception handling

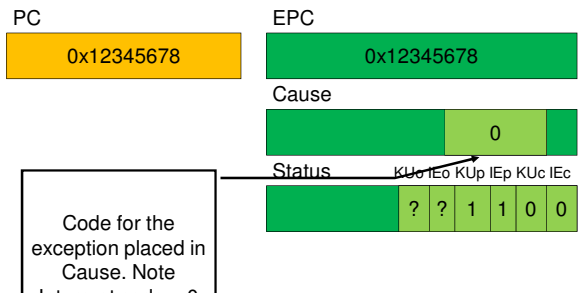


- Instruction address at which to restart after the interrupt is transferred to EPC

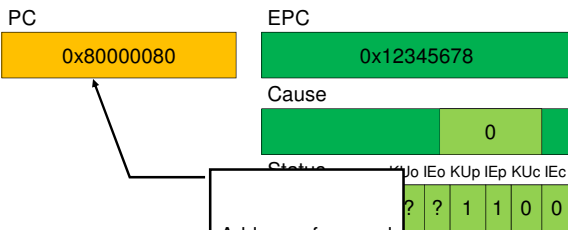
Hardware exception handling



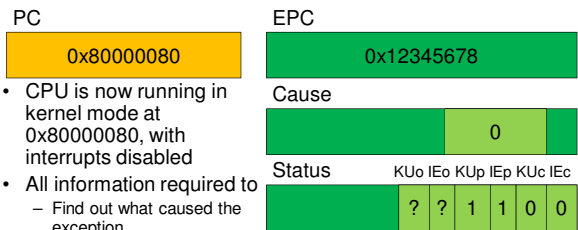
Hardware exception handling



Hardware exception handling



Hardware exception handling

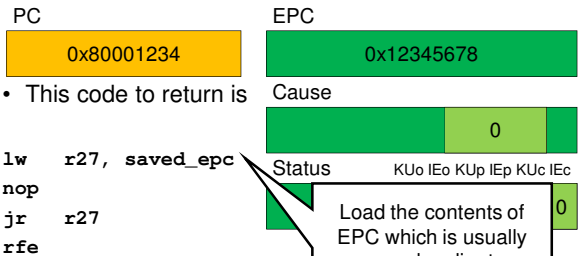


- CPU is now running in kernel mode at 0x80000080, with interrupts disabled
- All information required to
 - Find out what caused the exception
 - Restart after exception handling
 is in coprocessor registers

Returning from an exception

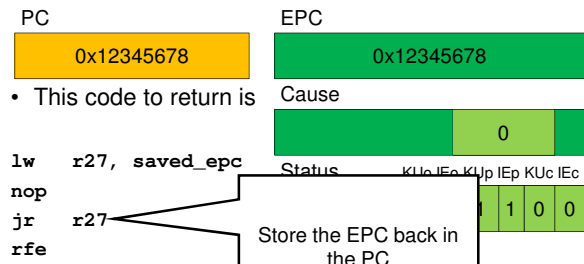
- For now, lets ignore
 - how the exception is actually handled
 - how user-level registers are preserved
- Let's simply look at how we return from the exception

Returning from an exception

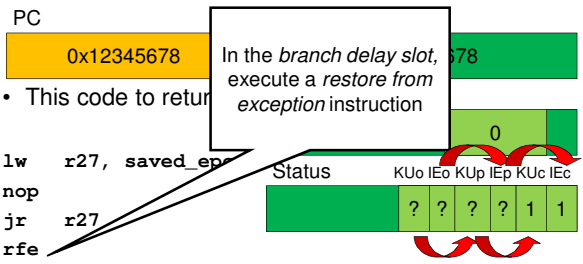


Load the contents of EPC which is usually moved earlier to somewhere in memory by the exception handler

