

Synchronisation and Concurrency II

Summarising Semaphores

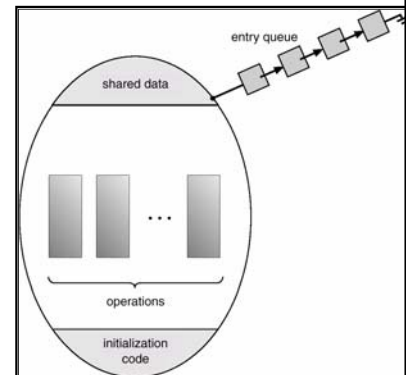
- Semaphores can be used to solve a variety of concurrency problems
- However, programming with them can be error-prone
 - E.g. must *signal* for every *wait* for mutexes
 - Too many, or too few signals or waits, or signals and waits in the wrong order, can have catastrophic results

Monitors

- To ease concurrent programming, Hoare (1974) proposed *monitors*.
 - A higher level synchronisation primitive
 - Programming language construct
- Idea
 - A set of procedures, variables, data types are grouped in a special kind of module, a *monitor*.
 - Variables and data types only accessed from within the monitor
 - Only one process/thread can be in the monitor at any one time
 - Mutual exclusion is implemented by the compiler (which should be less error prone)

Monitor

- When a thread calls a monitor procedure that has a thread already inside, it is queued and it sleeps until the current thread exits the monitor.



Monitors

```

monitor example
  integer i;
  condition c;

  procedure producer();
  .
  .
  .
end;

  procedure consumer();
  .
  .
  .
end;
end monitor;
    
```

Example of a monitor

Simple example

```

monitor counter {
  int count;
  procedure inc() {
    count = count + 1;
  }
  procedure dec() {
    count = count - 1;
  }
}
    
```

Note: "paper" language

- Compiler guarantees only one thread can be active in the monitor at any one time
- Easy to see this provides mutual exclusion
 - No race condition on `count`.

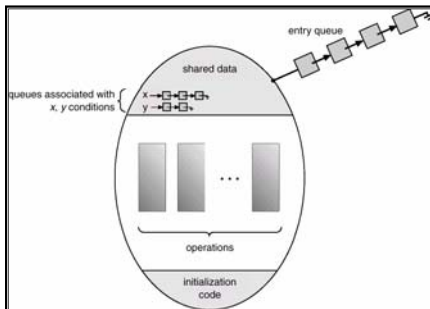
How do we block waiting for an event?

- We need a mechanism to block waiting for an event (in addition to ensuring mutual exclusion)
 - e.g., for producer consumer problem when buffer is empty or full
- Condition Variables**

Condition Variable

- To allow a process to wait within the monitor, a **condition** variable must be declared, as
 - condition x, y;**
- Condition variable can only be used with the operations **wait** and **signal**.
 - The operation **x.wait();** means that the process invoking this operation is suspended until another process invokes **x.signal();**
 - The **x.signal** operation resumes exactly one suspended process. If no process is suspended, then the **signal** operation has no effect.

Condition Variables



Monitors

```

monitor ProducerConsumer
condition full, empty;
integer count;
procedure insert(item: integer);
begin
    if count = N then wait(full);
    insert_item(item);
    count := count + 1;
    if count = 1 then signal(empty)
end;
function remove: integer;
begin
    if count = 0 then wait(empty);
    remove = remove_item;
    count := count - 1;
    if count = N - 1 then signal(full)
end;
count := 0;
end monitor;

procedure producer;
begin
    while true do
        begin
            item = produce_item;
            ProducerConsumer.insert(item)
        end;
end;
procedure consumer;
begin
    while true do
        begin
            item = ProducerConsumer.remove;
            consume_item(item)
        end;
end;
    
```

- Outline of producer-consumer problem with monitors
 - only one monitor procedure active at one time
 - buffer has N slots

OS/161 Provided Synchronisation Primitives

- Locks
- Semaphores
- Condition Variables

Locks

```

• Functions to create and destroy locks

struct lock *lock_create(const char *name);
void lock_destroy(struct lock *);

• Functions to acquire and release them

void lock_acquire(struct lock *);
void lock_release(struct lock *);
    
```

Example use of locks

```
int count;
struct lock *count_lock

main() {
    count = 0;
    count_lock =
        lock_create("count
lock");
    if (count_lock == NULL)
        panic("I'm dead");
    stuff();
}

procedure inc() {
    lock_acquire(count_lock);
    count = count + 1;
    lock_release(count_lock);
}
procedure dec() {
    lock_acquire(count_lock);
    count = count -1;
    lock_release(count_lock);
}
```