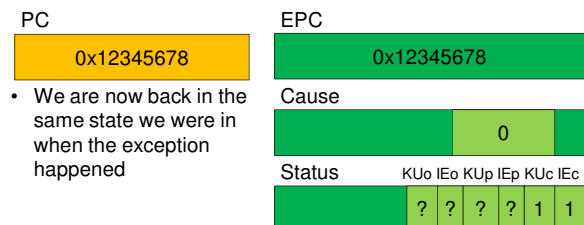
Returning from an exception



Returning from an exception

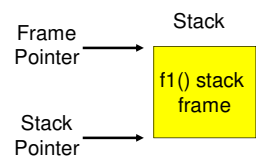


Returning from an exception



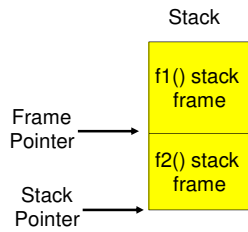
Function Stack Frames

- Each function call allocates a new stack frame for local variables, the return address, previous frame pointer etc.
 - Frame pointer: start of current stack frame
 - Stack pointer: end of current stack frame
- Example: assume f1() calls f2(), which calls f3().



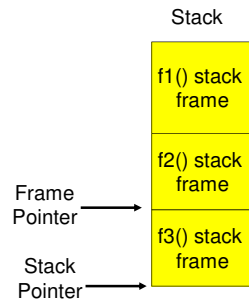
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Function Stack Frames

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- Example: assume f1() calls f2(), which calls f3().



Compiler Register Conventions

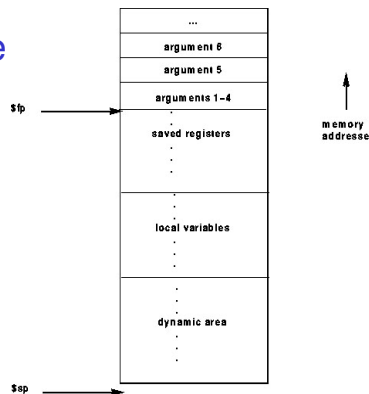
- Given 32 registers, which registers are used for
 - Local variables?
 - Argument passing?
 - Function call results?
 - Stack Pointer?

Compiler Register Conventions

Reg No	Name	Used for
0	zero	Always returns 0
1	at	(assembler temporary) Reserved for use by assembler
2-3	v0-v1	Value (except FP) returned by subroutine
4-7	a0-a3	(arguments) First four parameters for a subroutine
8-15	t0-t7	(temporaries) subroutines may use without saving
24-25	t8-t9	
16-23	s0-s7	Subroutine "register variables": a subroutine which will write one of these must save the old value and restore it before it exits, so the <i>calling</i> routine sees their values preserved.
26-27	k0-k1	Reserved for use by interrupt/trap handler - may change under your feet
28	gp	global pointer - some runtime systems maintain this to give easy access to (some) "static" or "extern" variables.
29	sp	stack pointer
30	s8/tp	9th register variable. Subroutines which need one can use this as a "frame pointer".
31	ra	Return address for subroutine

Stack Frame

- MIPS calling convention for gcc
 - Args 1-4 have space reserved for them



Example Code

```
main ()
{
    int i;

    i =
    sixargs(1,2,3,4,5,6);
}

int sixargs(int a, int b,
            int c, int d, int e,
            int f)
{
    return a + b + c + d
           + e + f;
}
```



```

0040011c <main>:
40011c: 27bdfdf8      addiu  sp,sp,-40
400120: afbf0024      sw    ra,36(sp)
400124: afbe0020      sw    s8,32(sp)
400128: 03a0f021      move  s8,sp
40012c: 24020005      li    v0,5
400130: afa20010      sw    v0,16(sp)
400134: 24020006      li    v0,6
400138: afa20014      sw    v0,20(sp)
40013c: 24040001      li    a0,1
400140: 24050002      li    a1,2
400144: 24060003      li    a2,3
400148: 0c10002c      jal  4000b0 <sixargs>
40014c: 24070004      li    a3,4
400150: afc20018      sw    v0,24(s8)
400154: 03c0e821      move  sp,s8
400158: 8fbf0024      lw    ra,36(sp)
40015c: 8fbe0020      lw    s8,32(sp)
400160: 03e00008      jr    ra
400164: 27bd0028      addiu  sp,sp,40
...

```

```

004000b0 <sixargs>:
4000b0: 27bdfdf8      addiu  sp,sp,-8
4000b4: afbe0000      sw    s8,0(sp)
4000b8: 03a0f021      move  s8,sp
4000bc: afc40008      sw    a0,8(s8)
4000c0: afc5000c      sw    a1,12(s8)
4000c4: afc60010      sw    a2,16(s8)
4000c8: afc70014      sw    a3,20(s8)
4000cc: 8fc30008      lw    v1,8(s8)
4000d0: 8fc2000c      lw    v0,12(s8)
4000d4: 00000000      nop
4000d8: 00621021      addu  v0,v1,v0
4000dc: 8fc30010      lw    v1,16(s8)
4000e0: 00000000      nop
4000e4: 00431021      addu  v0,v0,v1
4000e8: 8fc30014      lw    v1,20(s8)
4000ec: 00000000      nop
4000f0: 00431021      addu  v0,v0,v1
4000f4: 8fc30018      lw    v1,24(s8)
4000f8: 00000000      nop

```

```

4000fc: 00431021      addu  v0,v0,v1
400100: 8fc3001c      lw    v1,28(s8)
400104: 00000000      nop
400108: 00431021      addu  v0,v0,v1
40010c: 03c0e821      move  sp,s8
400110: 8fbe0000      lw    s8,0(sp)
400114: 03e00008      jr    ra
400118: 27bd0008      addiu  sp,sp,8

```

System Calls

Continued

User and Kernel Execution

- Simplistically, CPU execution state consists of
 - Registers, processor mode, PC, SP
- User applications and the kernel have their own execution state.
- System call mechanism safely transfers from user execution to kernel execution and back.

System Call Mechanism in Principle

- Processor mode
 - Switched from user-mode to kernel-mode
 - Switched back when returning to user mode
- SP
 - User-level SP is saved and a kernel SP is initialised
 - User-level SP restored when returning to user-mode
- PC
 - User-level PC is saved and PC set to kernel entry point
 - User-level PC restored when returning to user-level
 - Kernel entry via the designated entry point must be strictly enforced

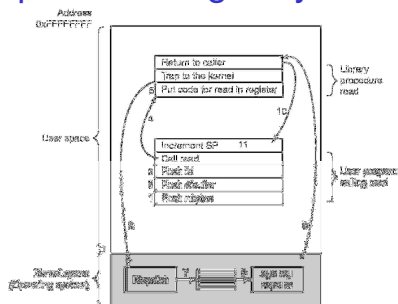
System Call Mechanism in Principle

- Registers
 - Set at user-level to indicate system call type and its arguments
 - A convention between applications and the kernel
 - Some registers are preserved at user-level or kernel-level in order to restart user-level execution
 - Depends on language calling convention etc.
 - Result of system call placed in registers when returning to user-level
 - Another convention

Why do we need system calls?

- Why not simply jump into the kernel via a function call????
 - Function calls do not
 - Change from user to kernel mode
 - and eventually back again
 - Restrict possible entry points to secure locations

Steps in Making a System Call



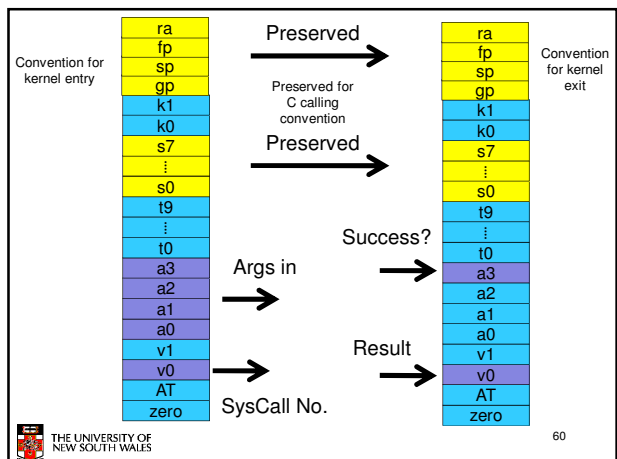
There are 11 steps in making the system call read (fd, buffer, nbytes)

MIPS System Calls

- System calls are invoked via a *syscall* instruction.
 - The *syscall* instruction causes an exception and transfers control to the general exception handler
 - A convention (an agreement between the kernel and applications) is required as to how user-level software indicates
 - Which system call is required
 - Where its arguments are
 - Where the result should go