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Semaphores

```
struct semaphore *sem_create(const char *name, int
initial_count);
void sem_destroy(struct semaphore *);

void P(struct semaphore *);
void V(struct semaphore *);
```



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Example use of Semaphores

```
int count;
struct semaphore
*count_mutex;

main() {
    count = 0;
    count_mutex =
        sem_create("count",
1);
    if (count_mutex == NULL)
        panic("I'm dead");
    stuff();
}

procedure inc() {
    P(count_mutex);
    count = count + 1;
    V(count_mutex);
}
procedure dec() {
    P(count_mutex);
    count = count -1;
    V(count_mutex);
}
```



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Condition Variables

```
struct cv *cv_create(const char *name);
void cv_destroy(struct cv *);

void cv_wait(struct cv *cv, struct lock *lock);
- Releases the lock and blocks
- Upon resumption, it re-acquires the lock
  • Note: we must recheck the condition we slept on

void cv_signal(struct cv *cv, struct lock *lock);
void cv_broadcast(struct cv *cv, struct lock *lock);
- Wakes one/all, does not release the lock
- First "waiter" scheduled after signaller releases the lock will re-
acquire the lock
```

Note: All three variants must hold the lock passed in.



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Condition Variables and Bounded Buffers

Non-solution	Solution
<code>lock_acquire(c_lock)</code>	<code>lock_acquire(c_lock)</code>
<code>if (count == 0)</code>	<code>while (count == 0)</code>
<code> sleep();</code>	<code> cv_wait(c_cv, c_lock);</code>
<code>remove_item();</code>	<code>remove_item();</code>
<code>count--;</code>	<code>count--;</code>
<code>lock_release(c_lock);</code>	<code>lock_release(c_lock);</code>



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A Producer-Consumer Solution Using OS/161 CVs

```
int count = 0;
#define N 4 /* buf size */
prod() {
    while(TRUE) {
        item = produce()
        lock_acquire(l)
        while (count == N)
            cv_wait(f, l);
        insert_item(item);
        count++;
        if (count == 1)
            cv_signal(e, l);
        lock_release()
    }
}

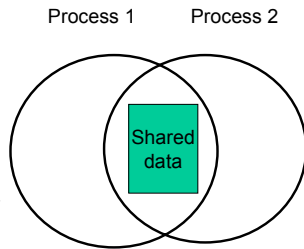
con() {
    while(TRUE) {
        lock_acquire(l)
        while (count == 0)
            cv_wait(e, l);
        item = remove_item();
        count--;
        if (count == N-1)
            cv_signal(f, l);
        lock_release(l);
        consume(item);
    }
}
```



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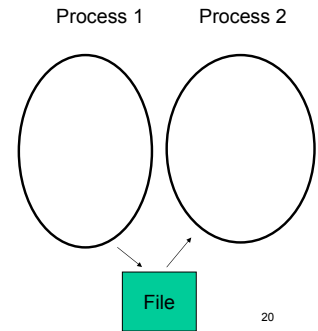
Interprocess Communication

- Shared Memory
 - Region of memory appears in each process
 - Communication via modifications to shared region
 - Requires concurrency control (semaphores, mutexes, monitors...)



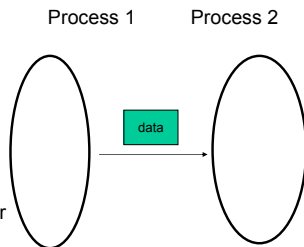
Interprocess Communication

- Shared files
 - Cumbersome



Interprocess Communication

- Message Passing
 - “real” IPC
- Requires two facilities
 - `send(message)`
 - Message may be fixed or variable in size
 - `receive(message)`
- OS ships the data from the sender to the receiver



Interprocess Communication (IPC)

- Mechanism for processes to communicate and to *synchronize* their actions.
- Message system – processes communicate with each other without resorting to shared variables.
- If *P* and *Q* wish to communicate, they need to:
 - establish a *communication link* between them
 - exchange messages via send/receive

IPC design issues

- Is the communication synchronous or asynchronous?
- How are links established?
- Can a link be associated with more than two processes?
- How many links can there be between every pair of communicating processes?
- What is the capacity of a link?
- Is the size of a message that the link can accommodate fixed or variable?
- Is the message format fixed or variable?
- Is a link unidirectional or bi-directional?