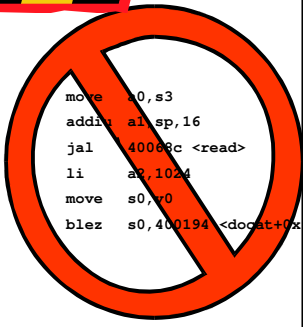
OS/161 Systems Calls

- OS/161 uses the following conventions
 - Arguments are passed and returned via the normal C function calling convention
 - Additionally
 - Reg v0 contains the system call number
 - On return, reg a3 contains
 - 0: if success, v0 contains successful result
 - not 0: if failure, v0 has the errno.
 - » v0 stored in errno
 - » -1 returned in v0



CAUTION

- Seriously low-level code follows
- This code is not for the faint hearted



```

move    a0,s3
addiu   a1,sp,16
jal     40068c <read>
li      a2,1024
move    s0,v0
blez    s0,400194 <docat+0x94>
    
```

User-Level System Call Walk Through – Calling read()

```
int read(int filehandle, void *buffer, size_t size)
```

- Three arguments, one return value
- Code fragment calling the read function

```

400124: 02602021  move a0,s3
400128: 27a50010  addiu a1,sp,16
40012c: 0c1001a3  jal  40068c <read>
400130: 24060400  li   a2,1024
400134: 00408021  move s0,v0
400138: 1a000016  blez s0,400194 <docat+0x94>
    
```

- Args are loaded, return value is tested

Inside the read() syscall function part 1

```

0040068c <read>:
40068c: 08100190  j    400640 <__syscall>
400690: 24020005  li   v0,5
    
```

- Appropriate registers are preserved
 - Arguments (a0-a3), return address (ra), etc.
- The syscall number (5) is loaded into v0
- Jump (not jump and link) to the common syscall routine

The read() syscall function part 2

Generate a syscall exception

```

00400640 <__syscall>:
400640: 0000000c  syscall
400644: 10e00005  beqz a3,40065c <__syscall+0x1c>
400648: 00000000  nop
40064c: 3c011000  lui  at,0x1000
400650: ac220000  sw  v0,0(at)
400654: 2403ffff  li  v1,-1
400658: 2402ffff  li  v0,-1
40065c: 03e00008  jr  ra
400660: 00000000  nop
    
```

The read() syscall function part 2

Test success, if yes, branch to return from function

```

00400640 <__syscall>:
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400644: 10e00005  beqz a3,40065c <__syscall+0x1c>
400648: 00000000  nop
40064c: 3c011000  lui  at,0x1000
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400654: 2403ffff  li  v1,-1
400658: 2402ffff  li  v0,-1
40065c: 03e00008  jr  ra
400660: 00000000  nop
    
```

The read() syscall function part 2

If failure, store code in errno

```

00400640 <__syscall>:
400640: 0000000c  syscall
400644: 10e00005  beqz a3,40065c
400648: 00000000  nop
40064c: 3c011000  lui  at,0x1000
400650: ac220000  sw  v0,0(at)
400654: 2403ffff  li  v1,-1
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40065c: 03e00008  jr  ra
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400660: 00000000 nop
    
```

Set read() result to -1

The read() syscall function part 2

```

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400644: 10e00005 beqz a3,40065c
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40065c: 03e00008 jr ra
400660: 00000000 nop
    
```

Return to location after where read() was called

Summary

- From the caller's perspective, the read() system call behaves like a normal function call
 - It preserves the calling convention of the language
- However, the actual function implements its own convention by agreement with the kernel
 - Our OS/161 example assumes the kernel preserves appropriate registers(s0-s8, sp, gp, ra).
- Most languages have similar *libraries* that interface with the operating system.

System Calls - Kernel Side

- Things left to do
 - Change to kernel stack
 - Preserve registers by saving to memory (on the kernel stack)
 - Leave saved registers somewhere accessible to
 - Read arguments
 - Store return values
 - Do the "read()"
 - Restore registers
 - Switch back to user stack
 - Return to application

```

exception:
    move k1, sp /* Save previous stack pointer in k1 */
    mfc0 k0, c0_status /* Get status register */
    andi k0, k0, CST_Kup /* Check the we-were-in-user-mode bit */
    beq k0, $0, 1f /* If clear, from kernel, already have stack */
    nop /* delay slot */

    /* Coming from user mode - load kernel stack into sp */
    la k0, curkstack /* get address of "curkstack" */
    lw sp, 0(k0) /* get its value */
    nop /* delay slot for the load */

1:
    mfc0 k0, c0_cause /* Now, load the exception cause. */
    j common_exception /* Skip to common code */
    nop /* delay slot */
    
```

Note k0, k1 registers available for kernel use

```

exception:
    move k1, sp /* Save previous stack pointer in k1 */
    mfc0 k0, c0_status /* Get status register */
    andi k0, k0, CST_Kup /* Check the we-were-in-user-mode bit */
    beq k0, $0, 1f /* If clear, from kernel, already have stack */
    nop /* delay slot */

    /* Coming from user mode - load kernel stack into sp */
    la k0, curkstack /* get address of "curkstack" */
    lw sp, 0(k0) /* get its value */
    nop /* delay slot for the load */

1:
    mfc0 k0, c0_cause /* Now, load the exception cause. */
    j common_exception /* Skip to common code */
    nop /* delay slot */
    
```

```

common_exception:

/*
 * At this point:
 *   Interrupts are off. (The processor did this for us.)
 *   k0 contains the exception cause value.
 *   k1 contains the old stack pointer.
 *   sp points into the kernel stack.
 *   All other registers are untouched.
 */

/*
 * Allocate stack space for 37 words to hold the trap frame,
 * plus four more words for a minimal argument block.
 */
addi sp, sp, -164

```

```

/* The order here must match mips/include/trapframe.h. */

sw ra, 160(sp) /* dummy for gdb */
sw s8, 156(sp) /* save s8 */
sw sp, 152(sp) /* dummy for gdb */
sw gp, 148(sp) /* save gp */
sw k1, 144(sp) /* dummy for gdb */
sw k0, 140(sp) /* dummy for gdb */

sw k1, 152(sp) /* real saved sp */
nop /* delay slot for store */

mfc0 k1, c0_epc /* Copr.0 reg 13 == PC for
sw k1, 160(sp) /* real saved PC */

```

These six stores are a "hack" to avoid confusing GDB. You can ignore the details of why and how.

```

/* The order here must match mips/include/trapframe.h. */

sw ra, 160(sp) /* dummy for gdb */
sw s8, 156(sp) /* save s8 */
sw sp, 152(sp) /* dummy for gdb */
sw gp, 148(sp) /* save gp */
sw k1, 144(sp) /* dummy for gdb */
sw k0, 140(sp) /* dummy for gdb */

sw k1, 152(sp) /* real saved sp */
nop /* delay slot for store */

mfc0 k1, c0_epc /* Copr.0 reg 13 == PC for exception */
sw k1, 160(sp) /* real saved PC */

```

The real work starts here

```

sw t9, 136(sp)
sw t8, 132(sp)
sw t7, 128(sp)
sw t6, 124(sp)
sw t5, 120(sp)
sw t4, 116(sp)
sw t3, 112(sp)
sw t2, 108(sp)
sw t1, 104(sp)
sw t0, 100(sp)
sw a9, 96(sp)
sw a8, 92(sp)
sw a7, 88(sp)
sw a6, 84(sp)
sw a5, 80(sp)
sw a4, 76(sp)
sw a3, 72(sp)
sw a2, 68(sp)
sw a1, 64(sp)
sw a0, 60(sp)
sw v1, 56(sp)
sw v0, 52(sp)
sw AT, 48(sp)
sw ra, 44(sp)
sw ra, 40(sp)
sw ra, 36(sp)

```

Save all the registers on the kernel stack

```

/*
 * Save special registers.
 */
mfhi t0
mflo t1
sw t0, 32(sp)
sw t1, 28(sp)

/*
 * Save remaining exception context information.
 */

sw k0, 24(sp) /* k0 was loaded with cause earlier */
mfc0 t1, c0_status /* Copr.0 reg 11 == status */
sw t1, 20(sp)
mfc0 t2, c0_vaddr /* Copr.0 reg 8 == faulting vaddr */
sw t2, 16(sp)

/*
 * Pretend to save $0 for gdb's benefit.
 */
sw $0, 12(sp)

```

We can now use the other registers (t0, t1) that we have preserved on the stack

```

/*
 * Prepare to call mips_trap(struct trapframe *)
 */

addiu a0, sp, 16 /* set argument */
jal mips_trap /* call it */
nop /* delay slot */