Blocking vs. Non-blocking

- | | |
|--|--|
| <ul style="list-style-type: none"> • Send <ul style="list-style-type: none"> – Operation blocks until partner is ready to receive • Rendezvous model • Send and receiver execute their system at the same time (synchronously) • Receive <ul style="list-style-type: none"> – Operation blocks until message is available • synchronous | <ul style="list-style-type: none"> • Send <ul style="list-style-type: none"> – Kernel receives message and delivers when receiver is ready • Asynchronous • Receive <ul style="list-style-type: none"> – System call returns immediately if no message is available • Asynchronous (polling) |
|--|--|

Blocking vs. Non-blocking

- Non-blocking IPC
 - Requires buffering of messages in the kernel
 - May fail due to buffer full
 - Overhead (copying, allocation)
 - Higher level of concurrency
 - Requires a separate synchronisation primitive
- Blocking IPC
 - May lead to threads blocked indefinitely
 - Can use *timeouts* prevent this
 - Zero-timeout \Rightarrow non-blocking receive



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Direct Communication

- Processes (or threads) must name each other explicitly using their unique process (or thread) ID:
 - **send** (*P*, *message*) – send a message to process *P*
 - **receive**(*Q*, *message*) – receive a message from process *Q*
- Properties of communication link
 - Links are established automatically (implicitly).
 - A link is associated with exactly one pair of communicating processes.
 - Between each pair there exists exactly one link.
 - The link may be unidirectional, but is usually bi-directional.



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Indirect Communication

- Messages are directed to and received from mailboxes (also referred to as ports).
 - Each mailbox has a unique id.
 - Processes can communicate only if they share a mailbox.
 - E.g. Mach
- Properties of communication link
 - Link established only if processes share a common mailbox
 - OS mechanism required to establish mailbox sharing
 - A link may be associated with many processes.
 - Each pair of processes may share several communication links.
 - Link may be unidirectional or bi-directional.



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Indirect Communication

- Operations
 - create a new mailbox
 - send and receive messages through mailbox
 - destroy a mailbox
- Primitives are defined as:
 - send**(*A*, *message*) – send a message to mailbox *A*
 - receive**(*A*, *message*) – receive a message from mailbox *A*



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Indirect Communication

- Mailbox sharing
 - P_1 , P_2 , and P_3 share mailbox *A*.
 - P_1 sends; P_2 and P_3 receive.
 - Who gets the message?
- Solutions
 - Allow a link to be associated with at most two processes.
 - Allow only one process at a time to execute a receive operation (Mach).
 - Allow the system to select arbitrarily the receiver.
 - First come, first served.



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Message Passing

```
#define N 100 /* number of slots in the buffer */
void producer(void)
{
    int item;
    message m; /* message buffer */

    while (TRUE) {
        item = produce_item(); /* generate something to put in buffer */
        receive(consumer, &m); /* wait for an empty to arrive */
        build_message(&m, item); /* construct a message to send */
        send(consumer, &m); /* send item to consumer */
    }
}

void consumer(void)
{
    int item, i;
    message m;

    for (i = 0; i < N; i++) send(producer, &m); /* send N empties */
    while (TRUE) {
        receive(producer, &m); /* get message containing item */
        item = extract_item(&m); /* extract item from message */
        send(producer, &m); /* send back empty reply */
        consume_item(item); /* do something with the item */
    }
}
```

The producer-consumer problem with N messages



Dining Philosophers

- Philosophers eat/think
- Eating needs 2 forks
- Pick one fork at a time
- How to prevent deadlock



Dining Philosophers

```
#define N 5 /* number of philosophers */

void philosopher(int i) /* i: philosopher number, from 0 to 4 */
{
    while (TRUE) {
        think(); /* philosopher is thinking */
        take_fork(i); /* take left fork */
        take_fork((i+1) % N); /* take right fork; % is modulo operator */
        eat(); /* yum-yum, spaghetti */
        put_fork(i); /* put left fork back on the table */
        put_fork((i+1) % N); /* put right fork back on the table */
    }
}
```