```

Create a pointer to the base of the saved registers and state in the first argument register

```

struct trapframe {
    u_int32_t tf_vaddr; /* vaddr register */
    u_int32_t tf_status; /* status register */
    u_int32_t tf_cause; /* cause register */
    u_int32_t tf_lo;
    u_int32_t tf_hi;
    u_int32_t tf_ra; /* Saved register 31 */
    u_int32_t tf_at; /* Saved register 1 (AT) */
    u_int32_t tf_v0; /* Saved register 2 (v0) */
    u_int32_t tf_v1; /* etc. */
    u_int32_t tf_a0;
    u_int32_t tf_a1;
    u_int32_t tf_a2;
    u_int32_t tf_a3;
    u_int32_t tf_t0;
    :
    u_int32_t tf_t7;
    u_int32_t tf_s0;
    :
    u_int32_t tf_s7;
    u_int32_t tf_t8;
    u_int32_t tf_t9;
    u_int32_t tf_k0; /* dummy (see exception.S comment) */
    u_int32_t tf_k1; /* dummy */
    u_int32_t tf_gp;
    u_int32_t tf_sp;
    u_int32_t tf_s8;
    u_int32_t tf_epc; /* coprocessor 0 epc register */
};

```

Kernel Stack

- epc
- s8
- sp
- gp
- k1
- k0
- t9
- t8
- :
- at
- ra
- hi
- lo
- cause
- status
- vaddr

By creating a pointer to here of type struct trapframe *, we can access the user's saved registers as normal variables within 'C'

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Now we arrive in the 'C' kernel

```

/*
 * General trap (exception) handling function for mips.
 * This is called by the assembly-language exception handler once
 * the trapframe has been set up.
 */
void
mips_trap(struct trapframe *tf)
{
    u_int32_t code, isutlb, iskern;
    int savespl;

    /* The trap frame is supposed to be 37 registers long. */
    assert(sizeof(struct trapframe)==(37*4));

    /* Save the value of curspl, which belongs to the old context. */
    savespl = curspl;

    /* Right now, interrupts should be off. */
    curspl = SPL_HIGH;
}

```

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What happens next?

- The kernel deals with whatever caused the exception
 - Syscall
 - Interrupt
 - Page fault
 - It potentially modifies the *trapframe*, etc
 - E.g., Store return code in v0, zero in a3
- 'mips_trap' eventually returns

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```

exception_return:
    /* 16(sp) no need to restore tf_vaddr */
    lw t0, 20(sp) /* load status register value into t0 */
    nop /* load delay slot */
    mtc0 t0, c0_status /* store it back to coprocessor 0 */
    /* 24(sp) no need to restore tf_cause */

    /* restore special registers */
    lw t1, 28(sp)
    lw t0, 32(sp)
    mtlo t1
    mthi t0

    /* load the general registers */
    lw ra, 36(sp)

    lw AT, 40(sp)
    lw v0, 44(sp)
    lw v1, 48(sp)
    lw a0, 52(sp)
    lw a1, 56(sp)
    lw a2, 60(sp)
    lw a3, 64(sp)

```

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```

lw t0, 68(sp)
lw t1, 72(sp)
lw t2, 76(sp)
lw t3, 80(sp)
lw t4, 84(sp)
lw t5, 88(sp)
lw t6, 92(sp)
lw t7, 96(sp)
lw s0, 100(sp)
lw s1, 104(sp)
lw s2, 108(sp)
lw s3, 112(sp)
lw s4, 116(sp)
lw s5, 120(sp)
lw s6, 124(sp)
lw s7, 128(sp)
lw t8, 132(sp)
lw t9, 136(sp)

/* 140(sp) "saved" k0 was dummy garbage anyway */
/* 144(sp) "saved" k1 was dummy garbage anyway */

```

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```

lw gp, 148(sp) /* restore gp */
/* 152(sp) stack pointer - below */
lw s8, 156(sp) /* restore s8 */
lw k0, 160(sp) /* fetch exception return PC into k0 */

lw sp, 152(sp) /* fetch saved sp (must be last) */

/* done */
jr k0 /* jump back */
rfe /* in delay slot */
.end common_exception

```

Note again that only k0, k1 have been trashed

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