A nonsolution to the dining philosophers problem

Dining Philosophers

```
#define N 5 /* number of philosophers */
#define LEFT ((i+1)%N) /* number of i's left neighbor */
#define RIGHT ((i-1)%N) /* number of i's right neighbor */
#define THINKING 0 /* philosopher is thinking */
#define HUNGRY 1 /* philosopher is trying to get forks */
#define EATING 2 /* philosopher is eating */
typedef int semaphore; /* semaphores are a special kind of int */
int state[N]; /* array to keep track of everyone's state */
semaphore mutex = 1; /* mutual exclusion for critical regions */
semaphore s[N]; /* one semaphore per philosopher */

void philosopher(int i) /* i: philosopher number, from 0 to N-1 */
{
    while (TRUE) {
        think(); /* repeat forever */
        state[i] = THINKING; /* philosopher is thinking */
        down(&mutex); /* acquire two forks or block */
        test(LEFT); /* yum-yum, spaghetti */
        test(RIGHT); /* put both forks back on table */
        up(&mutex);
    }
}
```

Solution to dining philosophers problem (part 1)

Dining Philosophers

```
void take_forks(int i) /* i: philosopher number, from 0 to N-1 */
{
    down(&mutex); /* enter critical region */
    state[i] = HUNGRY; /* record fact that philosopher i is hungry */
    test(i); /* try to acquire 2 forks */
    up(&mutex); /* exit critical region */
    down(&s[i]); /* block if forks were not acquired */
}

void put_forks(i) /* i: philosopher number, from 0 to N-1 */
{
    down(&mutex); /* enter critical region */
    state[i] = THINKING; /* philosopher has finished eating */
    test(LEFT); /* see if left neighbor can now eat */
    test(RIGHT); /* see if right neighbor can now eat */
    up(&mutex); /* exit critical region */
}

void test(i) /* i: philosopher number, from 0 to N-1 */
{
    if (state[i] == HUNGRY && state[LEFT] != EATING && state[RIGHT] != EATING) {
        state[i] = EATING;
        up(&s[i]);
    }
}
```

Solution to dining philosophers problem (part 2)

The Readers and Writers Problem

- Models access to a database
 - E.g. airline reservation system
- Can have more than one concurrent reader
 - To check schedules and reservations
- Writers must have exclusive access
 - To book a ticket or update a schedule

The Readers and Writers Problem

```
typedef int semaphore; /* use your imagination */
semaphore mutex = 1; /* controls access to 'rc' */
semaphore db = 1; /* controls access to the database */
int rc = 0; /* # of processes reading or wanting to */

void reader(void)
{
    while (TRUE) {
        down(&mutex); /* repeat forever */
        rc++; /* get exclusive access to 'rc' */
        if (rc == 1) down(&db); /* one reader more now */
        up(&mutex); /* if this is the first reader ... */
        read_data_base(); /* release exclusive access to 'rc' */
        rc--; /* access the data */
        if (rc == 0) up(&db); /* get exclusive access to 'rc' */
        use_data_read(); /* one reader fewer now */
    }
}

void writer(void)
{
    while (TRUE) {
        think_up_data(); /* repeat forever */
        down(&db); /* noncritical region */
        write_data_base(); /* get exclusive access */
        up(&db); /* update the data */
    }
}
```

A solution to the readers and writers problem

The Sleeping Barber Problem



The Sleeping Barber Problem

```
#define CHAIRS 5 /* # chairs for waiting customers */
typedef int semaphore; /* use your imagination */
semaphore customers = 0; /* # of customers waiting for service */
semaphore barbers = 0; /* # of barbers waiting for customers */
semaphore mutex = 1; /* for mutual exclusion */
int waiting = 0; /* customers are waiting (not being out) */

void barber(void)
{
    while (TRUE) {
        down(&customers); /* go to sleep if # of customers is 0 */
        down(&mutex); /* acquire access to 'waiting' */
        waiting = waiting - 1; /* decrement count of waiting customers */
        up(&barbers); /* one barber is now ready to cut hair */
        up(&mutex); /* release 'waiting' */
        if (&hair) /* cut hair (outside critical section) */
        }
    }
}

void customer()
{
    down(&mutex); /* enter critical region */
    if (waiting < CHAIRS) { /* if there are no free chairs, leave */
        waiting = waiting + 1; /* increment count of waiting customers */
        up(&customers); /* wake up barber if necessary */
        up(&mutex); /* release access to 'waiting' */
        down(&barbers); /* go to sleep if # of free barbers is 0 */
        get_haircut(); /* be shaved and be serviced */
    } else { /* shop is full; do not wait */
        up(&mutex);
    }
}

```

See the textbook